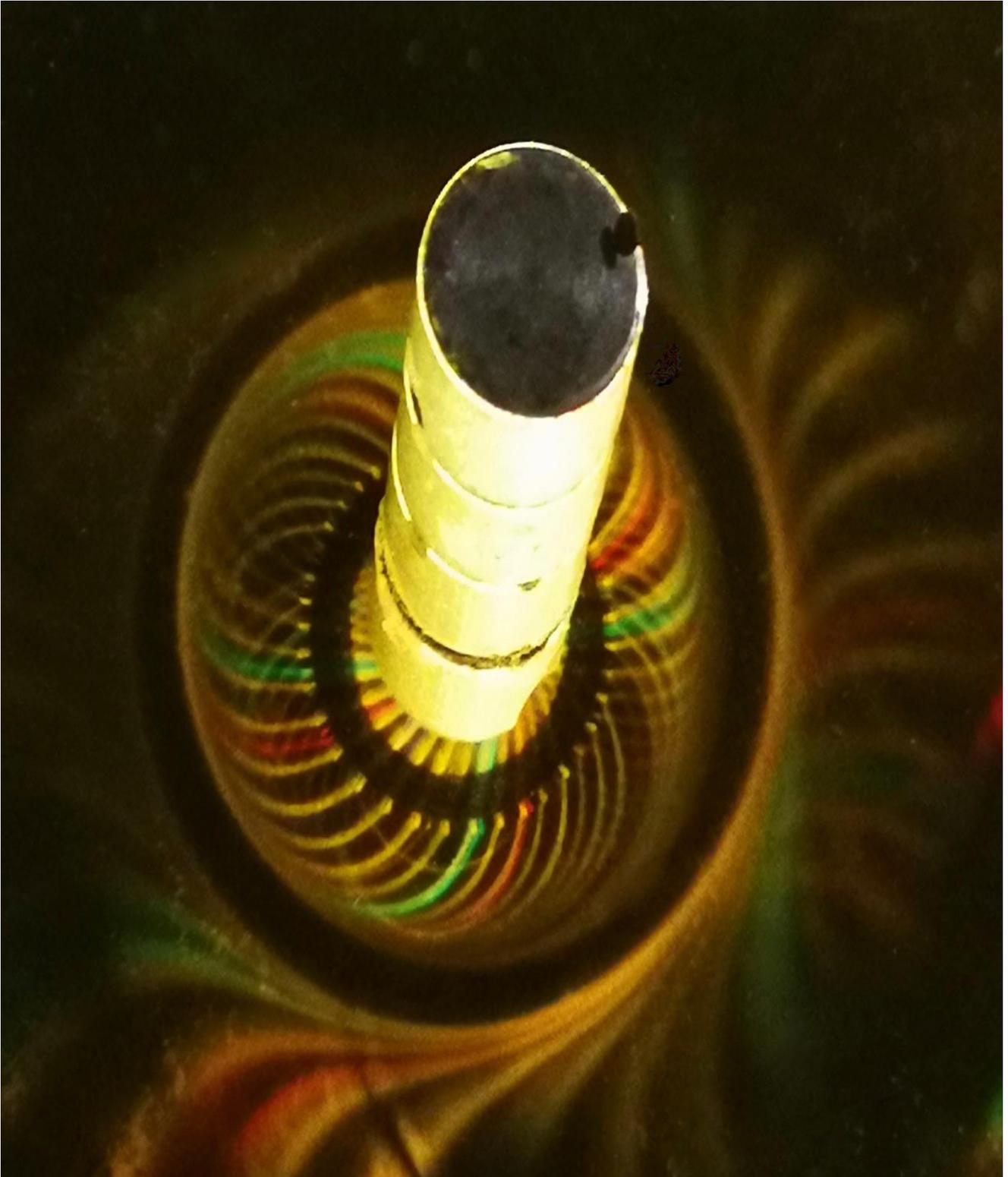
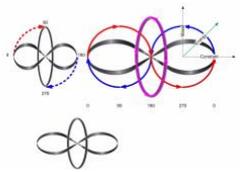


A Magnet is a what?





Today zero becomes greater than any other number.

To be able to understand the above will require the reader to let go of many academic mis-teachings and trust their own internal judgement defining a fact for themselves. I am not advocating that all academia has failed, but I will suggest it is a long way off a gold star for accomplishment or achievement.

Therefore, without further ado, I shall start at the end and at the beginning, (*at the same time*)! To understand where the two are in relationship to each other is to understand the failed concepts of “finite” and “infinite”; One being very small and the other being very big, but neither have a true calculable value thus, they are the numerical definitions that reside in the “GREY” area of calculations. This can be exemplified as “how small is small (*finite*)” and “how big is big (*infinite*)”[?]; Where, to give any answer, (*at all*) results in the addition or subtraction of “*something*” voiding the offered answer. Thus, finite and infinite cannot be established as a numeric.

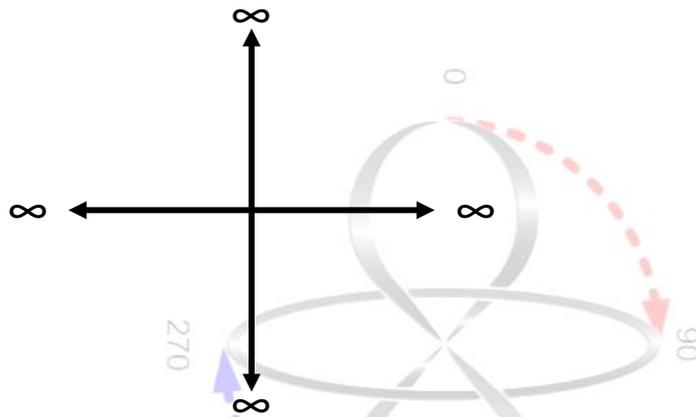
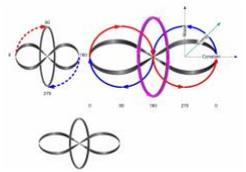
That was until now [!]; A simple calculation of $22/7$ results in 3.14287^r (Π); in fact, Π will recur ad infinitum; But, Π is a valid calculable number unlike finite and infinite. Having established the fact of the presence and validity of 3.14287 or Π leads to a process to define infinite, and of course finite; where both are best expressed within a two-dimensional x, y relationship; asking “how far is infinity”? As a numeric, this is not possible but is definable by symbol, that of ∞ . Therefore, it is possible to declare that “infinity” is from 0 to ∞ . That would be the perfect mathematical model of the definition of infinity or infinite as shown below:



It does not matter how long the line really is, it is the fact that the line expresses infinity and starts at 0 and ends at the theoretical end of the “x axis” of ∞ . That is factually and logically correct, (*in its most verbose condition*). This is where the current thinking of infinity collapses, and alas, the academic world today has no viable answer; To now suggest that the definition of infinity as shown above is a POSITIVE value, that being zero or (null) towards something along one axis in a single direction. Adding to this condition, it is also known that (*in most cases*) a POSITIVE number also has its corresponding NEGATIVE state.

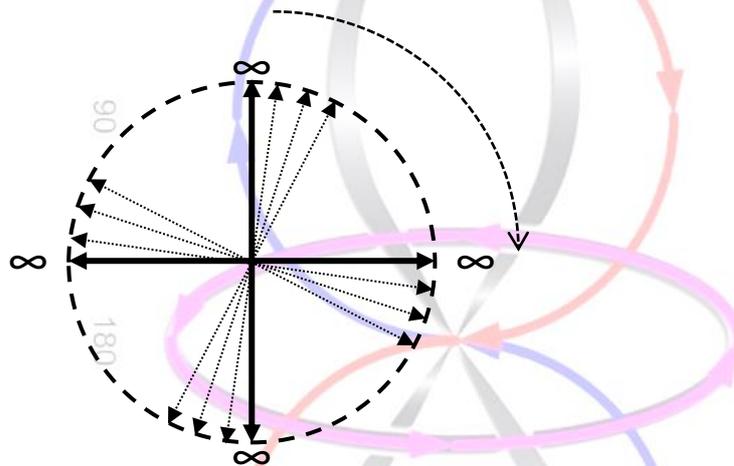
If ∞ is positive from 0 to ∞ , and a corresponding negative state exists, then it is factual and logical to also express a condition of NEGATIVE ∞ . The result of the negativity requires the logical state of ∞ to be re-written. **“For ∞ to exist as an entity (of) itself it must be two times itself in order to be infinity itself”**, (or) $[-\infty$ to 0 to $\infty+$] where $-\infty$ plus ∞ is NOT zero but two times ∞ along the x axis.

The “x” axis cannot exist as an independent condition and requires (*in the first instance*) the “y axis” or the x, y axis; And, if the definition of ∞ is factual and logical for the x axis, it must also be factual and logical for the y axis as shown below:



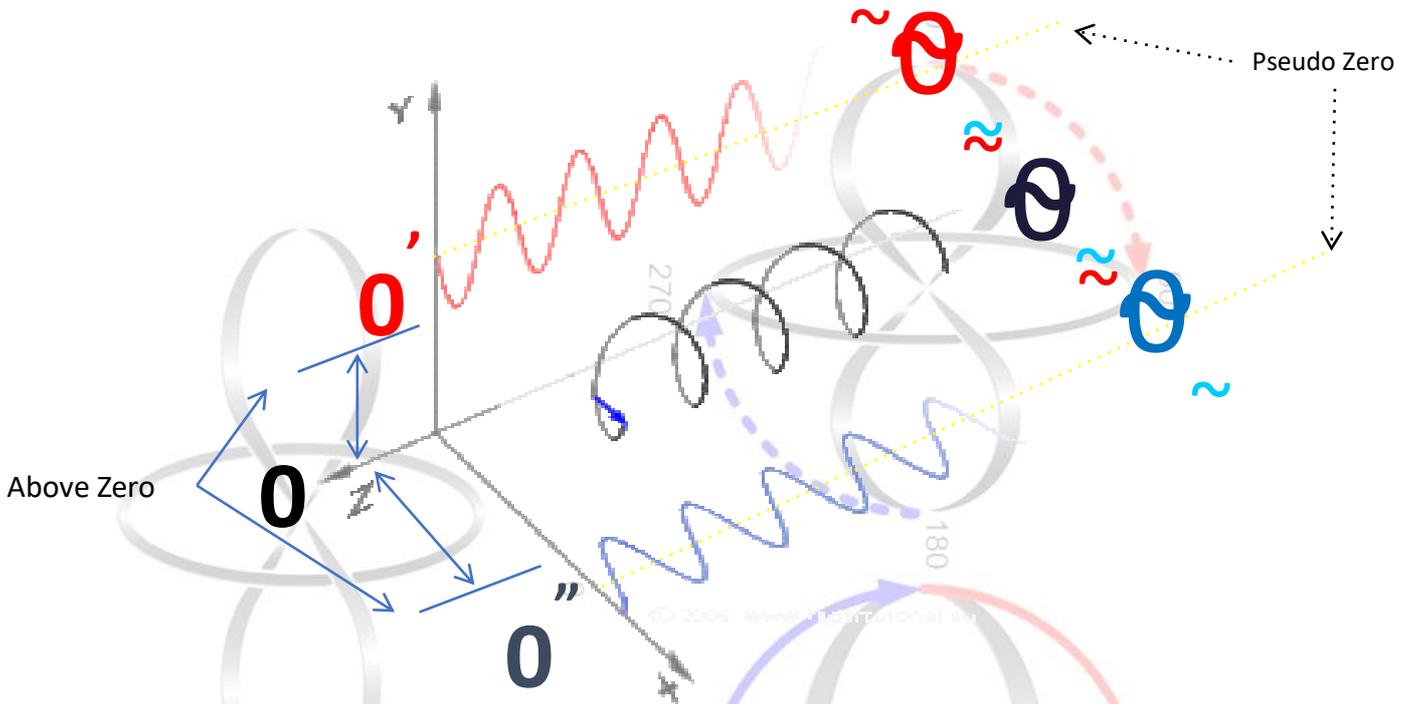
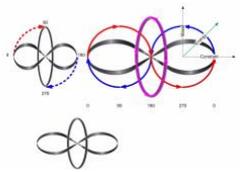
Again, substantiating the comment of “*For ∞ to exist as an entity (of) itself it must be two times itself in order to be infinity itself*”; as, within the image above infinity has be duly halved in both the x and the y axis’.

The geometry above visualizes the logical positioning of ∞ ; And to establish as an endpoint in any given direction of both the x and the y axis results in a third fundamental geometric condition. That is, that the orientation of x and y can be rotated about their own common axis to a point of ∞ ; where an infinite number of positions about its own axis is a circle as shown below:



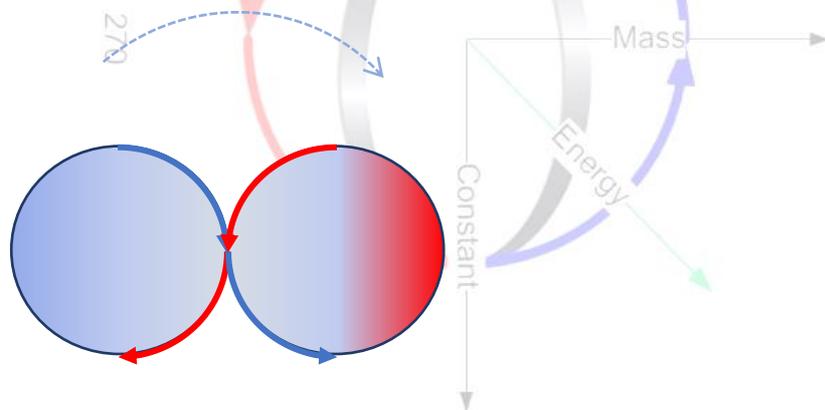
It is also known that the diameter of a circle is two times its radius (∞) which reasserts and bolsters the logical definition of infinity as previously stated; Where to calculate the circumference of a circle the formula of $\Pi \times D$ is used, where “D” is two times the radius which is two times $\infty!$ As a “curve” is longer that the straight line of itself results in that Π as depicted is greater than ∞ (or) to express as its logical condition $\Pi > \infty$. This now establishes a valid numerical condition to the impossibility of a numeric for ∞ , and allows further logic to be applied.

Having established the very big (Π), it is only right to establish the very small, and the very small is in the form of **NOT zero**. The only way to establish a NOT zero is by the **sum of the differential of plus and minus**. Where the academic sum of the differential of plus one and minus one is zero or $(1+-1=0)$; but this is does not represent the true logical condition, where one of something plus minus one of something is still something other than zero. This can be best represented by a helical waveform as shown below:

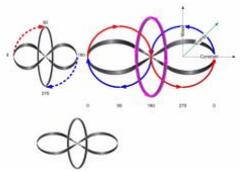


Although ZERO exists as the center axis with the helical spiral rotating around a common axis, resultant positive and negative values can be seen, each with their own zero axis. The result is a plus zero state and a negative zero state, which in turn is the differential function of itself, that of “the sum of the differential of plus one and minus one is NOT zero”, or NOT zero mass, NOT zero value, NOT zero movement. Allowing for the logical operation of a “**non-zero-sum accumulation**” and allowing for the logical as proven of $\prod > \infty$ allows for both logical conditions to form the “**cones of convergence**”.

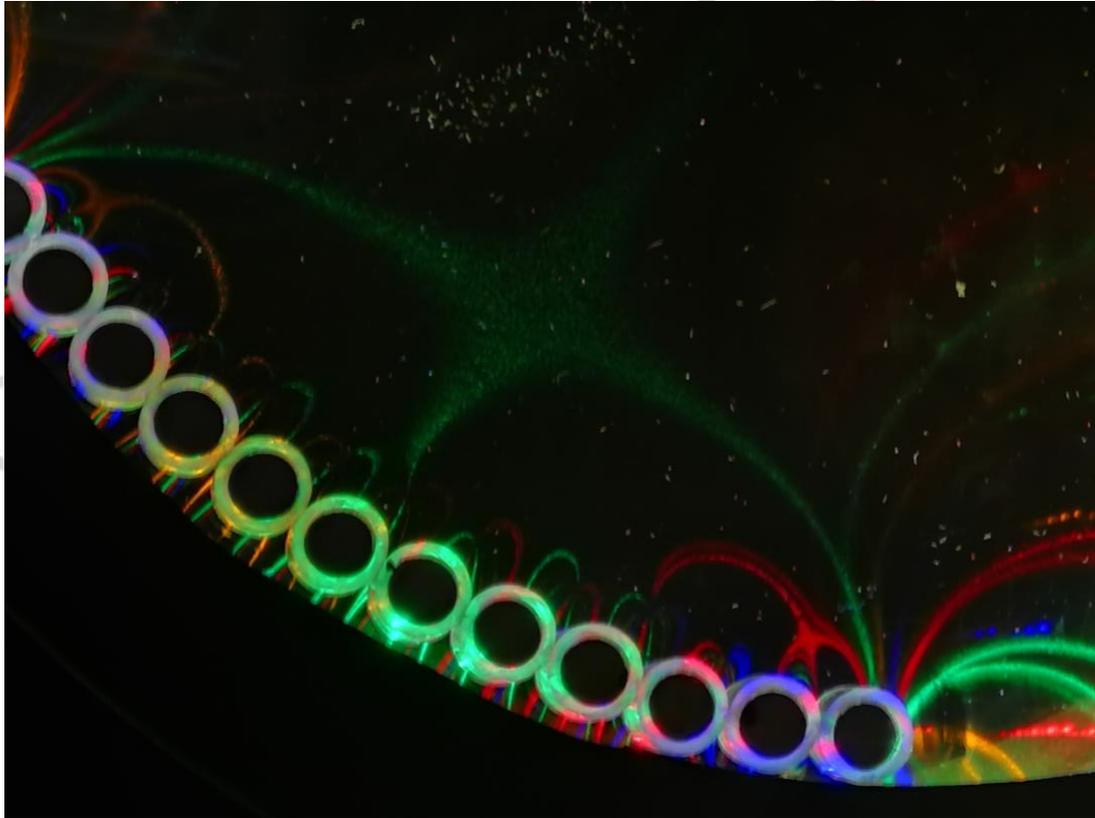
Reviewing the cones of convergence is similar to viewing “><” where the sum of the differential of plus one and minus one of > is NOT zero [and] the sum of the differential of plus one and minus one of < is also NOT zero resulting is NOT zero plus NOT zero is NOT zero $0' + 0'' = 0'''$ ”; this leads to the transpositional energy state within any cone of convergence and occurs EVERY day within two axial polarized magnetic bodies, as shown below.



The cross over point is **NOT ZERO**



It is all too easy to “surmise” a condition and theorize of what could or (*could*) not be; in the same way as Mr. Albert Einstein theorized the infamous equation of $E=mc^2$. A theory is a theory be it numerical or postulate, it will always be a theory until proven physically; Therefore, it is my pleasure to present to you the first of several images:



The above image encompasses the three preceding pages and the defined conditions as written.

1. An infinite sequence of magnets has been established based around $-\infty$ to $\infty+$
2. The functional sum of the differential of plus and minus is equal to NOT zero
3. The visual representation of $\prod > \infty$
4. The cones of convergence and its infinite repetition within a set of magnetic bodies.

Observation ONE

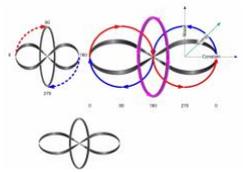
To the upper left of the image is the minus point of ∞ (also known as the North polar condition), and the lower right is positive point of ∞ (also known as the South polar condition).

Observation Two

The condition of NOT ZERO is established at the zero point or midpoint between $-\infty$ and $+\infty$

Observation Three

The cones of convergence culminate in a bi-direction helical movement of the magnetic field towards NOT ZERO; And, in doing so, meet the condition of “infinite mass or energy” attempting to move across an infinitely small gap (*as each of the magnetic bodies are NOT in contact with the next magnetic body*).



Observation Four

The NON-ZERO-SUM accumulation at the zero point via the cones of convergence amplifies an energy release at NOT ZERO via the functional sum of the differential of plus and minus resulting in NOT ZERO.

Observation Five

The infinite distance between $-\infty$ and $+\infty$ via the NON-ZERO-SUM accumulation of the cones of convergence via the functional sum of the differential results in an energy ejection (Central Green toroidal vortex) creating a visual energy curve (Green) which loops to both North and South as persistent energy states.

Contradictory Analysis One

“A magnet has a North and a South of equal proportions”; This cannot be so due to the greater luminescence of the energy fields at southern end of the magnetic sequence. In depth analysis revealed that the proportional energy displacement within a magnet body is 61.77:38.22 or 1.681:1 (*the golden ratio*). For quick calculations the values of 2/5:3/5 of itself in favor of South can be used.

Contradictory Analysis Two

“A magnet’s energy traverses or crosses the atomic structure of a magnetic body”; This cannot be true as it can be seen from the image above that the magnetic energy “flows” across the surface of a magnetic body. This is proven by the collision within the cones of convergence at the mid-point via the NON-ZERO-SUM accumulation and of the fact that NONE-of the magnetic bodies are in contact with each other, thus there is NO atomic contact.

Contradictory Analysis Three

“Infinity cannot be calculated and cannot be proven either as a $-\infty$ or a $+\infty$ or that $\prod > \infty$ ”; This is no longer true. It can be seen that from North to South is two times ∞ and that the cones of convergence create an energy release at within a zero-point condition, where that energy release is a visible energy curve, where the curve has a greater distance than the straight line of infinity resulting in the curve of $\prod > \infty$.

Contradictory Analysis Four

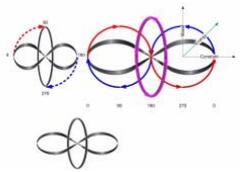
“A body or mass, (at rest) has no energy”; This cannot be so as the magnets as shown create a NEW energy field from a zero-point condition while at rest.

Contradictory Analysis Five

“Matter or energy can neither be created nor destroyed, it can only be converted to another form of matter or energy”; Thermodynamics enforces this condition based on a closed loop state, where it can be seen that the magnets reside in a NON-Closed loop condition and at rest, yet produce energy or matter at the zero point.

Contradictory Analysis Six

“Thermodynamic Entropy forces a condition of less than 100% efficiency”; This cannot be true as the total amount of energy of North and South is less than the energy released at the zero-point condition.



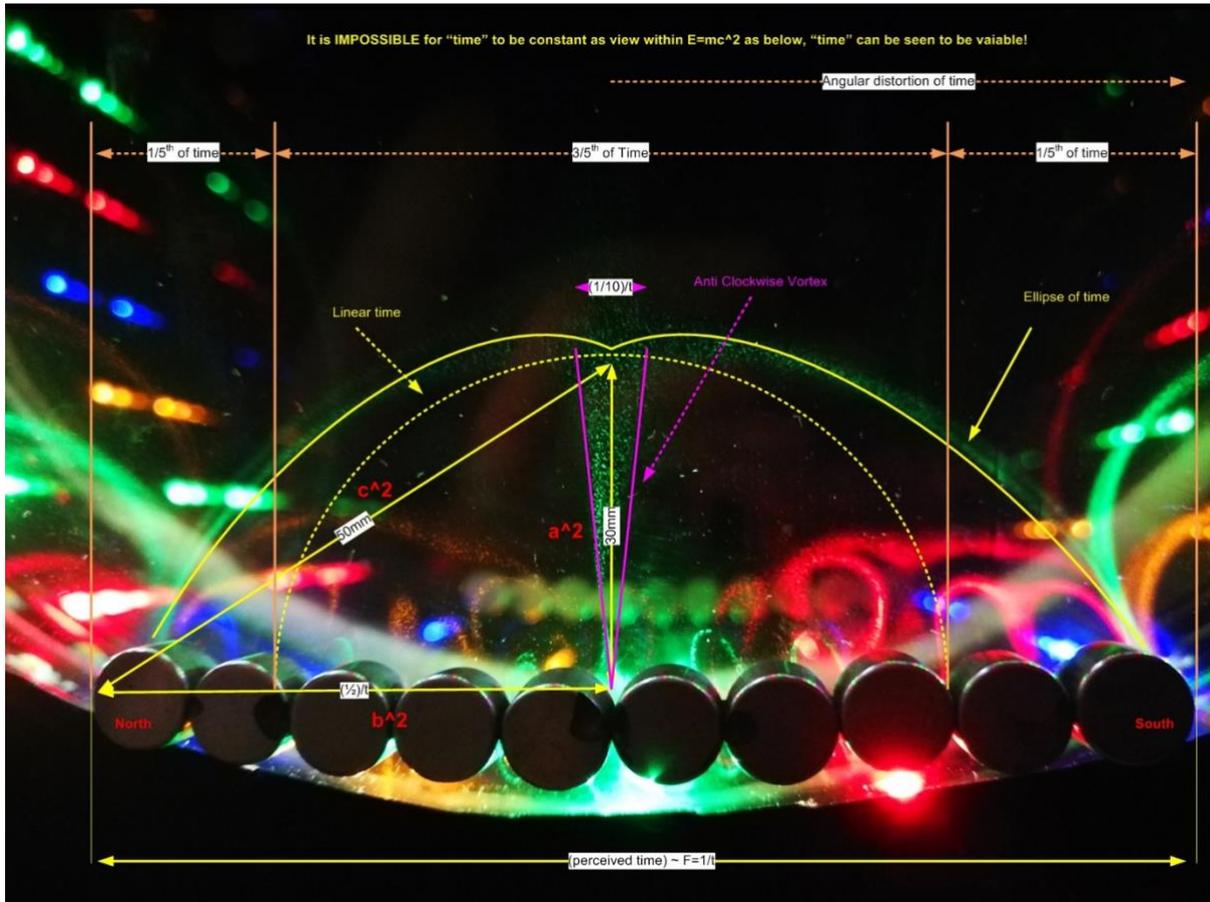
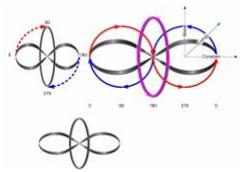
The image shown above is profound questioning many postulated theories. In doing so, the image requires humanity to reassess how it believes the universe is formed, how it functions, and where the universe's energy comes from.

Introducing a second image creates many other controversies; Where the definitive answers reside within the image and cannot be contested.



1. It can be clearly seen that magnetic bodies have more than **TWO** polar fields, and an obvious imbalance exists between the energy fields.
2. In the center of the image is a **NEW** magnetic field that until today has never been viewed or evidenced.
3. It can also be seen that the middle field is in **MOTION** forming a double toroidal vortex of energy in a clockwise and anti-clockwise direction from the zero-point and creating its own **ZERO POINT** above the magnetic body,
4. The magnetic field is ejecting its energy both toward the conditional North and South; It can be seen that the ejection of energy towards the polar conditions form their own helical vortex towards each polar condition. This ensues a force that will be addressed as the **MAGNETIC MOTIVE FORCE**, thus energy from a stationary body, that is contradictory to all laws of thermodynamics.
5. In addition to the **THIRD** magnetic field, many smaller transient fields can be seen to transverse or cross closely to the magnetic body proving the existence of magnetic surface wave propagation; When two or magnetic bodies are correctly aligned, the magnetic surface wave propagation is amplified via the infinite condition of the cones of convergence that exist between any two points.

The images above question the validity of the most fundamental definitions that humanity uses today. In order to justify the aforementioned, I present below a more detailed image overlaid with factual information:



For reasons of understanding, all artifacts or possible deviations were removed; The magnets were aligned and “tuned” to their transverse polar fields and NOT to the customary North-South condition. The state of infinity was set in both directions of plus ∞ and minus ∞ ; as well as the cones of convergence.

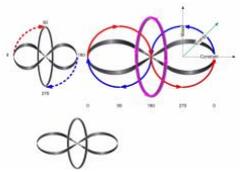
The transversal frequency of the surface magnetic wave results in $F=1/t$, where $F=1/t$ is two times ∞ . The zero point or ejection point is formed at the sum of the differential of plus and minus creating a NON-ZERO-SUM accumulation via the cones of convergence.

Establishing “North” (or “South”) as an origin and the zero point as a second origin results in a right-angled triangle or the Pythagorean condition of $a^2+b^2=c^2$.

Applying a linear time constant to the energy ejection [and] rotating 90 degrees places the ejection energy level at 3/5 of the magnetic body confirming the 2/5:3/5:1 magneto energy imbalance.

Plotting the outer ellipse (or curve) back to the origin of North (or) South shows the ellipse of **MAGNETIC TIME** versus the state of **LINEAR TIME** based from an origin of zero.

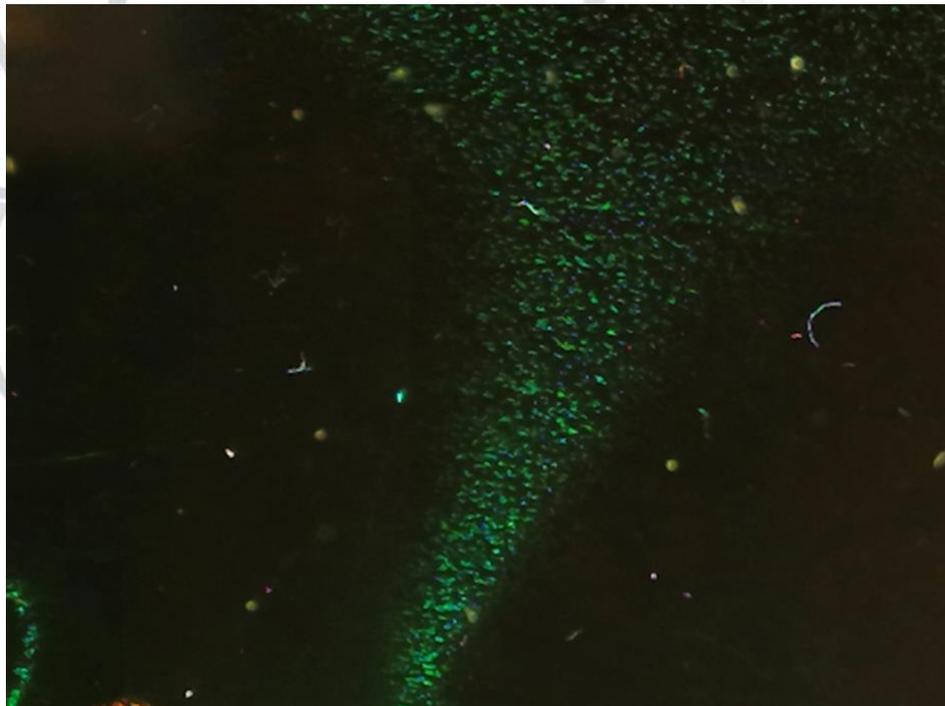
Reviewing $F=1/t$ as 2 times ∞ (of one event in linear time) showing that the ellipse of magnetic time is greater by a factor of 2/5 of its linear time self; and furthermore, the 2/5 (of) the magnetic time error are equally displaced between $-\infty$ and plus ∞ via a NON-ZERO condition.



Using the velocity of light of $3 \times 10^8 \text{m/s}$ as a formal constant and binding that constant to the linear time constant as shown, results in THREE different velocities being displayed within the image, those being a^2 , b^2 and c^2 .

The result proves “Visually” and “Mathematically” that the speed of light within a magnetic body is NO LONGER a constant, and that time within a magnetic body is a differential and NOT a linear condition; and that time can be displaced by a factor of 1/5 in either direction within a complex set of magnetic bodies.

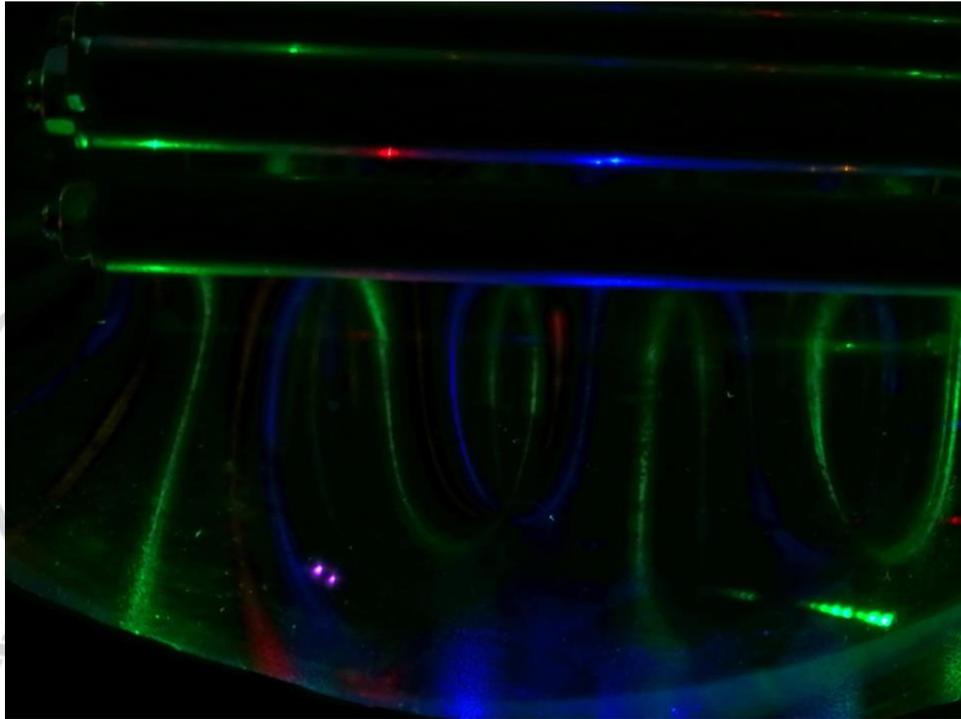
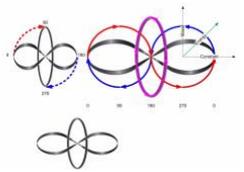
The magnetic motive force is a provable physical movement of the energy within a set of magnetic bodies contrary to current teachings; Knowing that the magnetic motive force exists and moves, this allows for the building of a device known as the kinetic linear motor. Below is a magnified view of the movement within the toroidal field:



The ejection point is at the bottom of the image with the toroidal ejection moving upwards and away from the NON-Zero point of the cones of convergence. The movement can be seen to be both clockwise and anti-clockwise, (or) a double helix structure. It can also be seen that the helical structure has an offset angle of 45 degrees; Knowing that magnetic energy moves is one thing; knowing its direction is better and understanding the two functions is the key to building the kinetic linear motor, (which had been demonstrated by myself to the Ministry of Defense U.K.).

The magnetic motive force is governed by the intrinsic energy ratio within a magnetic body, that being 2/5:3/5:1 of the overall magnetic body.

When two or (more?) magnetic bodies are placed into a permanent state of repulsion they form what is known as a **Synthetic Inertia Plane (SIP)**. When multiple SIPs are placed together the magnetic field can be seen to move in a clearly defined helical pattern external to the magnetic body of origin; This is magnetic convection and is shown in the image below:

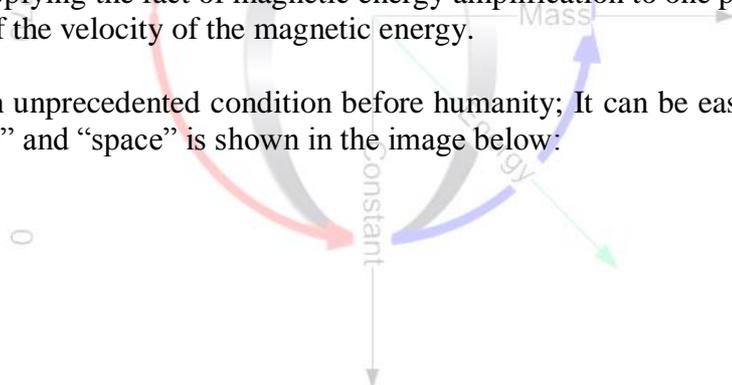


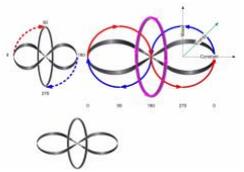
The magnetic energy can be seen to form loops moving from right to left, (or) from South to North (or) 3/5:2/5; this was achieved by applying a doppler shift process of luminescence (Green towards and Blue away). It can also be seen that the “loops” of energy are paired, with one traveling clockwise and one anti-clockwise emanating from the NON-Zero point of the cones of convergence (or) midpoint of the SIP itself.

It has been shown that magnetic energy becomes “accumulative” when two or more magnetic bodies are correctly tuned along the axial energy path, and not the polar path. It has also been shown that the amount of energy released is proportional to the number of magnets used. It has been shown that there is a velocity mismatch and a time mismatch within a set of two or more magnets; As well, it has been shown that when two or more magnetic bodies are placed into a SIP configuration the amount of energy release is further amplified.

As the energy IS **accumulative**, it poses a new conundrum: that of the static definition for the maximum speed of light, which has also been shown to be contradictory. Applying the logic of one plus one equals two, and applying the fact of magnetic energy amplification to one plus one, results in the amplification of the velocity of the magnetic energy.

This outstanding fact is setting an unprecedented condition before humanity; It can be easily visualized, and this event in “time” and “space” is shown in the image below:



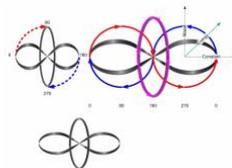


The above image displays six axial polarized magnets, (north and south to the side and not top to bottom); the axial diametry allows for each magnet to be turned through 180 degrees without affecting the polar or the natural inertia plane of the magnet itself. When done correctly, the cones of convergence force each magnetic pair to eject its energy towards a center point, and as every ejection is both clockwise and anticlockwise, the energy amplifies itself to the two adjacent fields; This process is repeated to infinity. It can be seen that at a point slightly off center (330 degrees) a BLACK area appears. This black area is where light is accelerating beyond visibility (or) at a velocity greater than $3 \times 10^8 \text{m/s}$ (as previously proven in earlier images of this document).

The following question arises: *“If the velocity of the energy of a combined magnetic body is greater than $3 \times 10^8 \text{m/s}$ (per magnetic body) and magnetic energy is accumulative as a body of energy and velocity; then the image above suggests that the light entering the BLACK area must by all mathematics’ and physics’ probabilities be faster than $3 \times 10^8 \text{m/s}$ or GREATER THAN the static speed of light”.* This too was demonstrated on the second floor of Lewin Building, at the Royal Naval base of HMS Dryad, Southwick, Hampshire, before Professor Lt. Cdr. Ian St John-Stevens who validated and confirmed my findings.

A device 3cm in diameter was built, that when attached to another device that I projected and made myself, produced 60Kw of energy per gram of magnetic body. In addition, when the device was viewed from the side and a laser light was introduced, **NO LIGHT** came out [!], yet when done in reverse the laser light was amplified proving that the light had been accelerated in one direction and decelerated to zero in the other. The demonstration was two hours long, late in the afternoon. It was strange that Lt. Cdr. Ian St. John-Stevens being the ONLY professional body to have observed and being able to validate this technology strangely died of a heart attack within 24hrs [?]. This technology had been created more than THIRTY YEARS ago, and produced unlimited clean energy, mass displacement (anti-gravity), propulsion and time dilation; but it was ALL **SURPRESSED** by the Ministry of Defense of the United Kingdom.

This document accompanies the PowerPoint presentation entitled “MHI - Magnetic Holographic Imaging”



Understanding the geometry of the magnetic fields:

Yes, it is correct to suggest that a magnetic body has TWO defined fields of North and South; However, this is NOT the whole truth. As shown within the previous pages there are many more fields and polarities. Yes, it is true that North or South display an attraction and/or a repulsion; Likewise, the subordinate fields offer both attraction and repulsion [BUT] the new fields do not have a dedicated polar response, (North or South) but display a doppler movement at +/- 360 degrees to the plane of polarization.

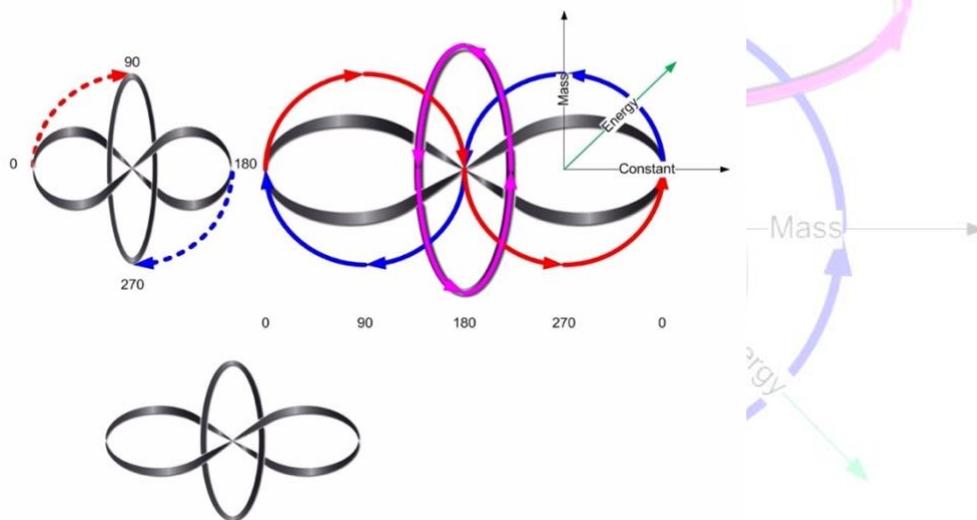
Amplifying the above:

Today, a magnet is treated as North and South with the polar inertia plane along the axis of orientation of the polar fields; And when a magnetic body has its polar orientation set to axial diametric (left to right rather than top to bottom), the polar inertia plane also rotates from *top to bottom* towards *left to right*.

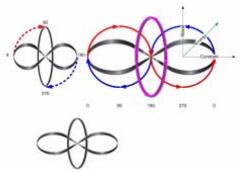
The magnetic toroidal pump:

The newly identified magnetic field (which comprises of many smaller fields) acts like a toroidal pump defining the magnetic motive force itself, where the energy within a magnetic must come from somewhere [!]; That somewhere is the sum of two forces working in harmony, those being a state of infinite compression and the state of infinite vacuum. If it were possible [...]; To stop the magnetic motive force for an instant in time, and to be able to “walk” the path of the toroidal field it is easily deduced that the customary definition of infinity (∞) cannot be so [!];

Today, ∞ is defined and depicted at TWO times 360 degrees interlinked in some form that is akin to a Mobius ring. Alas this representation fails to encompass the bi-directional doppler fields that MUST be present within the depiction in order for the definition of infinity to exist; And, therefore, to ADD the “Bi-directional” rotational forces of the new doppler fields to that of the customary vision of ∞ results in [Bi-Directional of 360 degrees is equal to 720 degrees] (and) [The current 720 degrees of the current expressed definition of infinity] (results in) [720 plus 720 = 1440 Degrees of infinity].



The above image encompasses both the current thinking of ∞ and adds the bi-directional instance of ∞ resulting in a path that is NOW TWO TIMES ∞ .

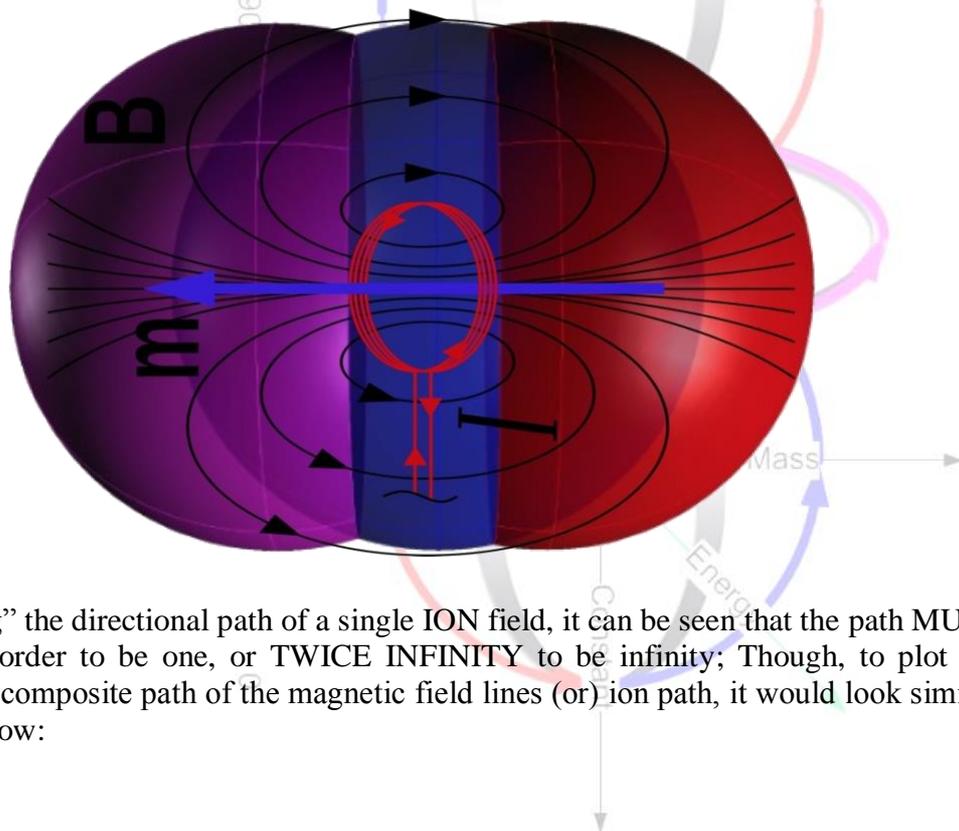


Walking the path of infinity:

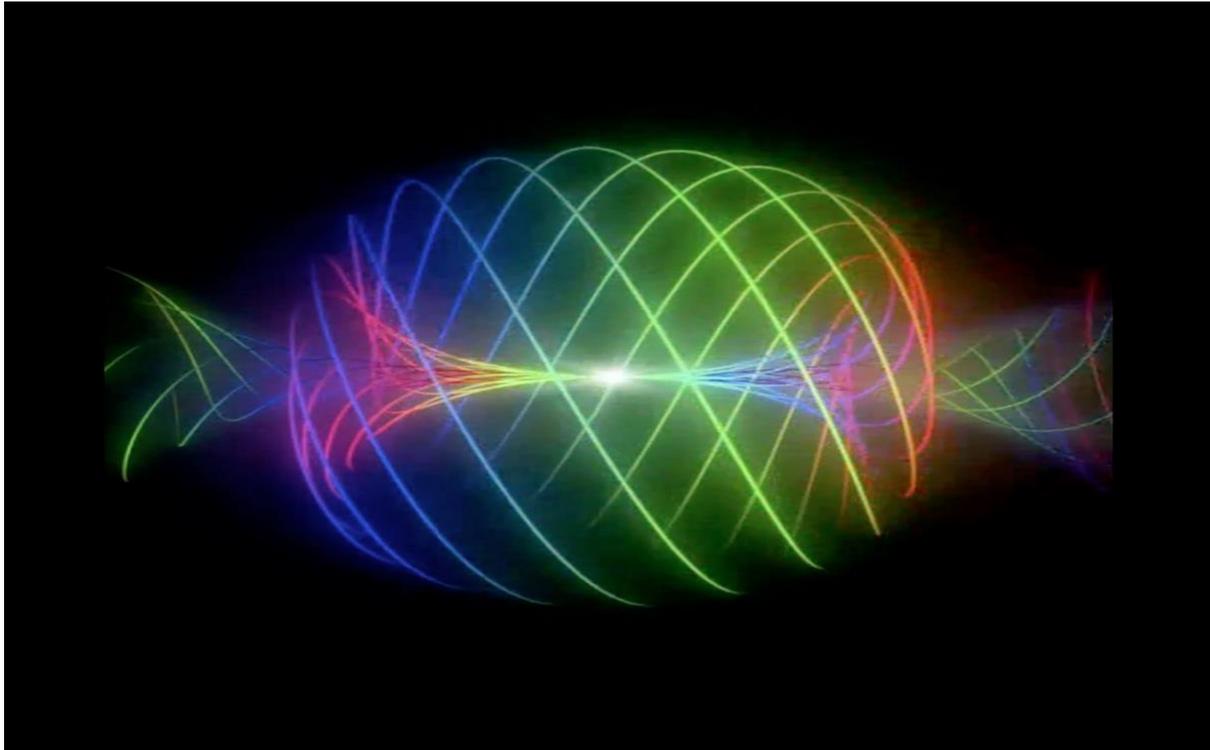
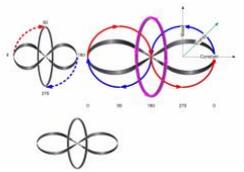
To create a start-point (or) zero point within the new definition of infinity, a “Cartesian” model must be used; This allows for a graticule view of 360 degrees. Establishing “ZERO” of time and “ZERO” of angular incidence [AND] “ZERO” of motion sets a point of localized origin to the left center point of the Cartesian model offering the contemporary view of a transition from North to South via 360 degrees, and its reversal path of 360 degrees from South to North (as depicted in RED and BLUE). That is as far as the current logic goes; Alas, this fails time, this fails zero and this fails movement!

In reality, the path does NOT transverse ∞ in a left to right (or) top to bottom fashion, but in fact rotates through 360 degrees within half the time constant within the magnet. This forms a twinned Mobius function as follows:

With the origin set to ZERO (of) ZERO (of) ZERO [Left center point], the path follows a clockwise motion rotating through 180 in both “x” and “y” axis’ (or) a combined 360 degrees of polar shift, and enters for the first time the finite point of the cones of convergence exiting at 180 degrees from the origin to an apex point and is equal to $\frac{3}{5}$ th of the body mass of the magnetic field; The path then rotates (again) through 180 degrees (x and y) or another 360 degrees clockwise, perusing the original polar axis towards a Cartesian point of ZERO [BUT] at the other end of the magnetic body. Holding at this point in time, so far, the magnetic path has transverse’d “x” and “y” polar planes twice [BUT] has only traveled half of the magnetic field, (or) [360 plus 360 = 720 degrees]; The magnetic field then continues to follow the clockwise path forward mirroring the path for another 720 degrees. The result is 720 degrees plus 720 degrees in 1440 of infinity [!]”.



When “mapping” the directional path of a single ION field, it can be seen that the path MUST travel twice in order to be one, or TWICE INFINITY to be infinity; Though, to plot the “synthetic” (or) composite path of the magnetic field lines (or) ion path, it would look similar to the image below:



To consider the image above, (as a single event in time) or (a single path of an ION) shows that the ION itself travels via THREE toroidal conditions; Those being as stated:

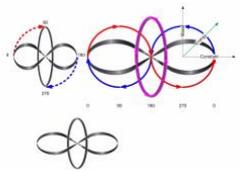
“With the origin set to ZERO (of) ZERO (of) ZERO [Left center point], the path follows a clockwise motion rotating through 180 in both “x” and “y” axis’ (or) a combined 360 degrees of polar shift, and enters for the first time the finite point of the cones of convergence exiting at 180 degrees from the origin to an apex point and is equal to 3/5th of the body mass of the magnetic field; The path then rotates (again) through 180 degrees (x and y) or another 360 degrees clockwise perusing the original polar axis towards a Cartesian point of ZERO [BUT] at the other end of the magnetic body. Holding at this point in time, so far, the magnetic path has transverse’d “x” and “y” polar planes twice [BUT] has only traveled half of the magnetic field, (or) [360 plus 360 = 720 degrees]; The magnetic field then continues to follow the clockwise path forward mirroring the path for another 720 degrees. The result is 720 degrees plus 720 degrees in 1440 of infinity [!]”.

At the center of the image a singularity can be seen (or) a point of minus infinity or a finite point or a zero point. To consider that the entire energy of a magnetic body MUST transverse this the singularity causes TWO conditions to occur:

1. A point of infinite compression (inward)
2. A point of infinite vacuum (outward)

It can also be seen that at each end of a magnetic body, TWO asynchronous fields are present, and both are rotating in a clockwise motion. To isolate each and working from Left to Right:

1. A centripetal (ejection) occurs outwards towards infinity
2. A Centrifugal (surface wave) occurs towards the opposing end of the magnetic body.

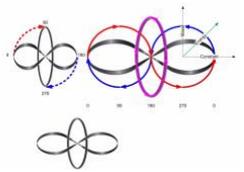


3. A return or bi-directional Centrifugal surface wave compresses to infinity (at the sub-atomic level) before ejecting towards the left centripetal action.
4. From the right (center), a centripetal (induction) occurs towards the zero-point forming a second asynchronous compression point, before being ejected to form point [1].
5. This dual asynchronous compression and expansion creates the Magnetic Motive Force (MMF) which results in two unique conditions.
 1. The polar attraction or repulsion (based on the clockwise motion) which results in a "SPLINE LOCK (*two contra rotating paths interlocking*)" mechanism at the sub atomic level.
 - (a). Clockwise to Clockwise creates repulsion
 - (b). Clockwise to Anticlockwise creates attraction (Spline lock)
 2. The toroidal motion of infinite compression and vacuum (or) MMF, Magnetic Motive Force.

Contradictory Analysis (MMF)

To apply VISUAL analysis and "logic" to Euclidian mathematics and geometry, (or) the founding principle of $E=mc^2$, and the laws of thermodynamics defines many contradictory arguments; Those being:

1. $E=mc^2$ defines "Energy" as equal to mass times constant squared. However, within this postulate and shown within the enclosed images this cannot be so. It is clear that the greatest amount of energy is located closer to zero than to any other point. This creates an inversion to $E=mc^2$ insofar as the Energy is equal to "A" magnetic constant and NOT the constant of the speed of light of $3 \times 10^8 \text{m/s}$. Light CANNOT be constant as shown; If the speed of light were to be constant then there could be no cone of convergence, as a cone of convergence causes a variation from infinity to minus infinity.
2. Thermodynamics: A body at rest has no energy; How can this be so [?], When a magnetic body is at rest it generates energy, and the energy created passes through a zero point or a point of negative infinity resulting in energy and matter being continuously generated by a stationary body.
3. Thermodynamics: Entropy defines a state of less than 100% efficiency; How can this be so [?]; As, a magnetic body at rest produces energy at a rate of 100% efficiency with no wastage what so ever. If Entropy were to be applied to a magnet, a magnet would not be a magnet!
4. **TIME** as a UNIVERSAL constant can be defined as from 0 to ∞ step ($\infty - n^{n-1}$); Where time within the image of a magnetic body varies. To consider the "x" plane time expands and compresses over the length of the magnetic body, and to consider the "y" plane, time contracts and expands; while in the "z" plane time collapses to zero (or) to a finite point; Therefore, for time to be constant the images within this document could not exist.



Section II

The Fibonacci sequence and magnetic association

The Fibonacci sequence is nothing new, alas the sequence has been treated with triviality to a point of *near extinction*. The foundation behind the fundamental equation to the Fibonacci sequence (that of) $x(n) = x(n-1) + x(n-2)$ also forms the principle construct of magnetic fields; where to review a magnetic body in isolation (it) forms the very first numerical part of the sequence, insofar as:

- One magnet is a whole or (0)
- It has one North (1)
- It has one South (1)
- It has two distinct fields (2)
- It has three associated magnetic fields (3)
- It has five inertia directions (5)
- It has eight fundamental vortex directions (8)

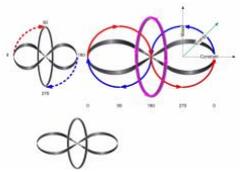
Giving the result of 0, 1, 1, 2, 3, 5, 8. But it does not stop there; a magnet is the reflection of itself, that is to say that if a magnet were to be cut in half or "1C" its mirror of itself is 101, and the accumulative mirror of 101 is 21013 [ad infinitum] and to express this sequence in both its accumulative and its mirrored forms produces:

0, 1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, 144 has a mirrored reflection of 89,34, 13, 5, 2, 1, 0, 1, 3, 8, 21, 55, 144.

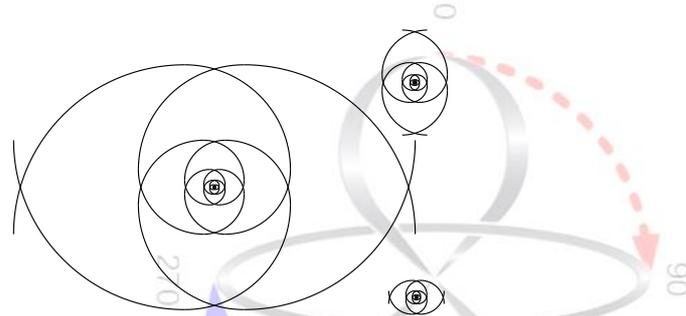
Balancing the sum of the mirrored part results in the sum of (144, 55, 21, 8, 3, 1) = 232 and the sum of (1, 2, 5, 13, 34, 89) = 144

Where the differential of 232/144 is equal to 1.61111^R ; However, to review the reflection there is an **ERROR of ONE**, where the CORRECT Fibonacci sequence should be 233 and not 232, this is due to the reflective part of the real part of the imaginary part of the mirror; where to recalculate with the differential of ONE is to form the result of 233 / 144 resulting in **1.681** which, is in fact, **the golden ratio** confirming that a magnetic body is built upon the Fibonacci sequence, and this is why there is an imbalance within the North and South fields of a magnet, and this is why the toroidal ejection fields equates to exactly 0.681 or the overall magnetic energy released.

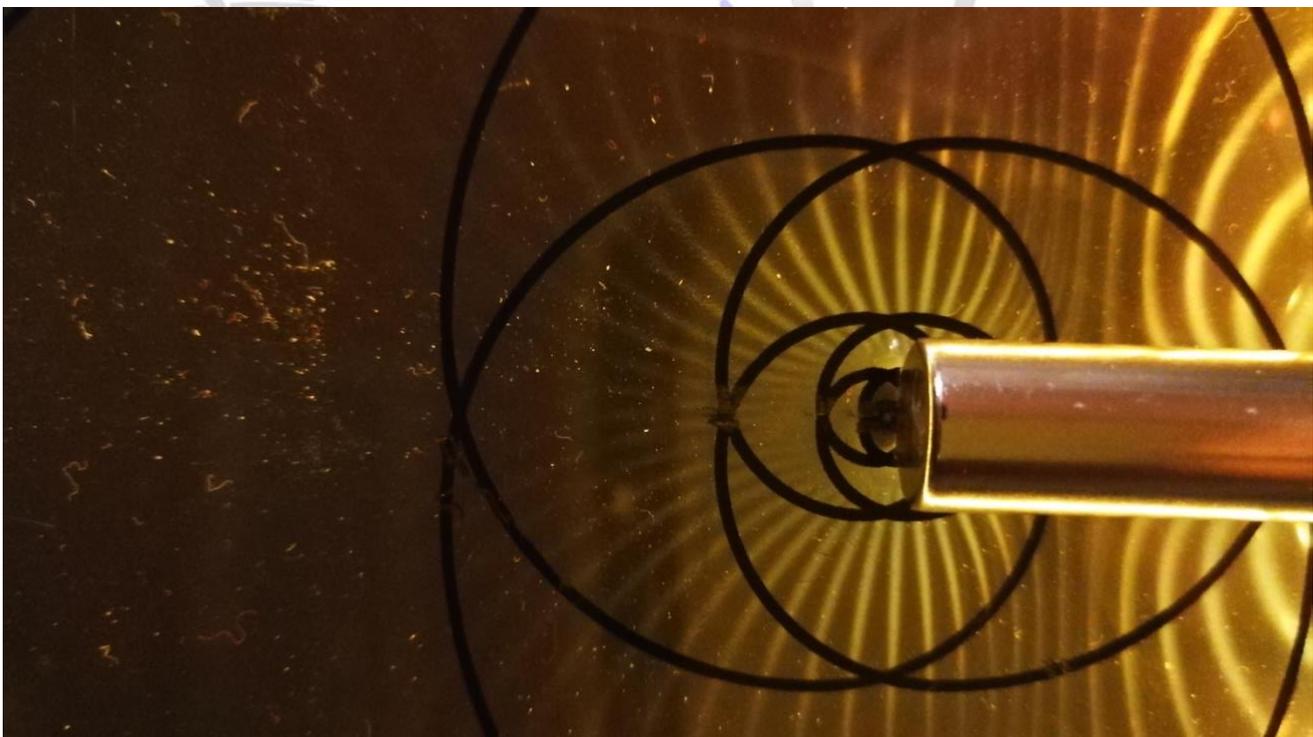
This condition is further exemplified when applying $a^2+b^2=c^2$ where the result for a given magnetic sequence as shown on page [7] results in (a) being equal to 5, (b) being equal to 3 and (c) being equal to 5.830; again proving the distance of (a to c) is greater than (a to b), and applying the speed of light to the same function results in the visible fact that the elliptical curve within a magnet (a to c) must have a velocity of 0.830 greater than the velocity of (a to b) and (b to c) has a velocity of 0.830 less than (a to b) resulting in a computational condition of THREE variables for the same instant in time.



To apply a computational condition to a fundamental mathematical problem requires an analogue to both calculate and confirm the computation; This was achieved with a transparent graticule of a four-way Fibonacci sequence as shown below:

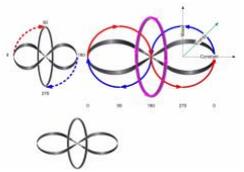


The transparency was used as a reference scale place upon the surface of the MHI (Magnetic Holographic Imager)

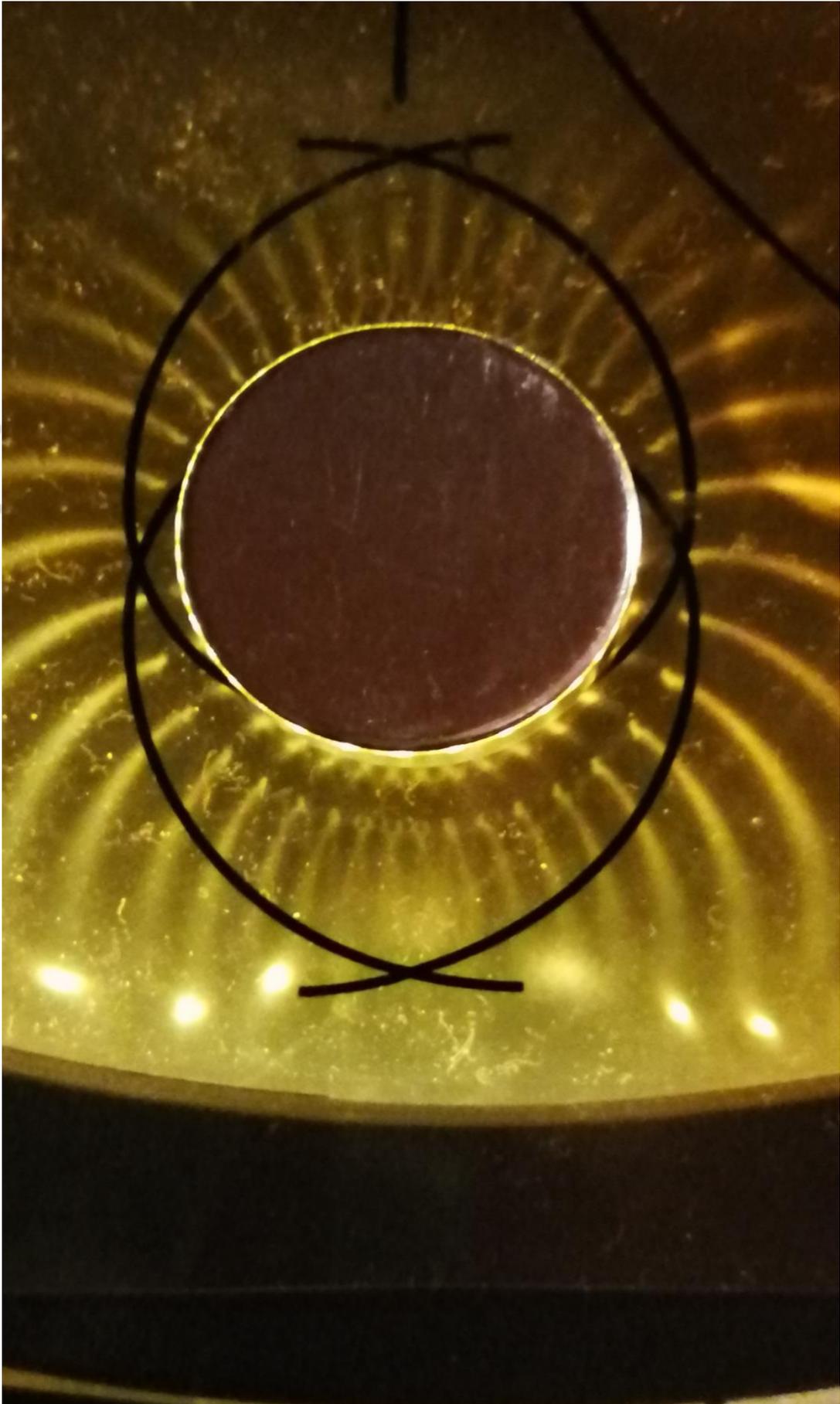
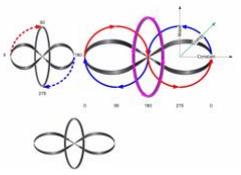


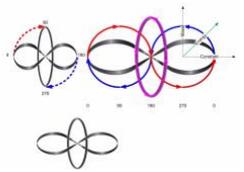
The “Eye” of the graticule was placed over the toroidal ejection, and it can be seen that the magnetic field lines emanating from “zero” do so in a radial pattern; though to review closer, it can be seen that both convergence and divergence are present within the same radial condition. It can also be seen to the right of center the second toroidal ejection forming at the cross point of the Fibonacci graticule; And, at the right center of the magnetic body a ZERO condition forms, where the formation of the zero condition is proportional to 1.1681:1 of the length of the magnetic body.

Repositioning the graticule [off] center to the first natural alignment of the graticule displays toroidal ejection and its corresponding twin helix’s and each magnetic field line increases proportionally to 1.681:1 of the previous field line.

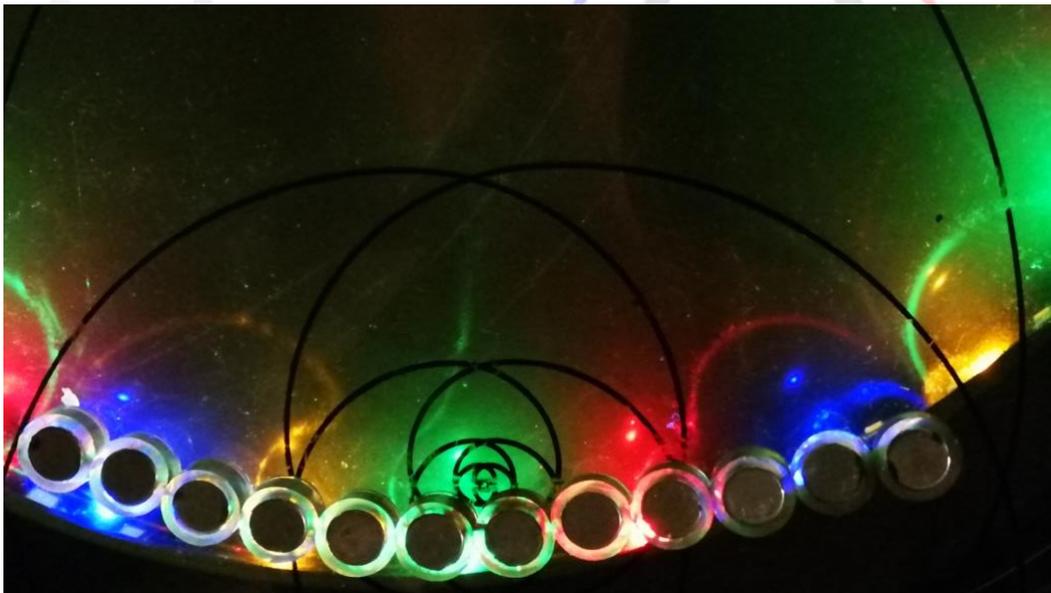
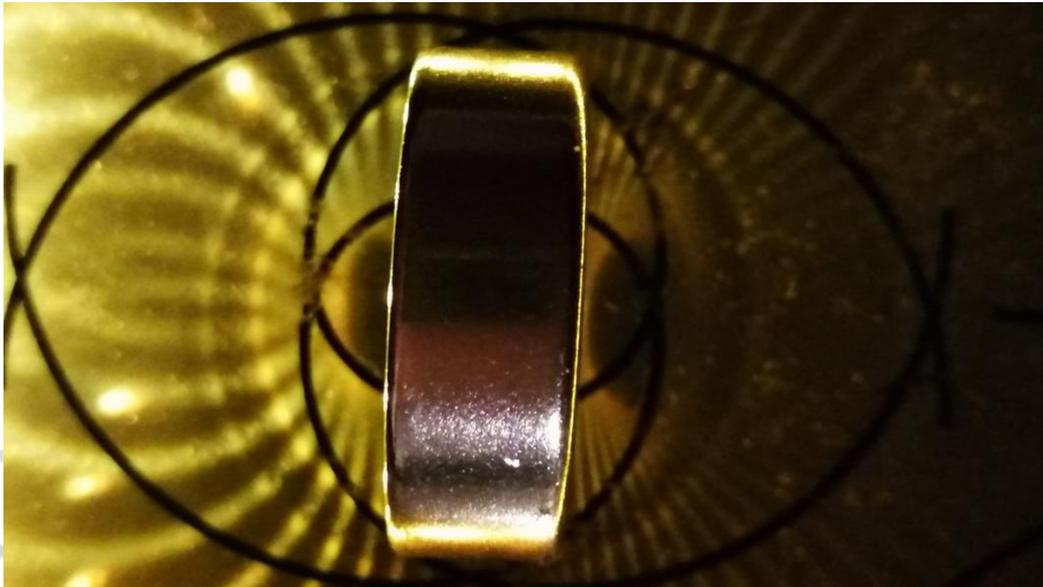


To further substantiate the construct of magnetic field lines to the Fibonacci sequence the diometry of the magnet was change and the size and orientation of the graticule; a 25mm diameter polar magnetic body was used which produce this stunning image. Not only do all magnetic field line **MAP** perfectly to the graticule but the inner toroidal vortex can clearly be seen. Within the toroidal vortex a twined pair of helixes' can be seen along with the North/South divide occurring at the cross point of the graticule.



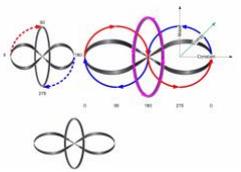


It does not matter the type of diometry of the magnet, the field line will always align to the graticule.



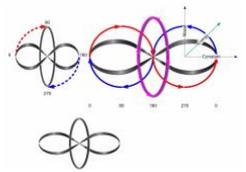
When a complex set of magnets are viewed, it can be seen that the graticule aligns perfectly to the corresponding and predicted magnetic field lines confirming beyond all reasonable doubt that a MAGNETIC field is fundamentally built from the Fibonacci sequence.

Be it one magnet or many magnets the sequence will always be the same, that of 0,1,1,2,3,5,8 [...] of the Fibonacci prime order. Though it has to be understood that the prime order of 0,1,1,2,3,5,8 [...] is actually WRONG and must always be mirrored based around an axis of zero; Thus, the “Fibonacci Integer Resequencing Mirror (FIRM) would result in 8,3,1,0,1,2,5; where the mirror “terminator” must be an even set of Fibonacci numbers. When two magnets



are aligned along the axial diametric plane the cones of convergence occur at the contact point of the two circular bodies. This contact point is ONE molecule wide and look like this:





The power of ZERO

Magnetic Holographic Imagery (MHI)

In order to produce the images in this document, (that have never been viewed or witnessed before); a unique device had to be constructed; And, in order to build such a device, a very intimate understanding of a magnet was needed:

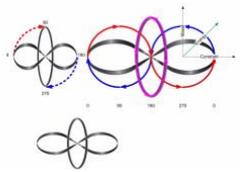
1. A magnet has many magnetic fields
2. The fields are three-dimensional
3. The image must be viewed from the fourth perspective
4. The image must be a time slice of the magnetic fields similar to MRI scan
5. A material that vigorously interacts a magnetic field must be used
6. The material must be fluidic in its composition
7. The absolute minimum thickness is required
8. A process to illuminate the material is required
9. A 360-degree 3micron time slice defines a single event
10. An inert viewing platform is required to hold the 3-micron fluidic material in place

In order to define a measurable calibrated constant, the MHI was designed to meet a value of ONE, (that being one meter). The one meter was the circumference of the MHI device itself resulting in that the viewing platform at [10] above was constructed at 318.1805mm in diameter. That gave a 3.1428795:1 (x and y) calibration accurate to six decimal places.

To define the 3-micron condition two plates of optically milled and polished (clear) glass were used with a polishing depth to 1.5-microns per plate. This defined the condition at [9].

Illumination defines the angular accuracy of the MHI; Therefore, this value forms the angular index; A 10-point light source is accurate to 36-Degrees, and 100-point light source is accurate to 3.6-Degrees and a 1000-point light source is accurate to 0.36 of one degree. The result is that a device with a circumference one 1-meter (1000mm) was divide into a binary (on/off) light source at a 2:1 ratio resulting in 500-point light sources giving an accuracy of 0.72 degrees as a deinterleave rate.

A magnetic field is not a singularity but is formed from many subordinate fields as shown within the many images presented; And, where the velocity within those fields also varies. In order to view and measure the velocity, a color scheme was used to take advantage of the doppler motion within the central toroidal fields(s) and graticule measurements were taken along with the application of known and trusted constants. It is known that all color(s) respond (as a velocity) as part of any light source; This can be exemplified as a rainbow and the curve that is witnessed. Light (as a velocity within a rainbow) must be going faster at the blue end of the spectrum (700nm) than at the red end of the spectrum (420nm) else a rainbow would be a straight line; As to say two waves of different length do not measure the same length, yet when the two wavelengths are positioned upon a curve it is possible to make the start and end points match; once again proving that $\prod > \infty$.



Utilizing the previous facts and the desired requirement listed at points 1 to 10 of the previous page, a device that has become to be known as the (MHI) “Magnetic Holographic Imager” was built.

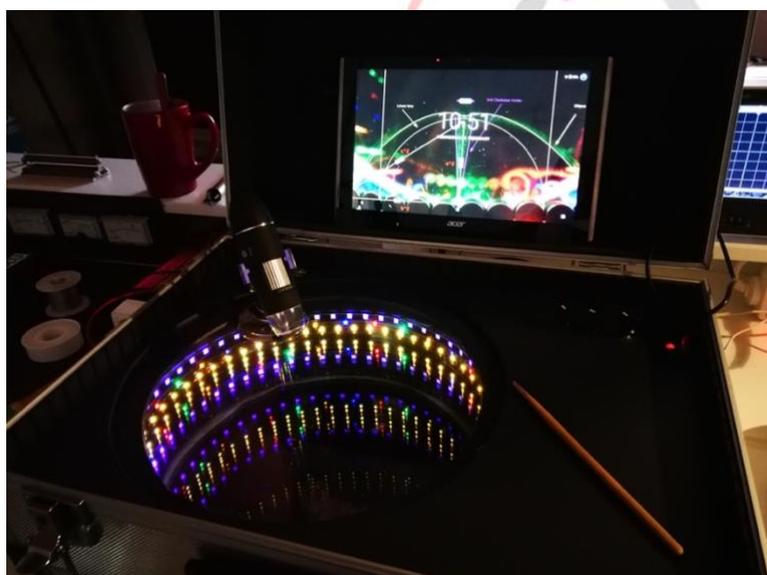
To take advantage of multiple spectral analysis, the MHI was outfitted with three separate spectral arrays:

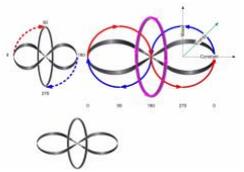
1. Red, Blue, Green, Orange (430 ~ 700nm separated by 67.5 +/- 1nm)
2. Broadband White (at 6500K)
3. Ultra Violet (470nm)

In order to “mix” or utilize multiple spectral arrays a three-way variable resisted power supply was used. This allowed any of the arrays to work from less than 5% luminescence to 100% or (10 ~ 12v variable per array); In addition, this allows for mixing or “color tuning” of one or more arrays. The mixing of array colors allows for the vivid contrast within the images, and when using only the RGBO array, it allows for the visualization of NOT two BUT four unique fields. Where to color-code the fields results in Red ~ North, Blue ~ South, Green ~ Doppler acceleration, Orange ~ Doppler deceleration. To enhance the holography a black mirror was added to from the spacial reflection.



To complete the MHI base configuration the MHI lens's, light arrays and mirror where housed in an aluminum case finished with a non-reflective black surround. To aid viewing a 10” hi resolution smart-tablet was built into the case, along with a USB-C 1000x resolving microscope. The smart-tablet has a full “OPEN IP” web broadcast function enabled with image tracking. An x, y axis microscope table (tunable to 1mm) was added, and standard imagery can be taken with and modern DSLR or High Resolution (20 megapixel and above) smartphone.

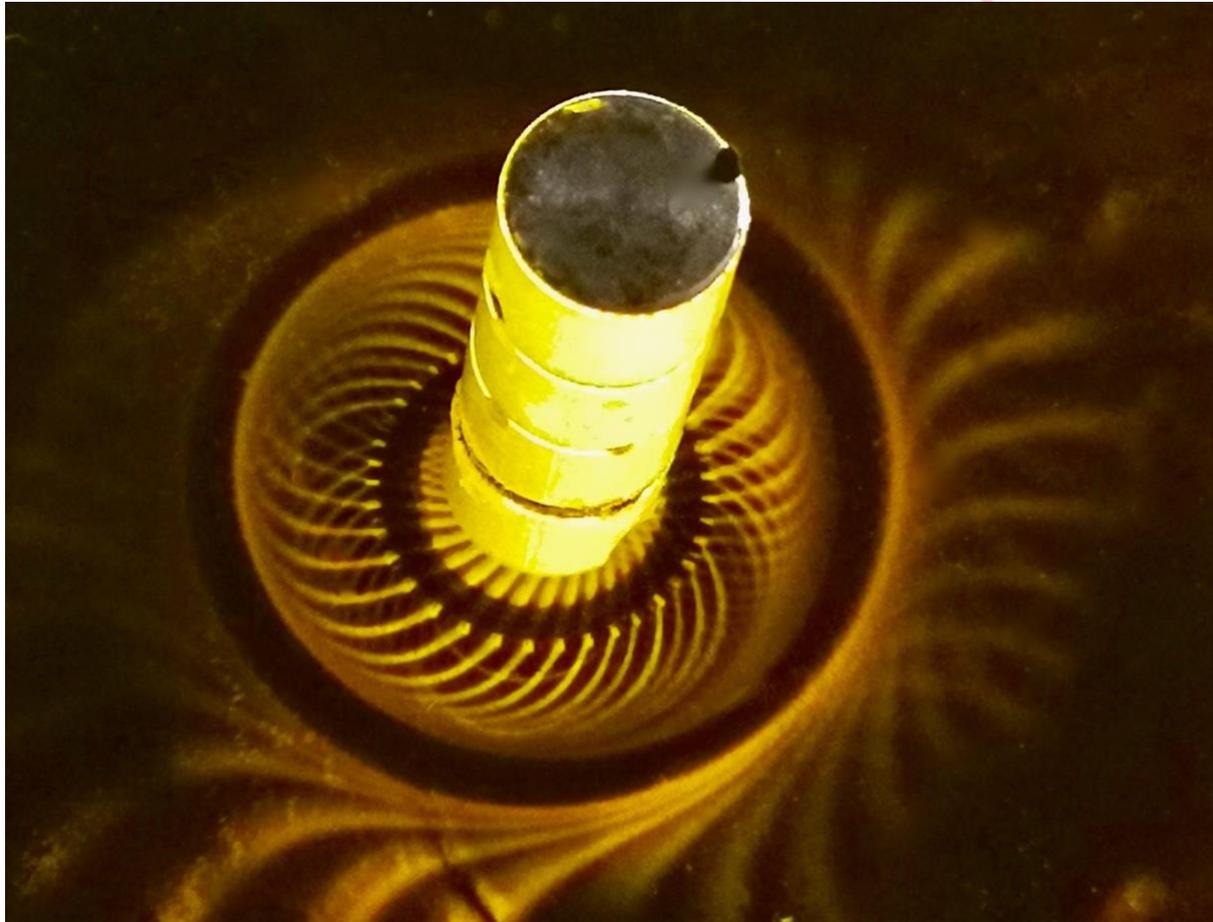




The Magnetic Motive Force

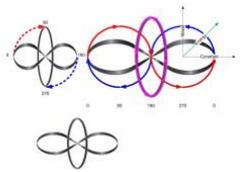
MMF

Contrary to physics in general and the wider field of academia; Magnets MOVE. It is not suggested that a magnet jumps around on the table all by itself, but the energy within a magnet is in a state of permanent movement which has been previously described. The only clear way is to view the movement first hand via the MHI as shown below:

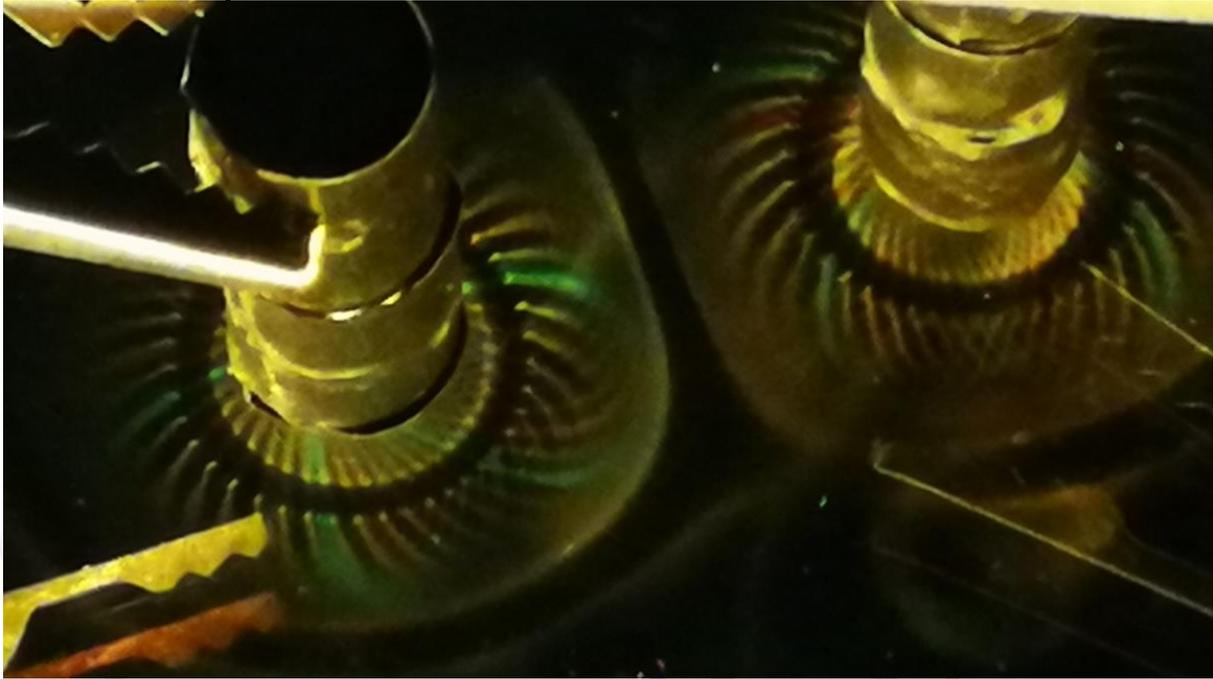


There are four diametric polar axis' magnets arranged in a unique manner. The arrangement or configuration allows for the visual verification of the toroidal field's, and I DO say field's as plural. Viewing from the center axis of the base magnetic body (8mm diameter), a first toroidal ejection can be seen at 2mm in length rotating clockwise and "down-angled" at plus 45 degrees. The magnetic field then loops under itself to form a second and a third event (or) a paired toroidal field 8mm from the body of the magnet extending for 10 to 11mm before creating a VIOD, a fourth paired toroidal field can be seen accelerating to infinity at the periphery. The energy at the periphery forms what is known as the magnetic self-seduction range (MSSR); This is the point where two magnetic bodies have no direct influence upon each other. For there to be an x, y, and z movement forming the multiple toroidal fields MOVEMENT must exist; This is the magnetic motive force.

It can also be seen that the outer most field can be seen to be rotating counter clockwise; Thus, two contra rotating magnetic fields forming the "spline lock" process. The spline lock causes one of two actions, two likewise (clockwise to clockwise) create a repulsion, and two different (clockwise and anti-clockwise) create an attraction. The spline lock within the toroidal fields

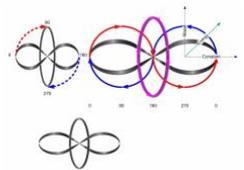


works at the sub atomic level, and it does not matter how powerful the viewing optical device is, there will always be the same visual effect.



Above, two sets of four magnets were configured to give the same polar diometry resulting in both sets of fields rotating in the same direction. The visual outcome of this configuration is a repulsion of the magnetic bodies. To note although the fields are equal in all directions a perfect parallel void is formed between the two opposing fields, but this opposition does not affect the internal geometry of the inner toroidal void. However, when two different rotational forces (the





lower image) were presented to each other, instant attraction occurs, along with the deformation of the inner toroidal void. RGBO was used to hi-light a single field (Green); and it can be seen that the green field of the left magnet at 120 degrees is rotating anti-clockwise to merge with the green field at 270 degrees on the opposite magnet. This process is repeated for all merging fields, but for this demonstration the green fields were hi-lighted to offer clarity to the viewer.

Having isolated the rotational direction, the toroidal filed(s) the spline lock process, the centripetal force and the centrifugal force, the variation in velocity and the variation in time along with a new magnetic field (doppler non-polarized) has allowed for a device known as the kinetic linear motor to be built. As stated higher in this document, it was built [!], some 35 years ago, and the UK Royal Navy stole the technology along with so much more.

The KLM itself utilizes the above forces against itself in order to create a linear movement from two or more static magnetic fields without the use of super-conductivity. **In its most basic of forms, FIVE magnetic bodies are required. Where those FIVE magnetic bodies are separated into three conditions.**

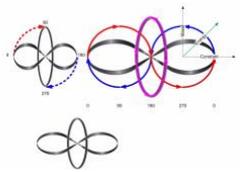
1. Two magnets configured NS
2. Two magnets configured SN
3. One magnet at 45 degrees to the plane of polarization.

To think of this as a complex binary computational state result's in

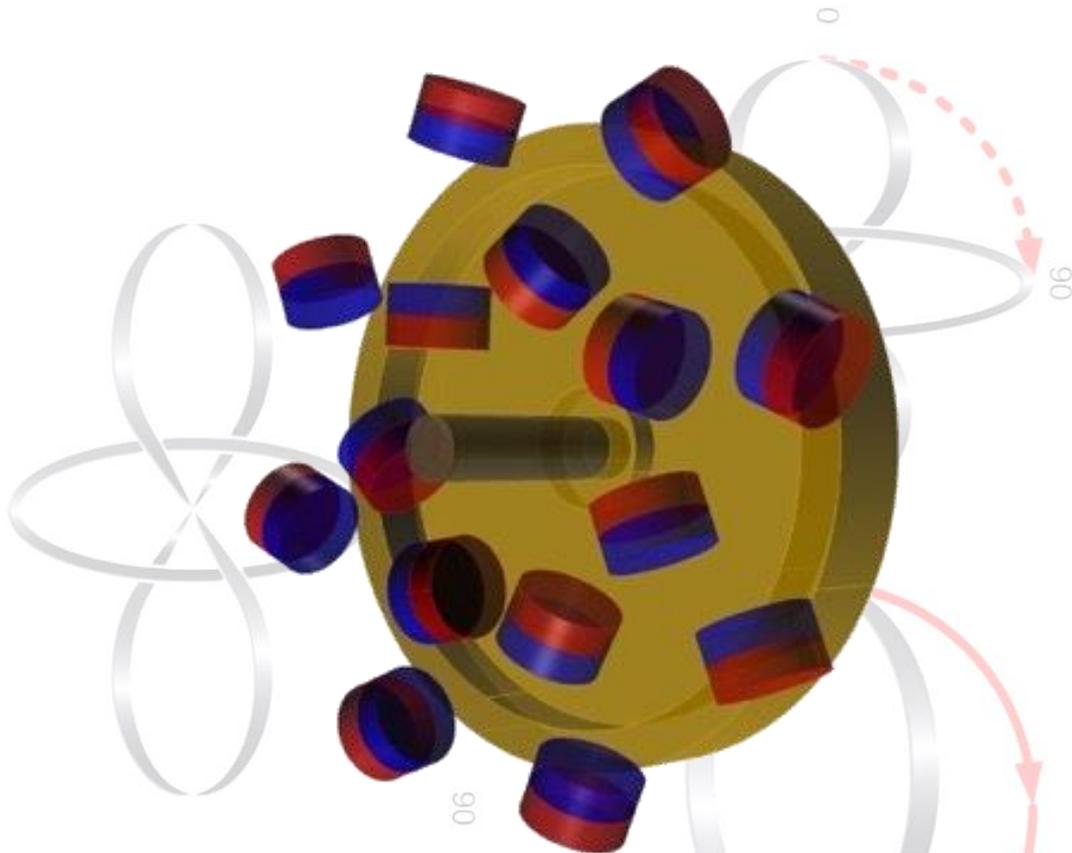


If the left-hand row of magnets were “mobile”, and the diagonal was fixed. When the (MSSR) is breached it causes forward movement towards the first point of the diagonal magnet. As all FOUR moves together, when the first magnetic is located over the top of the first zero it has zero MSSR, the second magnet is now within MSSR and is drawn towards the second point of the diagonal, and the first point now goes into repulsion (MSSR)! This moves the four magnets to position 3 and into an MSSR condition, where two goes into repulsion and three goes into zero MSSR, and finally magnet four goes into MSSR and 3 goes in to ZERO, and 2 goes in repulsion. To now reconstruct the above and to place as a rail track (the sleepers the STATIC of four magnetic bodies) and the “motor” becomes the diagonal magnet. Velocity can be adjusted or controlled by changing the angle of attack between -45 degrees and +45 degree's; Where, at +/-45 maximum velocity is achieved [VERY FAST]. Where very fast is in direct relation to the maximum velocity within the magnetic field. (yes, wind resistance, and localized frictional force will come into play, but the result is a magnetic motive force engine (or) KLM).

The diagonal can also be transposed on to the inner surface of a cylinder and the four magnets are then introduced to create a free mounted rotational force that can be used to power any locomotive process; likewise, the same principle can be used to drive the propellers of ship or the propellers of an aircraft. In fact, the torque is so powerful a turbine engine can be made to rotate without fuel and still produce an infinite thrust.

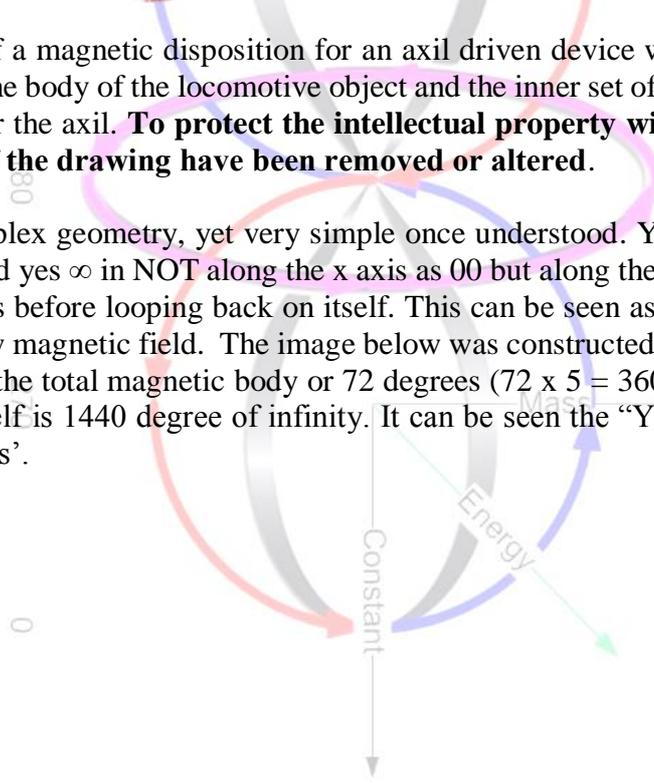


The geometry of the KLM can be increased from $4/1$ to ∞/∞^{-1} where the smaller the magnet, the tighter the magnetic fields the smoother the movement. This is exemplified below.

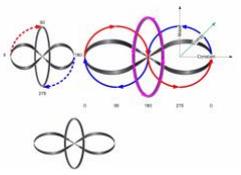


This is a spacial representation of a magnetic disposition for an axil driven device where the outer set of magnets are fixed to the body of the locomotive object and the inner set of magnets are fixed to the rotational point or the axil. **To protect the intellectual property within this document “certain” elements of the drawing have been removed or altered.**

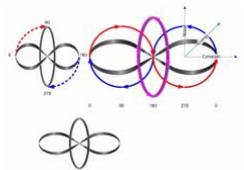
The MMF has an extremely complex geometry, yet very simple once understood. Yes ∞ can be view in both $+/-\infty$ states; And yes ∞ is NOT along the x axis as 00 but along the x, y axis of $|0$ or twisted though 90 degrees before looping back on itself. This can be seen as a mirror of itself and cross validate the new magnetic field. The image below was constructed using 10 curved magnets at exactly $1/5$ of the total magnetic body or 72 degrees ($72 \times 5 = 360$) and 10×72 is 720, plus its mirror of itself is 1440 degree of infinity. It can be seen the “YES” ∞ is present in both the x and the y axis’.



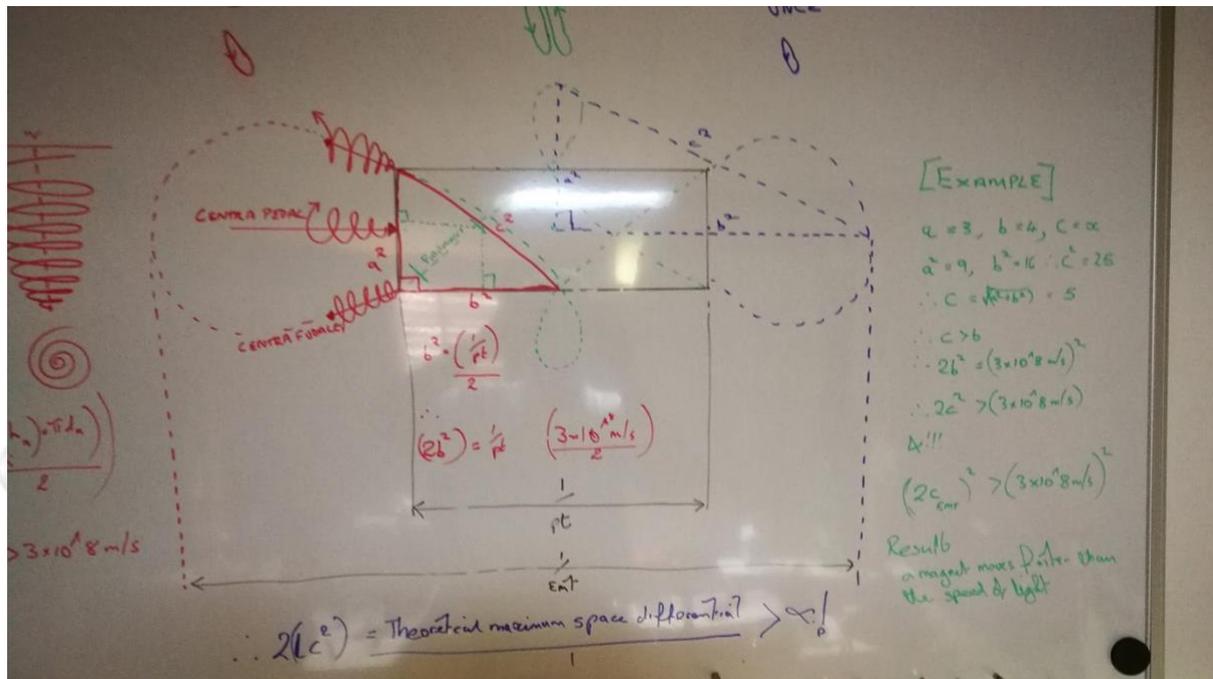
The power of ZERO



To now consider that ALL 10 magnetic bodies create a single magnetic field; Where is North and where is South? The

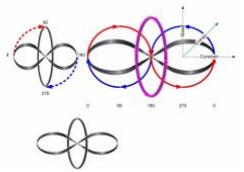


location is best represented within the line drawing below where North and South are defined as Red and Blue, along with the toroidal fields defined in Green. When applying the computational mathematics to the 3d geometry of the drawing many questions arise.



1. $A^2+B^2=C^2$ shows the implicit time error within the body of the magnet and,
2. $A^2+B^2=C^2$ shown the implicit time error within the overall magnetic field,
3. Both centripetal and centrifugal vortex's can be seen,
4. The central toroidal field is also clearly shown,
5. Applying the non-conditional state of ∞ to the image also proves that ∞ must be two times ∞ in order for ∞ to be one of itself,
6. Applying the speed of light constant of $3 \cdot 10^8 \text{m/s}$ to the magnetic body results in multiple values for a constant, thus cannot be a constant,
7. Applying a time differential to the physical body of the magnet to the magnetic condition of the MSSR shown a time differential error, thus time can no longer be a constant,
8. Applying "The length of a coil" to the path of the helical vortex shows the helical length of time and speed fail the length of the physical body of the magnet.

The result of the drawing above, and of the images shown, and of the mathematical computations and logical expressions within this document that have been proven so many times in so many different ways leaves the reader in no uncertain terms that the current thinking and philosophy of Euclidian time is flawed, and that the speed of light is only $3 \cdot 10^8 \text{ms}$ when measured in isolation. This brings into question Mr. Albert Einstein's secondary postulate, that of the space-time constant (which is now also flawed); And, when extending the above to encompass other material written by Mr. Einstein, that of the special relativity theory this too becomes wholly questionable; Insofar as to ask the paradoxical question of the distinct relationship between space and time. Give that "space" is a distance, and "time" is a duration result in that any space time event requires a third party that is velocity. Below is an image to



two magnets is a permanent state of repulsion “<|>” Be it North to North or South to South, the repulsion is always present.

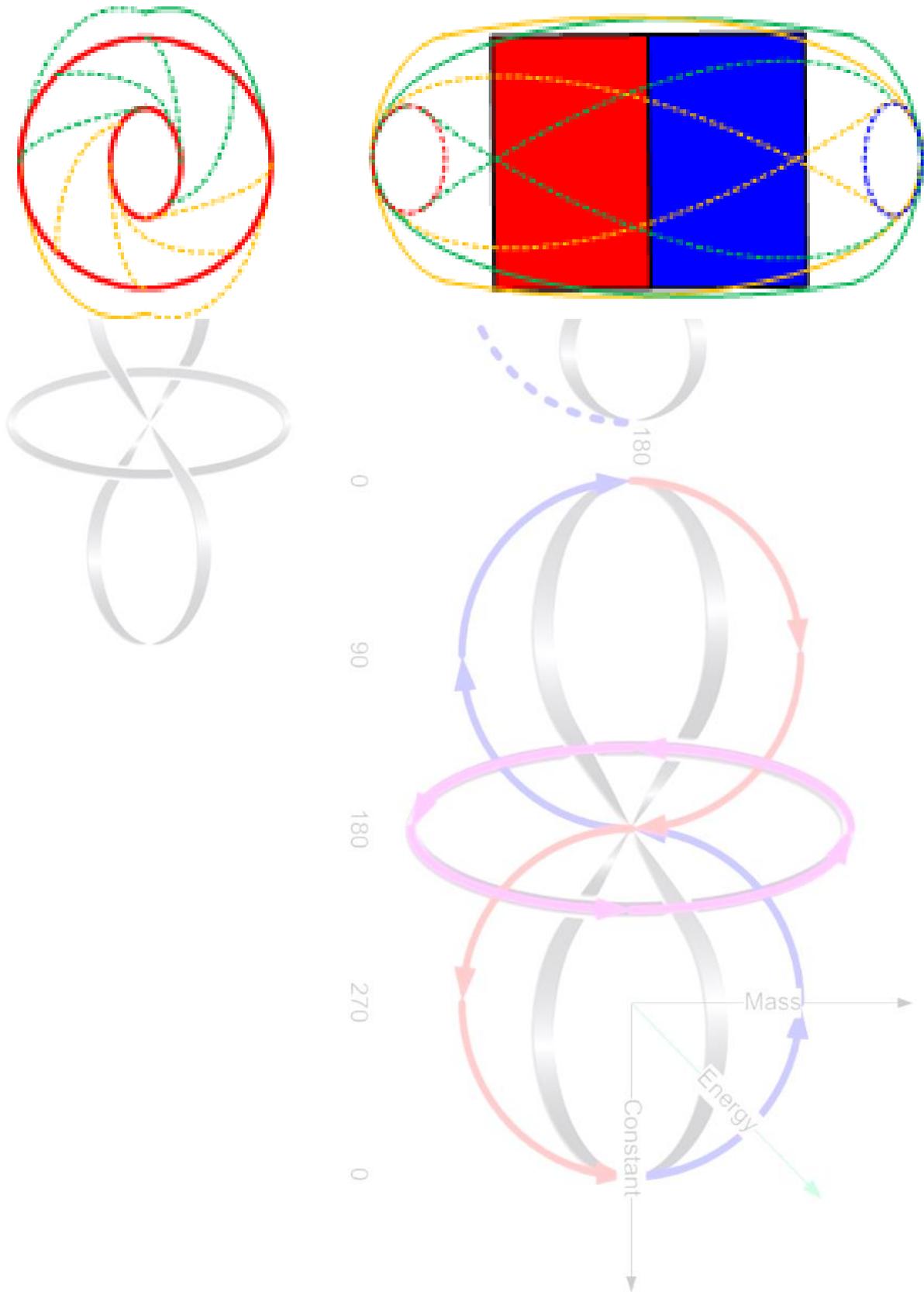
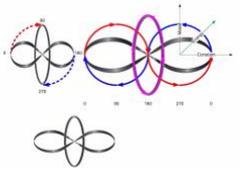
There are many events occurring within this image, and to assist the reader they are listed below:

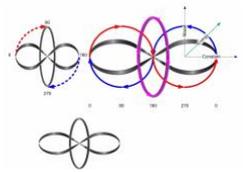


1. Two opposing forces (of magnetism),
2. Magnetism has an “energy” field is proportional to the surface area of the magnetic body,
3. Magnets have a motive force,
4. The space occupied by the magnetic energy is equal within both magnets,
5. The time (distance) within both magnets remains constant,
6. The energy within the magnetic bodies remains constant,
7. The velocity of the inner toroidal fields remains constant,
8. The angular displacement (both vertical and horizontal) remains constant,
9. No physical or meta physical interaction occurs.

If, according to Mr. Albert Einstein and, (both of his postulates), that of general and special relativity theories rely on the constants of time, space and the speed of light. If this were to be the case and all were to remain constant, then it would be impossible for the parallel lines at the convergence point to exist as the parallel lines show a distinct change in the circular constant about the circumference of the magnetic field. To now consider space and time as two directly linked differentials of themselves, or a double differential would suggest that the change in one would result in the change of the other; Thus, as the SPACE between the magnetic fields is evidently COMPRESSED then the result is that TIME must by all logical reason be EXPANDED. This was also demonstrated at HMD Dryad before the Royal Navy who STOLE this technology some 35 years ago.

A simple physical test can be done with a child’s balloon. It is a body of one of its own mass and content occupying its own space and time. When two balloons are compressed together the space is reduced that the size elongates (time changes).





Chapter II
Removing the Mystery

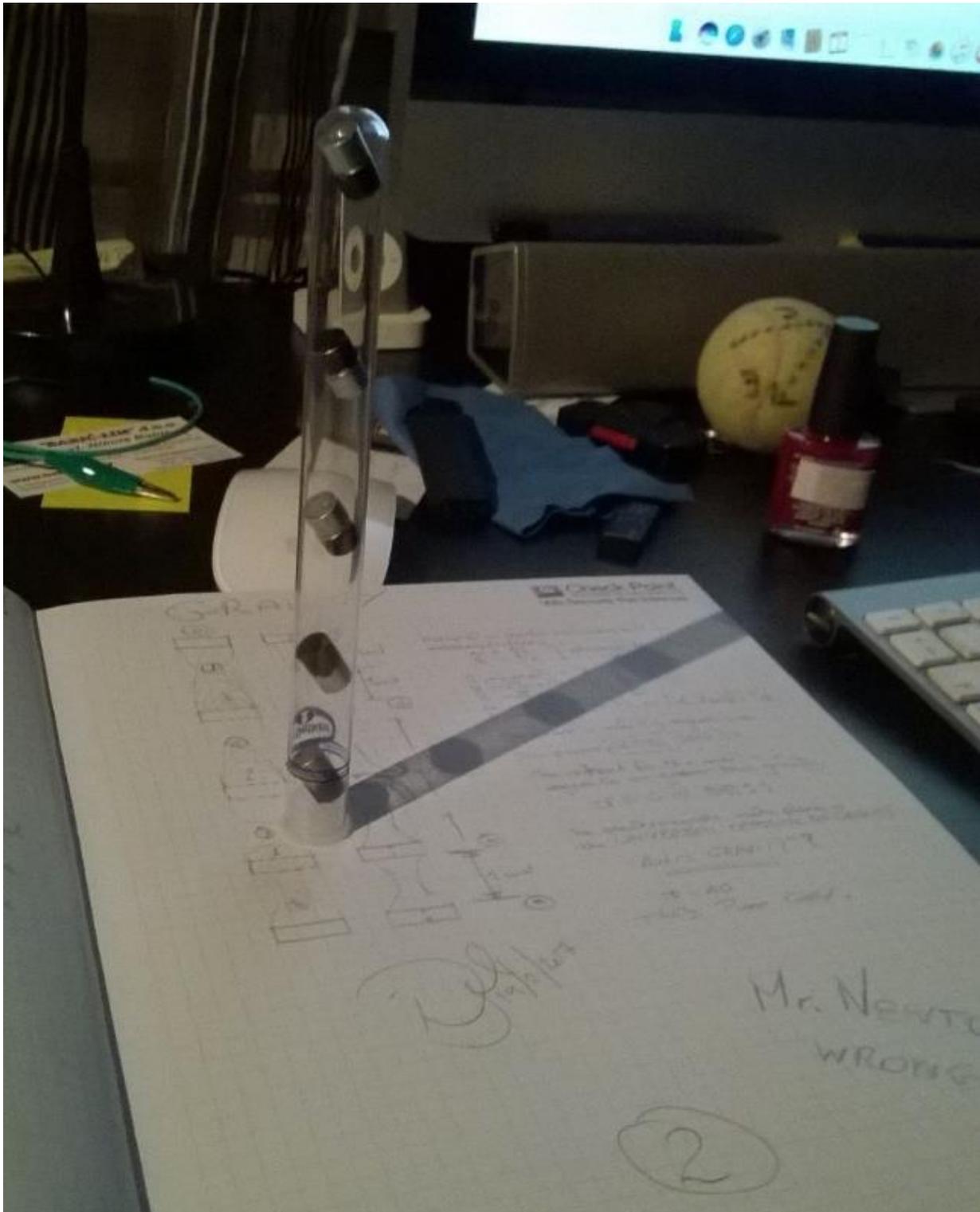
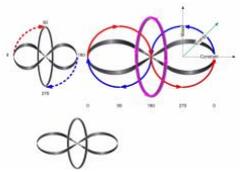
“Having dealt a somewhat lethal blow to many notorious and self-proclaimed scientist of the past, would it not be nice to know the truth”?

The MSSR (or) minimum self-seduction range has been discussed (and) proven; Though the MSSR has, at this time, has only been used to express the magnetic force condition between two or more magnetic bodies. But how does the MSSR affect the way things are done? Obviously, it is somewhat trivial if that force cannot be used to the benefit of others or cannot be used or defined in such a manner to offer a future vision for humanity; And, to that end [...];

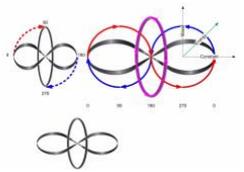
Gravity “A force defined as $F=mg/ma @ 9.81m/s^2$ ”

How can this be so [?]; If two magnets are placed on top of each other as to **form a repulsion**, and gravity applies to both. Yet, while the first magnet may be physically in contact with a non-movable surface, the second magnet is NOT. Utilizing “A” and “B” as the magnetic bodies results in A at $0 = 0$ and B at 0 equals something NOT zero. There is a physical gap between the two magnets, and this gap is the interaction of the MSSR of both magnetic bodies. The question is, if “B” is persistently falling at $9.81m/s^2$ but does not move, then the combined force of MSSR (A) and MSSR (B) is equal to $9.81m/s^2$; If it was any other number then one of two things would occur, (1) there would be no gap between magnet one and magnet two, and (2) Or “B” would have drifted off into space!

The conditions of two opposing MSSR’s cause a visual and perpetual action that is in direct relation to $9.81m/s^2$; but when a THIRD MSSR is introduced “C” the definition of gravity fails itself. If “A” is stationary or in contact with a fixed body, and “B” is in a perpetual state of implied levitation, then “C” must contradict gravity as “B” is not bound by gravity but by the MSSR of “A”, thus the MSSR of “C” is independent of gravity. It cannot be suggested that “B” (on one side of the magnet) gravity applies and on the other side of the magnet, it does not; And to add “D”, “E”, “F” and more, where is gravity [?]; As, as more MRRS’s are added the gap between the MSSR’s increases. If all bodies fall to earth at the same velocity then all gaps must be the same! However, it is evidently clear from the image below that the more MRRS’s added the greater the gap, thus “gravity” (as defined by “Sir Isaac Newton”) is totally incorrect. To clarify, when the “shadow” of the image is viewed the distance between A and B is exactly one of itself, however, the distance between B and C is 1 and 1/5, and between C and D the distance is 1 and 2/5, and so on. **The result is that when two or more MSSR’s are placed into repulsion** the composite energy release is equal to 1.962 m/s; thus 5 sets of MSSR’s is equal to 9.81m/s.



The above image also includes the geometric constant below the magnets themselves, and the written explanation to the right, it is also signed and dated by the author and the originator. The shadow shows the 1.962 m/s increment and the angular disposition is exactly 45 degrees (which validates the angular inclination of the rotational force of the magnetic motive force (as discussed in previous pages). Given the very evident facts of both the MMF and the existence of the MSSR leads to “how to use them together [?]”.

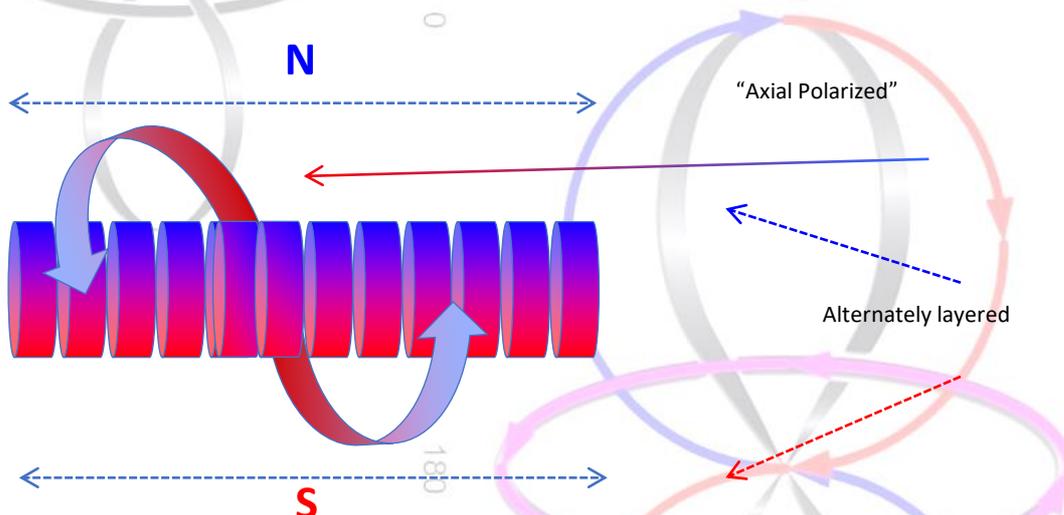


It can be seen that MSSR's are accumulative, they are bound by the Fibonacci sequence and exert a magnetic motive force or 1.962 above 9.81m/s² per MSSR pair. To now extrapolate this obvious condition, it would suggest that if many MRRS's where to be configured in a unique fashion then the MMF would very soon, overcome the total force of the implied gravity.

Defining a list of parts (or condition's) suggests:

1. Many MSSR's (in repulsion)
2. The repulsion is in compression forming a SIP
3. Many SIP's configured at the angular disposition of the MMF (45 Degrees)
4. The geometric condition must be infinitive (a circle)

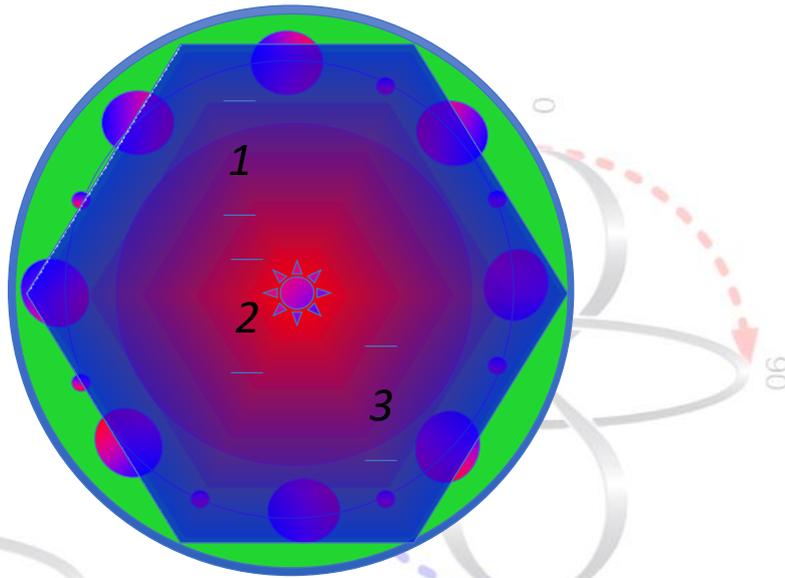
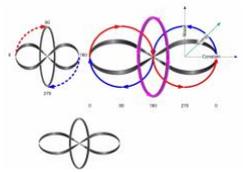
Utilizing the listed properties above, SIP conduction and induction creates a condition known as a magneto P.I.N. (point of infinite neutrality). When configured correctly the magnetic field can be made to self-invert or "induce" resulting in the self-magnification by **induced conduction**, as shown below.



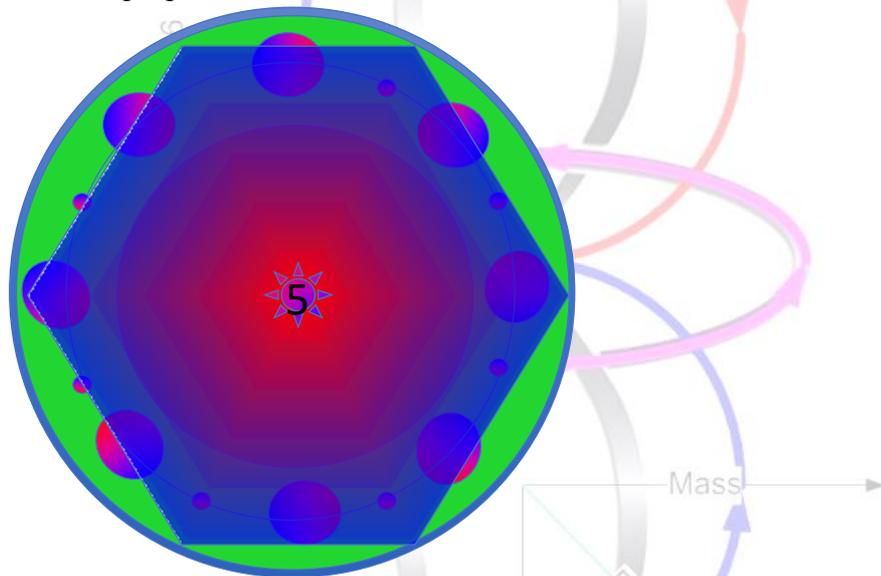
The above is a two-dimensional representation of a three-dimensional state, where (in conjunction with the many previous images) results in the formation of a torus. Applying the "magnetic accumulation constant" of the SIP energy field to the torus function of:

$$((x^{n!-1}) * (y^{n!-1}) * (z^{n!-1})) = (\infty * \infty * \infty)$$

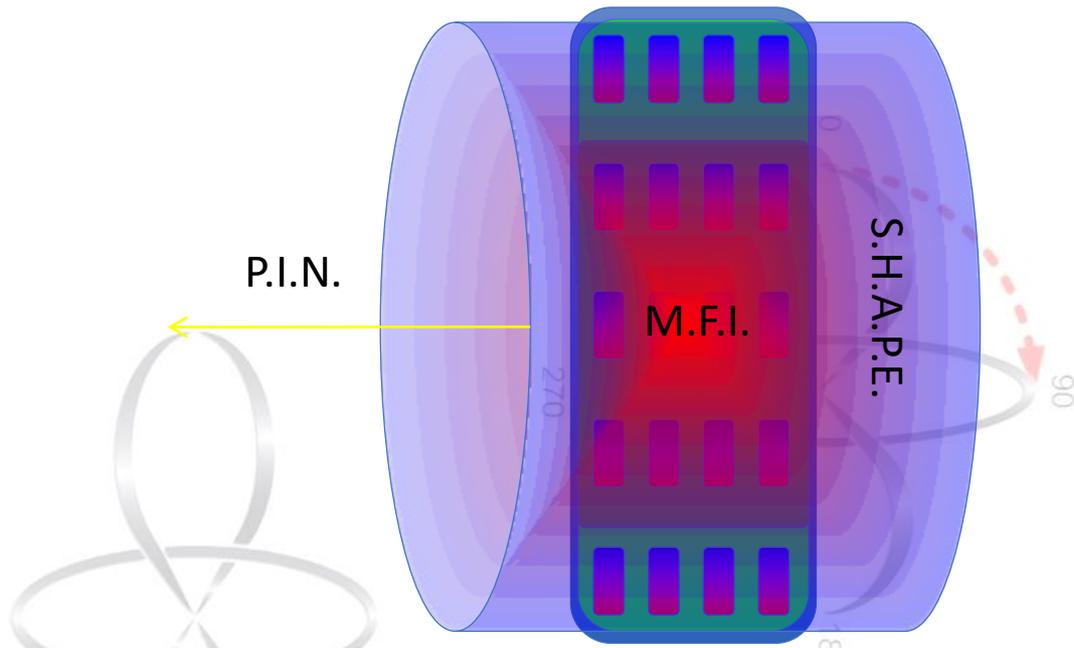
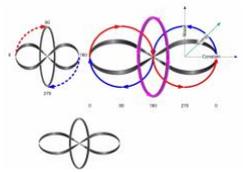
The result is massive amplification to the MMF via the SIP of the MSSR's. Addressing the image above as a single object or "STACK" (of magnets). By geometrically placing the "Stacks" around a common "zero" "z" axis creates an [ADDITIONAL] induction field about the common axis of zero further amplifying the MMF within the SIP of the MSSR above its original field of **ONE** (unit of energy per magnetic field), resulting in the internal state of magnetic rotation creating multiple "self" amplifications to each field and to the adjacent field all being now TRAPPED or "BOUND" within a non-pervious aluminum shield known as an Aluminum LENS. Utilizing the MMF and the unique alignment of a "45 Degree" angular incidence forces a compound function of "BEAM SHAPEING" or magnetic "Beam Forming" where the INVERSION is further constrained within the geometric confines of the **Aluminum Torus** condition resulting in "Elliptical" field compression of opposing fields, that of the opposing neighbors.



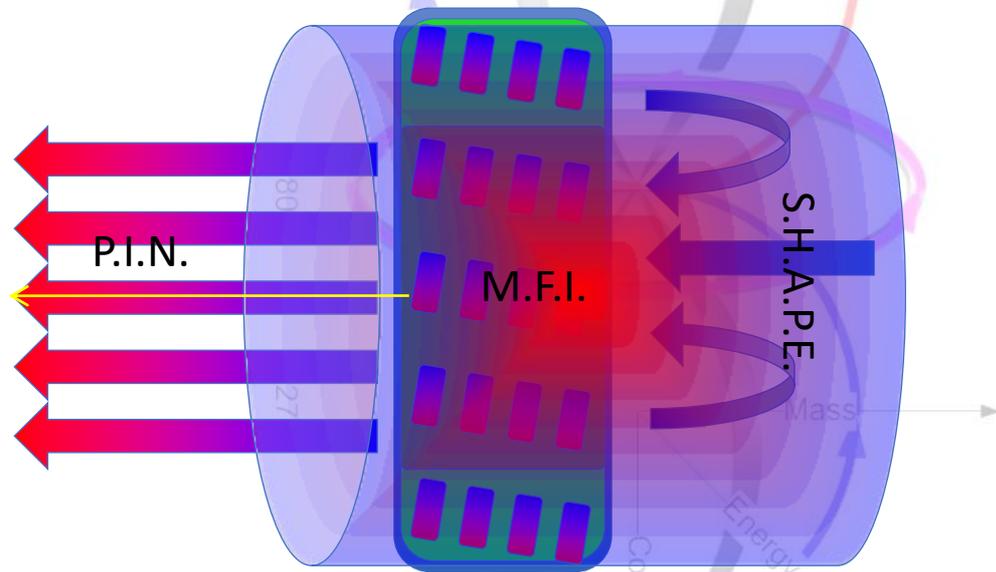
“Folding” the outer magnet field in onto itself (1), along with the inner magnet field (3) creates the “P.I.N.” condition at the nominal “zero” point as shown at the center of (2). Having “established” the “P.I.N.” or “Magnetic Field Induction *zone*” or M.F.I. results in the “S.H.A.P.E.” function occurring, that of a “Spherically Harmonized Aperture (of) Phased Energy”, Phase being the “polar” displacement of the outer beam. Within the convergence zone of the M.F.I., the S.H.A.P.E. forms a cavity of highly energized magnetic energy that holds an “attraction” charge of immense proportions in both the POSITIVE and NEGATIVE fields.



At the “Sub-ATOMIC” level, the magnetic ION fields of both POSITIVE and NEGATIVE states migrate to the M.F.I. zone where the “sub-atomic” bonding that occurs is akin to the of VELCRO. To consider the “free space” and not the magnetic element of the condition as the “Spiked” part of VELCRO and the “M.F.I. ~ S.H.A.P.E.” as the “Hairy” part; [BOTH] stick together. To now consider the “y” axis view or “side-on” view of a “M.F.I. S.H.A.P.E.’d P.I.N” (it) would look like:

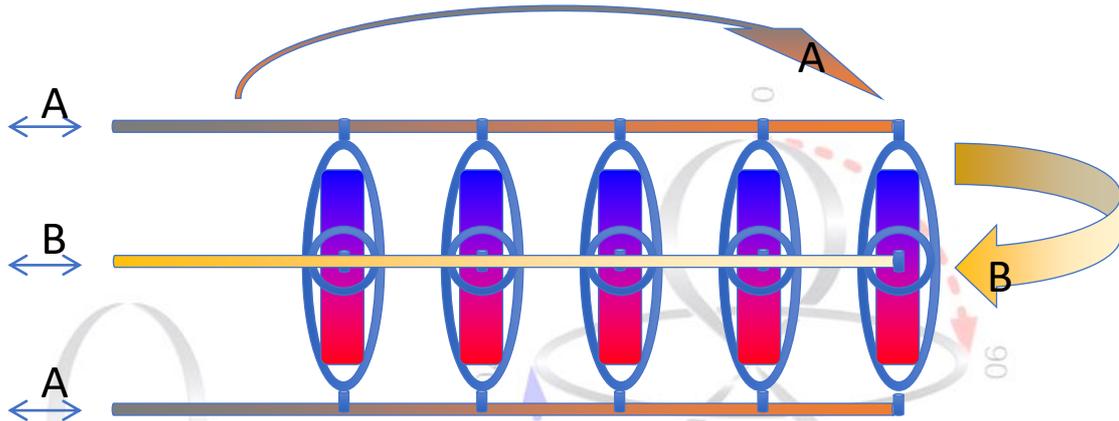
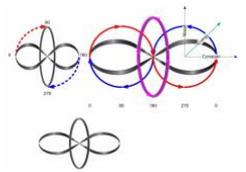


Viewing the P.I.N. as a longitudinal “infinite” condition, that is infinitely “narrow”, (down to the “sub-atomic” level), and the magnetic force of the P.I.N. act’s with the same properties of VELCRO, (to hold in place) or “Stick together” at the sub-atomic level; Back to Sir Isaac Newton and the “Force of Motion” (“*Each force acts in an equal and opposite direction*”), where shown above, the “STACKED” magnets are perpendicular or (90 Degrees) to the plane of polarization creating a “Standing Motionless Wave” about itself; thus ENFORCING Sir Isaac Newton’s “Motion Law’s”. Therefore, to “MOVE” any part of the GEOMERTRY would “induce” a movement or “MOTION”, as shown:



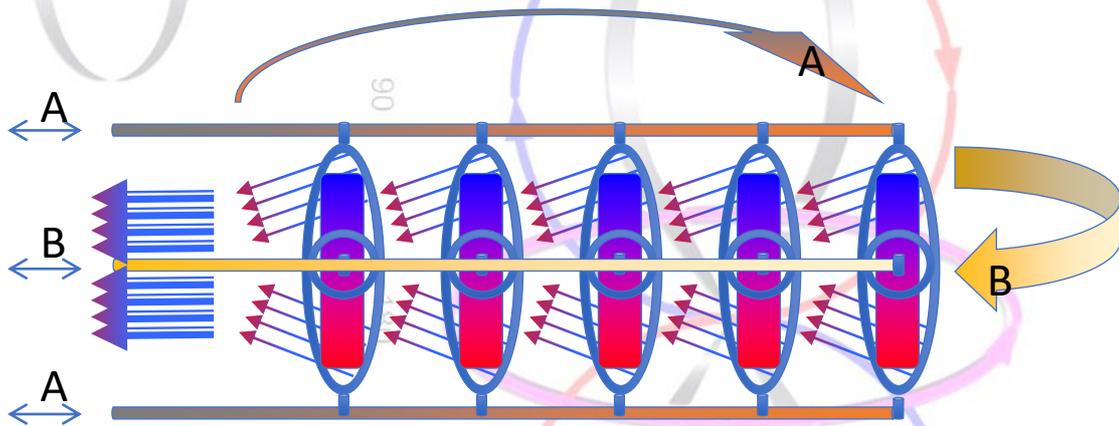
The mechanism for “Auto Geometry Change” (A.G.C) is achieved by utilizing a “GIMBLE”; where a “GIMBLE” creates infinite movement around a common combined access of “zero” as shown:

The power of ZERO

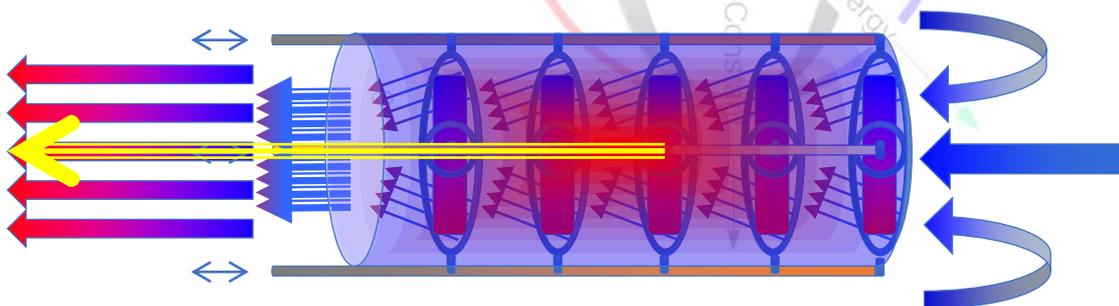


By applying a Unidirectional opposing force, via a GIMBLE, the plane of axis can be rotated in [ANY] axis, to an infinite degree. When applied in UNISON, that of A.G.C. of the magnetically generated P.I.N. the result is “Geometry Change” or (M)otion of the P.I.N.

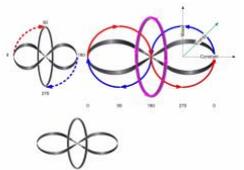
$$GC = (M_{(P.I.N.)})^{n-1} * (Stacks) * (360/Stacks) * (SIP's * 2):$$



The result is THRUST or MOTION in [ANY] direction, no moving parts, nothing to break, [ALL] achieved against the laws of thermodynamics and entropy, against $e=mc^2$, and against $F=mg/ma @ 9.81m/s^2$; the generated thrust can now be further accelerated by the use of a TOURS PUMP now shown in situ as part of a complete construction below:



To understand the “Quantum Mechanics” at a sub atomic level, is to understand the P.I.N.



The P.I.N. (*at the atomic level*), and also (*at the molecular level*) are “SOLID” objects, all bound by a magnetic field which forms a fluidic solid, the P.I.N. is held in place by the immense constraint of the super imposed geometric condition, that of a Torus function:

$$((x^i) * (y^i) * (z^i))$$

The “flow” or “Rotational” Axis of the P.I.N. has been “Induced” directly and proportionally to the Universal magnetic field; where the result is “DRIVE”, or “Motion” or “Thrust” in [ANY] direction, and at [ANY] speed, where the relation to speed is that of the currently bound constant of $3 * 10^8$ Meters per second results in an “engine” with a potential velocity that will exceed $3 * 10^8$ m/s which direct contradiction to the definition of a magnetic field, a direct contradiction to the fundamentals of $E=mc^2$, and a **MATHEMATICALLY PROVEN CONTRADICTION** to $f=mg$, that of the force of gravity.

Given the massively “SIMPLIFIED” construct, (*a gimbal, a tube and some magnets*), allows for fabrication at any scale, from a handheld device creating “NEUTRAL” weight (*A smart phone that weights nothing*), to passenger transport mechanisms to ocean transport vessels. The “Magneto-Drive” is a one size that fits all. Given the fact the motion or thrust generated can be generated in [any] plane of axis, it WILL create lift, as well as thrust, **so what is wheel or wing for?** Letting the truth be known; But it is no good showing the “truth” if those who read the truth then go ahead contest it [?]; surely by observation and fact; And proof, then the proof becomes evident itself. It is Occam’s razor at its very best where it is said “**simpler solutions are more likely to be correct than complex ones**”.

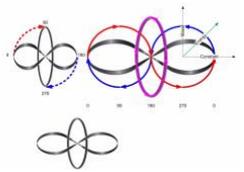
The shape of things to come:

Defining the customary shape of most magnets (if not all) defines an object that is equal within its shape. That being a cylinder, a square a sphere or even a curved magnet, it will still be universally equal in the parallel of the curve. Creating magnets in this fashion leads to the extinction of ability. A square is a square, and a cylinder is a cylinder irrespective of its size. Though to be a little more creative will allow so much more; but [...] in order to be creative, the reader must understand the fundamentals of a magnet; And, to ease the reader into conceptual magnetology it is necessary (firstly) to set several common standards:

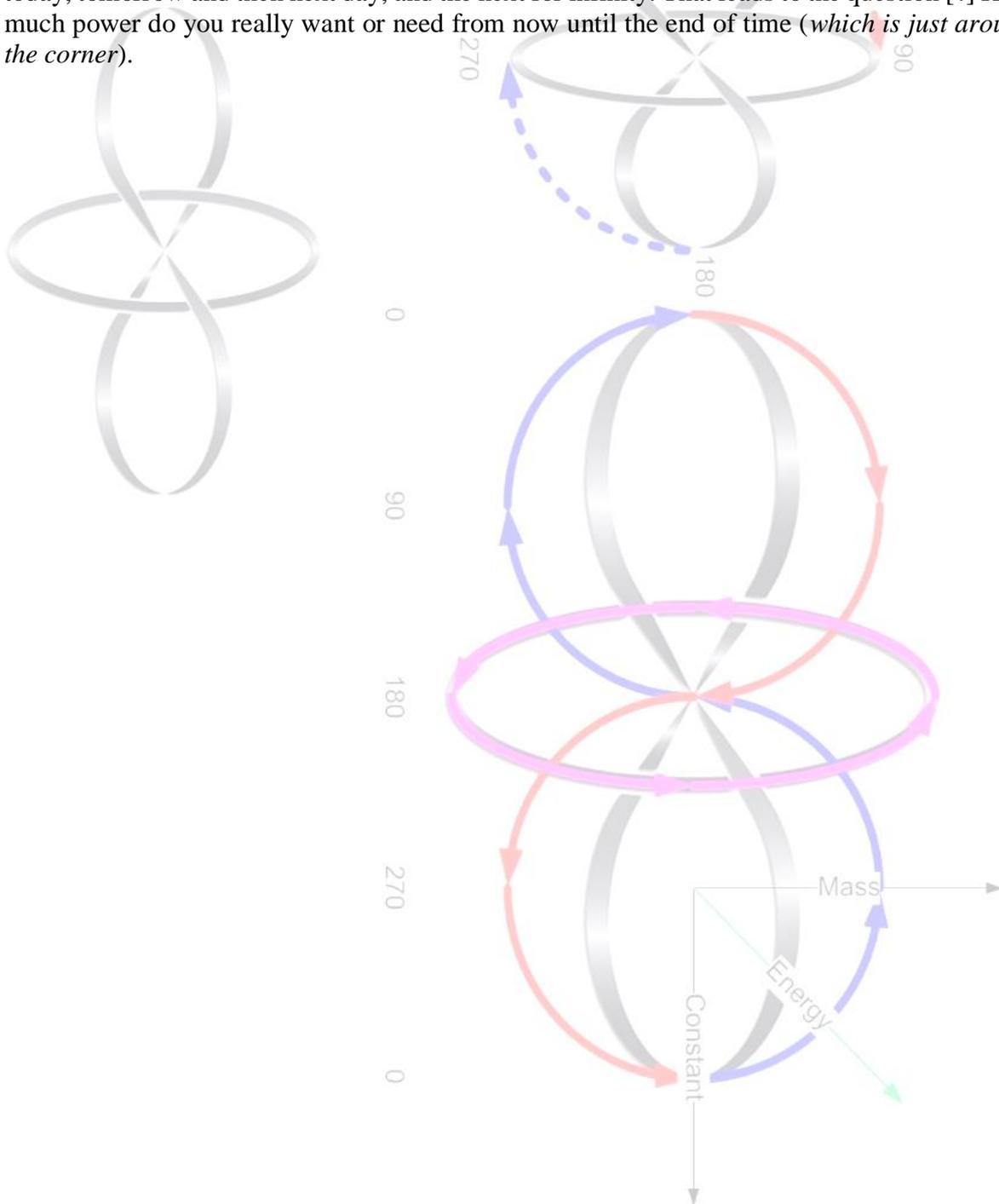
1. Magnets have two poles (North and South)
2. Magnets have many intrinsic fields that are NOT north or south
3. Magnets have a motive force
4. Magnets have a split differential of energy (roughly 3/5 and 2/5 in favor of south)
5. Magnets are bound by the MSSR of itself and any other co located magnetic body
6. Magnets defy thermodynamics (and that is the cool one)

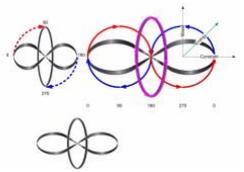
Given the six common standards it can be seen at no time was the shape of the magnet brought in to question, that is because the fundamental shapes used today to not in any way optimize the ability, form and or function of a magnet. This can be easily resolved with a simple condition; If a magnet is uniform in construction then so is its magnetic field (from and function), but to apply infinity to a magnet so much more can be done.

If a magnet were to be constructed as a cone, (in fact two cones of opposing condition’s); One constructed with North at the apex and one constructed with South at the apex. Applying magneto infinity to either magnetic body offers to the reader a visual approach to infinity. If the base of the magnet were to be given a value of 100 units of something and it persists for



infinity, then the apex being infinity as a point results in 100 times infinity at the apex! To now have TWO cones point each other, ALL of the magnetic inertia energy must transverse the apex of each magnetic body, and when you “cramp” 100 times infinity and invite the MSSR of 100 times infinity to merge, you get a SPARK. Yes, you did read correctly a SPARK, and when Pachens’ law is applied to that SPART and GAP it results in 3.4 Mega Volts per meter of spark. Though, if the spark was a mere 2 mm, or 10mm or 10cm, the amount of energy being released would greater than every atomic device ever built or detonated along with every ton of hydrocarbon ever burnt, as this spark and this 3.4 Mega volts will be 3.4 Mega volts now, today, tomorrow and then next day, and the next for infinity. That leads to the question [?] How much power do you really want or need from now until the end of time (*which is just around the corner*).





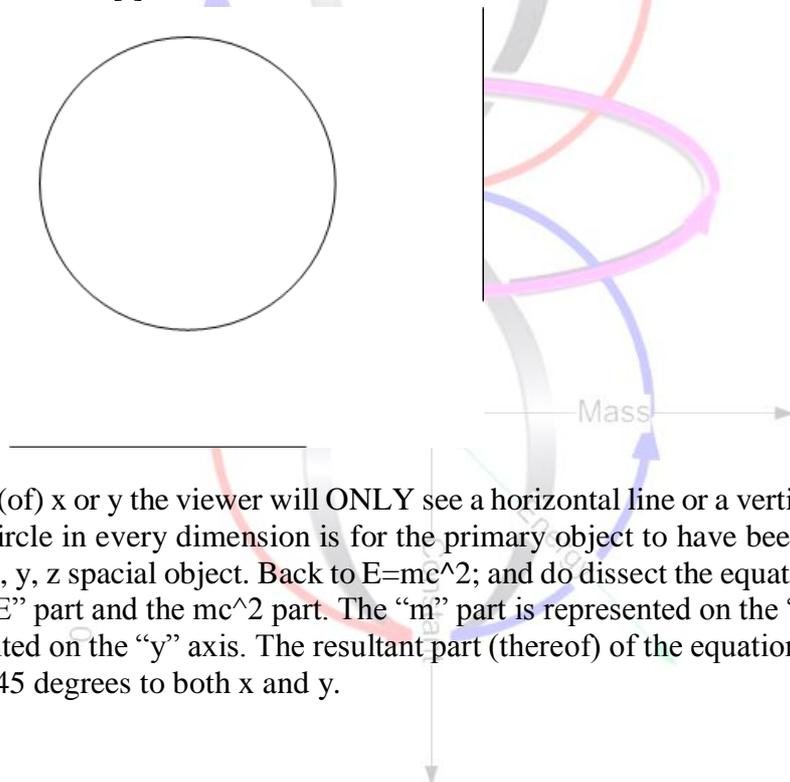
Once, the ability of a magnet is understood, so many things become available to humanity; many things have been shown and proven with the evidence clearly displayed. It now becomes difficult for “others” to continue to deny the very facts embedded within this document.

Many have asked, the same or similar questions’ to “How did all of this come about [?]”; Here, I now try to offer an answer and a solution. Not wanting to be the person to “run the metaphorical knife” through someone’s back, that being Mr. Albert Einstein, that being said, and letting the truth be known, this may come as a shock to many readers.

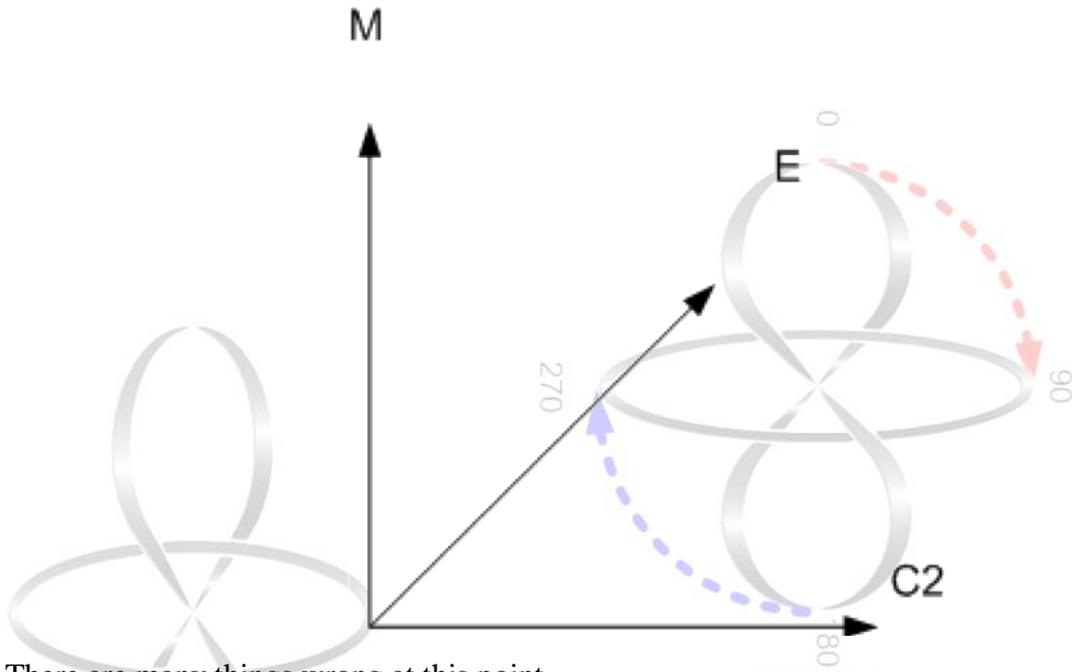
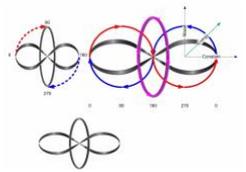
Bertie, (Albert Einstein), was assessed to be one of the most brilliant minds on this planet. Within his brilliance he derived an equation that has formed the basis of everything that humanity does today; That being, $E=mc^2$ [!], Which when translated to the layman’s terms results in the verbiage of (E)nergy is (=) to (m)ass times (c)onstant squared. Where the result of the energy output is the combination of the amount of mass and two times the constant. That constant is $3 \cdot 10^8 \text{m/s}$. (though as shown earlier, this constant cannot be constant, thus the equation fails itself). The equation fails in so many ways; Alas everyone can’t be that stupid [!]. It reminds me of the philosophical comment to fooling people:

“You can fool all of the people some of the time, and some of the people all of the time, but you cannot fool all of the people all of the time”.

Where’s the error [?] The error comes in the form of a miss-representation of reality. You, like myself reside in a three-dimensional space along the axes of x, y, and z (or up and down, left and right, and in and out), and of course the viewpoint. To simplify this would be to review a circle; which is a two-dimensional object [x and y]; but, when viewed from either side or from top or bottom, all that is seen is a line [!]:



Depending on the viewpoint, (of) x or y the viewer will ONLY see a horizontal line or a vertical line. The only way to see a circle in every dimension is for the primary object to have been a sphere, where a sphere is an x, y, z spacial object. Back to $E=mc^2$; and do dissect the equation into two parts results in the “E” part and the mc^2 part. The “m” part is represented on the “x” axis and the “ c^2 ” is represented on the “y” axis. The resultant part (thereof) of the equation is the “E” which is depicted as 45 degrees to both x and y.

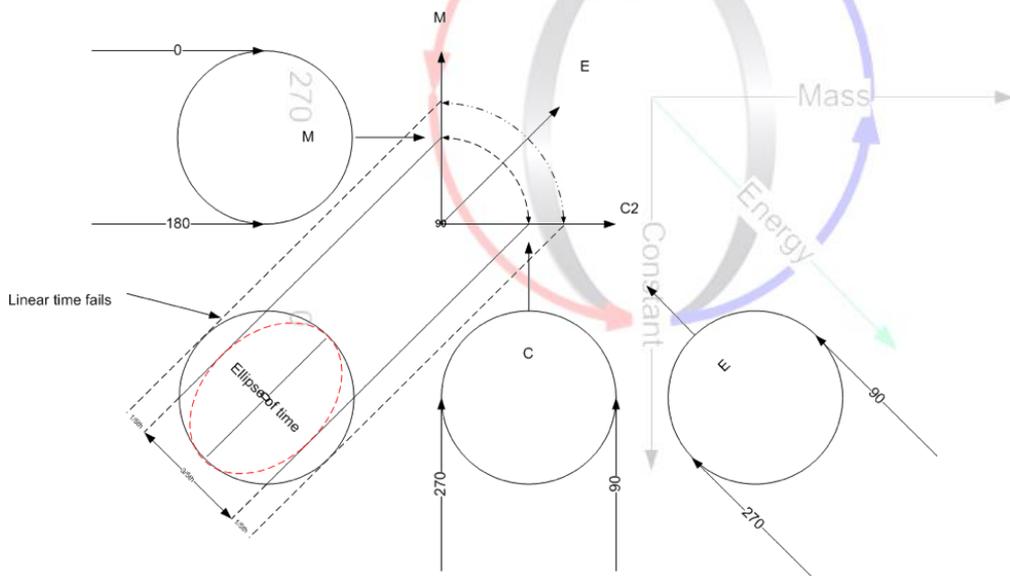


There are many things wrong at this point.

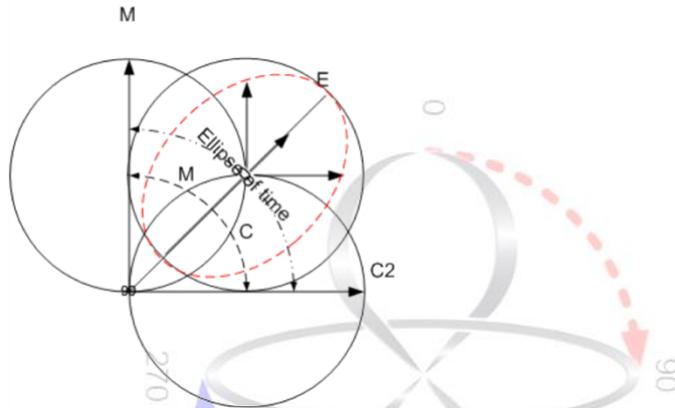
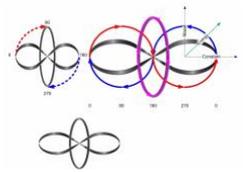
1. This is a composite of THREE one dimensional accumulative states being used within a two-dimensional representation attempting to depict a three-dimensional condition[!]
2. The origin of zero is assumed to be at the bottom of “m” and to the left of “c2”
3. “E” cannot be at 45 degree’s due to the square function of “c”
4. M must be a circle or a sphere
5. C must also be a circle or a sphere.

The result of applying LOGIC and geometrical (real world) conditions to the equation results in:

The image transposes the one-dimensional lines of $E=mc^2$ to the two-dimensional condition for balancing the equation. The interesting point to note is the position of zero, as when zero of [NO Energy] and zero of [NO mass] and zero of [NO constant] are applied equally, the visual result is shocking:

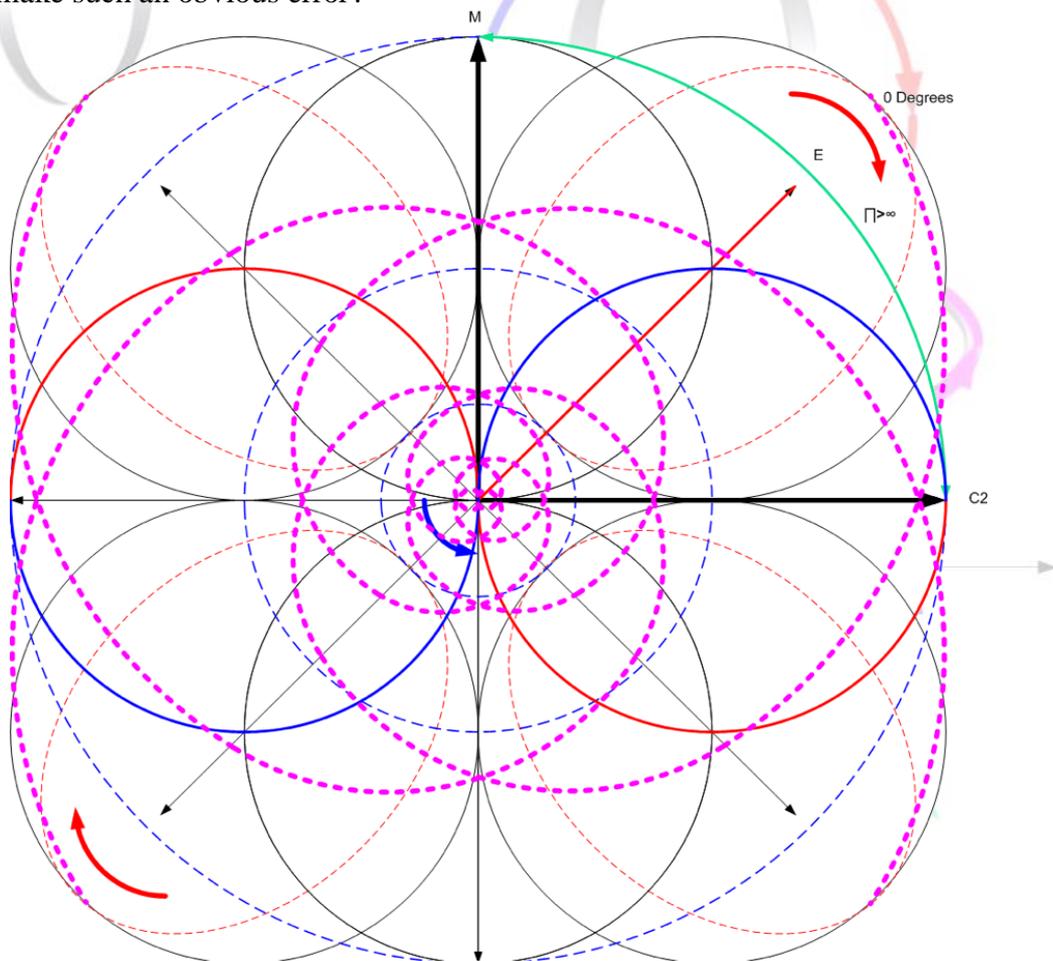


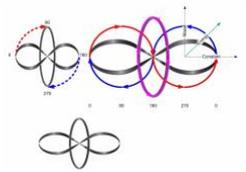
The power of ZERO



It can be seen from the above image that zero is **no longer** located at the **lower left** position, rather, it is now positioned correctly within its spacial condition, showing the **true** value of E, M and C to be much smaller than originally displayed;

It can be seen that the complete construct of the equation resides in an upper quadrant and not as a hole (encompassing) object. In order for the equation to be “universal” it would also have to incorporate the other three quadrants; Alas, this will only cover the front view thus an additional four quadrants at the rear of the image would also need to be calculated. The result is that $e=mc^2$ is actually $1/8^{\text{th}}$ of an equation, and why would a man who was so clearly brilliant make such an obvious error?





In order to disprove the above image, the reader is required to “prove” the natural value of zero, where zero is a non-zero-accumulation, and not a null or a nothing; this can be expressed as $10/10 = 1$, $5/5 = 1$, $1/1=1$ and $0/0=$ (NOT zero) but a “non-zero-accumulation” resulting in that the harder the reader tries to prove the non-existence of zero the more the existence of zero becomes resulting in, (in every instance) that pi will always be greater than infinity. $E=mc^2$ defines an infinity and a magnet defines the unconditional state of pi in relation to the now clearly wrong condition of infinity. $E=mc^2$ is bound by thermodynamics; Therefore, to subdivide the equation back to E, M and C results firstly, in (M)ass; Where a stationary body of (M)ass has no energy; this cannot be valid as two or more stationary magnets attract or repel which is a state of transposed stationary energy contrary to thermodynamics; And, (C)onstant² has been clearly proven NOT to be constant at all. Thus, the liberation of (E)nergy within the equation is woefully incorrect.

“You can fool all of the people some of the time, and some of the people all of the time, but you cannot fool all of the people all of the time”.

Secondly, attaching the word “electro” to a magnet to form electromagnet is a 100% falsity. There is NO electricity in a magnet, NON-whatsoever; If electricity were to be present in a magnet, you would get some form of electric shock just by picking one up, and, or spinning around with a magnet in your hand would become a shocking experience. But, as this is not the case, the “electro” is a purely manmade concept to force an attachment or direct linked association of electricity to the body of a magnet. It is done so purely out of commercial ignorance and greed. Yes, if you take many magnets and bind them within a copper coil (magneto lens) and move then is a regular pattern opposing the geometry of the magnetic field it will force ionic exchange within the copper coil. But it is a FORCED condition and not a natural state.

NOT FINISHED !!!

