

THE UNIVERSAL RELATIVITY THEOREM
"Infinity is part of the "trinity" of (ME [and] I)."
 $\Pi > \infty$

The Universal Relativity Theorem is, as the name suggests, a theorem that encompasses everything in the universe, it's constructs and their individual relationships everywhere.

The theorem is very simple in its form, but it is very difficult to fathom, because it requires the reader to utilize personal logic and relinquish everything they have been taught and, or, believe in, from the very first day of their life on this planet.

To accept the theory is a matter of personal belief, either the reader accepts it, or they do not; In either case, it does not change anything in the Universe. The Universe remains to be what it is, regardless what anyone may, or may not believe in.

Postulate: Only Unity Exists.

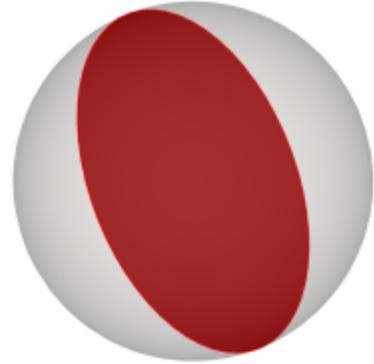
To depict "Unity", it can be graphically represented a sphere, not necessarily a perfect sphere, but a sphere. The logical reasoning for using a sphere is that; everything is made up of spheres, from smaller than the smallest particle to larger than the largest planet in the Universe, and everything in between, everything smaller and larger; That is Unity.



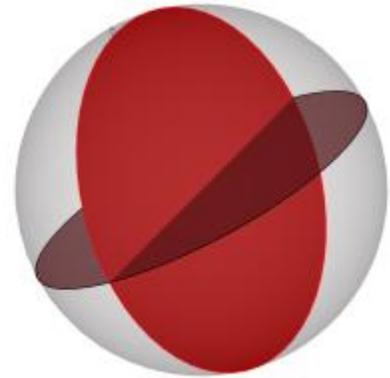
1st Order Derivatives and Composites

Having defined Unity, it is now possible to look into its first order derivatives and composites. The common factor for all first order derivatives and composites are; they are not “**man-made**”, but already exist Universally in nature.

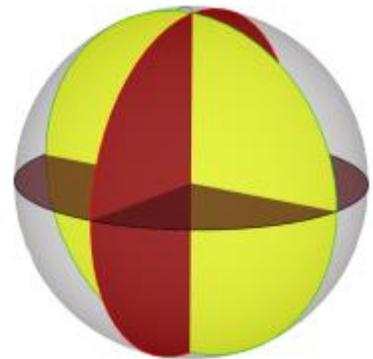
Electro Magnetism (EM): The forces that act upon [ALL] Matter (M) and Space (S). EM is defined as the (red) plane within the sphere, and it has two poles, a Positive and a Negative pole. The Positive and Negative poles are colloquially called North and South. The ratio between EM+ and EM- is exactly 1:1.2 in favor of EM-¹



Inertia (I): The release of Energy (E) contained within the EM field. I, is a (red) plane in the sphere that is 90° to EM's poles and the inertia plane sits between¹ EM+ and EM-. An analogy would be amplitude modulation (AM) and can be viewed as either the EM field and its resonance, or as a Sine wave vs. EM field. As one increases the other decreases.

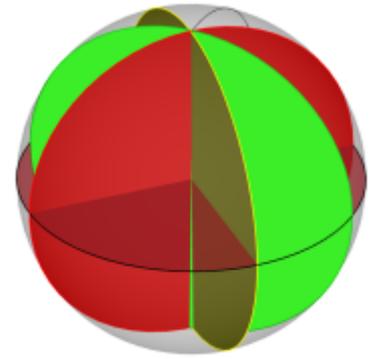


Matter (M): The Universal fabric of which “**everything**” is made of. M is a (yellow) plane in the sphere that is 90° to EM.

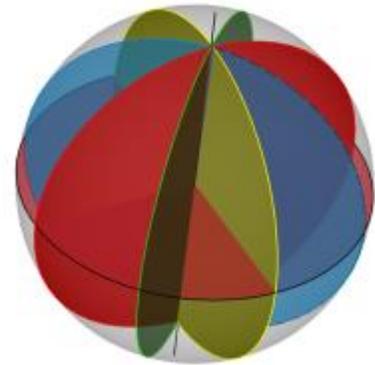


¹The ratio between EM+ and EM- is exactly 1:1.2 in favor of EM-. Therefore, the exact resulting sphere is in fact Ovoid shaped, or colloquially "egg-shaped", but for sake of simplicity a perfect sphere is used.

Energy (E): The liberation of a force from the composite of M and I. E is a (green) plane in the sphere that is 45° to EM and 45° to M, and tangential to I.



Space (S); The place where M resides. S is a (blue) plane in the sphere that is 45° to EM and 45° to M and tangential to I.

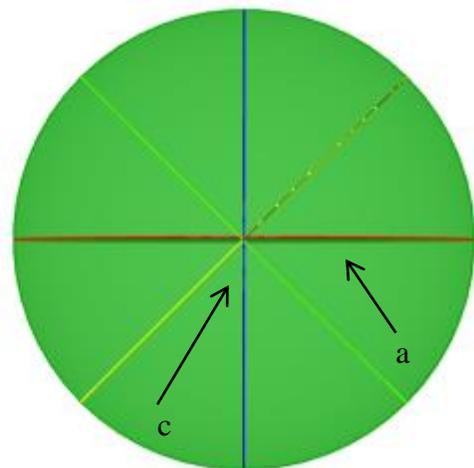


The Division of Everything

Having Unity defined, the logical deduction of the coherence between 1st order derivatives and composites can be deduced.

To the right is a unity model, tilted, so that E (green) becomes a full circle, and I (red) becomes perpendicular to EM (blue); The model resembles a two-dimensional coordinate system.

In the top half, M (green) is -45° to EM and S (yellow) is 45° to EM. In the bottom half M is 45° to EM and S is -45° to EM.



Placing two points c and a; c becomes the center or zero, and a becomes infinity; Therefore:

$$\text{If } a = \infty \text{ then } (c - a) = \infty \therefore (-a + a) = 2\infty \therefore \infty = 2\infty \therefore 2[\infty, \infty, \infty] \text{ of } 0$$

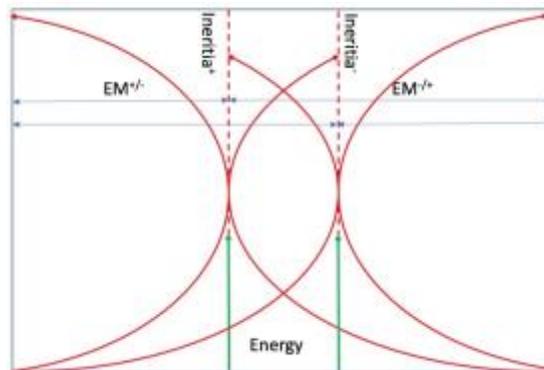
$4/3\pi*r^3$ is a volumetric condition set in a two-dimensional world, whereas $[x, y, z]$ is a zero to max volume in a three-dimensional world. Now to apply the volumetric formula for a sphere $4/3\pi*r^3$ to $2[\infty, \infty, \infty]$. From any $[0, 0, 0]$ to any $[x, y, z]$ creates a volume. In a three-dimensional world zero is always zero on all axis. Therefore $4/3$ is the $1/3$ greater than the cube of a linear state and π becomes multiple of the radial state of r , which is then cubed for the xyz axis's from 0 to x, y, z

$$\therefore \pi > \infty \text{ (by a factor of one third (1/3))}$$

When two compressive forces (EM+) and (EM-) are in a permanent state of conflict, the energy resides between the conflict; Therefore, EM forces liberate energy, and the energy resides within I.

$$\therefore E=EM/I$$

The division between $EM^{(+/-)}/I$, is the spacial separation of the two EM forces, which is a representation of EM+ to EM- via zero.



To consider all matter (M); All matter is made up of itself and space, even to the point of the smallest atom, the content of that atom is matter and space. The electron or electrons that form the orbit of the atom have a distance, therefore space is always adjacent to matter.

" $E=EM/I$ " is a polar equation, but the encompassing actions of EM/I are energy. M comes from the form of EM, be it plus or minus, space comes from matter itself, therefore space and matter are sub-parts of EM.

The only plane that is truly unique to itself is I, it is one of one, whereas EM is two of one (+/-). It can be said that "I", has three states, a negative kinetic push, or a positive kinetic push, and (or) a combined (+/-) pull. Each of the "I" states rely on the combination of two EM states. The result of the conditions of EM and I, is the creation of M, and with M comes space S, with S, M, I and EM (+/-) comes energy E, therefore $E=EM/I$.

Encompassing S, M with EM and I

To formulate an equation that encompasses S, M with EM and I where the product output is E, results in $E=(EM+)/I(\text{of } (S, M) \text{ of } (I/EM-))$. That is a compressive equation resulting in both ends being removed for balance using classical mathematics where $EM+ + EM- = 0$. That leaves $EM(I) = SME$ which is a Spatial State. To now extract power via energy E, results in that Space*Matter/Magnetic Energy and Inertia equals energy E:

$$SM/MI=E$$

The "electro" part E of EM is a manmade condition derived from M, it is a resultant part, not a founding part. Changing EM to ME (Magnetic Energy), results in the product output of ME and I resulting in EE of I, $EE=I$ (smaller still). It is an Energy equation, but not a polar equation.

$$M = (EE/EM)/I$$

$$S = (EM/I) * M$$

The result is that Inertia (I) combined with Magnetic Energy (Me results in Matter (M) which is Space (S) itself.

$$I*ME=S\&M$$

Everything always comes back to the same very small equations, they all have to balance or else the universe cannot exist. An analogy would be Pythagoras theorem of $a^2+b^2=c^2$ that can be swapped around in all their planes, each giving the common output of the missing part of the equation.

Therefore, applying the same to ME or (Me) and I as one side and S&M as the other side, the combination will always release Energy (E). To create the "brevity" in the code (equation) the result is $E=ME/I$. $E=ME/I$ is the "division" of "everything" matter and space are RESULTS of ME/I, matter and space are composite energy states, thus S&M is a result of ME/I and as ME is Magnetic Energy of (Me) that result is $ME/I=S\&M$ and S&M is E! Therefore, to remove S&M and replace with E results in $E=ME/I$ a complete circle within the equation.

Compressing “space” in order to move forward

ME of I of S&M is K.E.

To understand the above:

ME = Magnetic Energy

I = Inertia

(of) is part thereof

S = Space

M = Matter

KE is Kinetic Energy.

A body consists of Matter and Space, and when the body is in motion, however so small or large, carries within its body Kinetic Energy KE. This can be from an egg to an apple, to house-brick to a car to a human, and finally to a whole galaxy within the space of a Universe.

All moving bodies will release stored kinetic energy when the body of inertia or mass (of one direction) is modified. This can be example as two balls on a pool table, when rolled towards each other, each have their own mass and, inertia and kinetic energy, when they come into contact, the combined mass and inertia transfers part thereof of the internal kinetic energy to the combined collision i.e. the balls go off at a tangent to the collision. The tangent is the release of the stored kinetic energy.

Therefore, Kinetic Energy (KE) is every-where; It is in all matter and is a result of the movement of inertia plane (I) in a given direction, (from zero to infinity) $[0,0,0] \sim [+\infty, +\infty, +\infty]$ or 0 to ∞ . The release of KE is a result of the change of state of the plane of inertia. A perfect replication of the transfer of kinetic energy within a common inertia plane is a device known as the Newton’s Cradle.



To view the above image, the two balls to the right have (2) units of mass and a stored kinetic energy of (3) units (in motion or (space)). The three balls at rest have a mass of (3) of (0) kinetic energy. Then the two balls collide with the three stationary balls the kinetic energy is transferred with a result of 3 balls having a kinetic energy of (2). To view the same as an opposing magnetic condition, the result is 2/5 and 3/5 of itself. The kinetic energy is transferred between matter.

Therefore, the combination of (space and matter) on a given plane of inertia in motion produces the mass of stored kinetic energy. By moving the space between the mass of (S&M) via the IP results in the transfer of KE to another body of (S&M).

Therefore $S\&M * IP = KE$; $KE + IP = \text{Energy}$.

To simplify, Kinetic Energy plus direction equals energy; to change the direction or stop the direction will cause the Kinetic Energy to be transferred to another form of mass storage, (another body of (Space and Matter)). The action is universal and bi-directional in any plane throughout the universe.

To reiterate:

Me = Magnetic energy; I = Inertia (of) is, part thereof, S = Space, M = Matter, KE is Kinetic Energy. [and] $E=EM/I$ [and] $[EMI=S\&M]$ results in the universal Unity theory of the transfer of energy via the compressive electromagnetic forces applied to an inertia state contained with a body of matter and it occupying space.

Energy (KE) = $S\&M * IP$

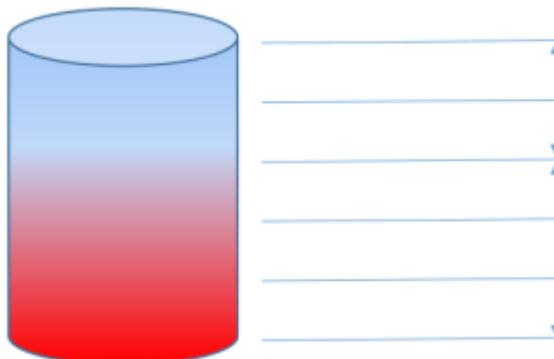
S&M are a result of I and Me, and KE is a result of Me and I; removing the result parts renders $E=Me/I$. The perfect power equation.

Magnet Basics

The magnetic poles Positive and Negative, are colloquially called North and South.

Positive and Negative suggest half and half or fifty percent to the Positive polar field and fifty percent to Negative polar field. Alas, the polar fields of a magnet are not equal as in 50/50 %; they are in a permanent state of imbalance (or) unequal, and is why two magnets want to stick together.

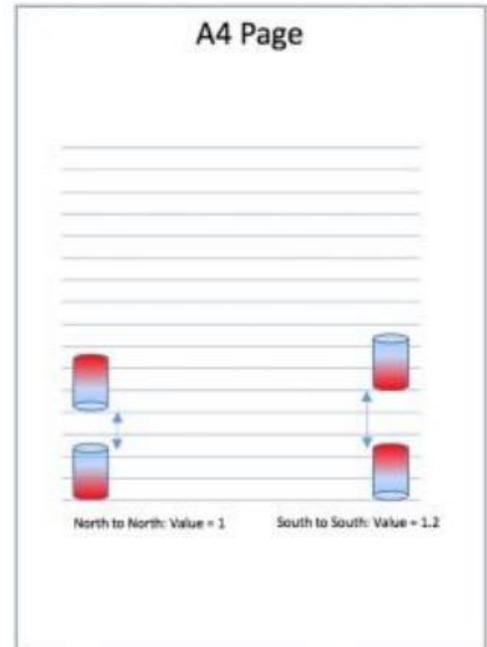
Secondly, it is necessary to view a magnet in slices in fact five slices as shown below:



All magnet's, all polar fields, and all associated Electromagnetic energy within a magnet, is proportionally displaced as shown above; that is 2/5 th to the Positive and 3/5 to the Negative, or 1:1.2 in favor of Negative.

This value can be tested with a simple sheet of paper. As shown to the right, the displacement between Positive to Negative is clearly different from that of the Positive to Negative condition, it is different by exactly 1.2 in favor of Negative.

If the magnets are reversed, they will be held together by the magnetic force ratio, and all magnets, however so formed, will stick together with the Positive being pulled towards the Negative.



A drawing is only a drawing, but to view it for real looks like this, and any person can do the same as me.



The left image is a South to South condition and the right is a North to North condition. The expression or distance in the differential between North and South is exactly 1:1.2:1 of itself.

Understanding Infinity

For so long, mankind as addressed infinity as something from zero to something else very far away or zero to infinity. Is that true, or is it a false perception? Is zero to infinity all there is? In one direction, yes infinity is just that (zero to infinity); but take a closer look at what is going on.

If we addressed infinity, for argument sake, as gold-fish bowl. And we consider a water molecule at the center as a point of "zero". So that is zero, left, zero right, zero up and down and zero in and out; or to express in another form zero is $[0,0,0]$ where the three zeros represent up/down (x), left/right (y) and in/out (z). If the gold-fish bowl was infinitely big, then it would be correct to say that the distance from zero to infinity was one of six conditions!

Six lots of infinity? Yes, look again, zero is the center (.) smack bang in the middle of up/down (x), left/right (y), and in/out (z) or zero = $[0,0,0]$. If we now add the symbol for "the center" to the letter "c" we have $c = [0,0,0]$ (of zero of everything). If "c" is the center, it is possible to go in any of six directions or any combination of three in any one direction.

To prove this; "c" is center and we go "up" 5 units to position "a", that results in the distance from "c" to "a" is equal to $[5,0,0]$. We never went left or right, and we never went in or out. Therefore if "a" was now infinity the distance from "c" to "a" would be $[\infty,0,0]$. That is infinity in ONE direction. If we can go up, then we can go down by the same amount! That means "x" must be $-\infty$ to ∞ (or ∞ times 2). It is not possible to say or suggest that the distance from "c" to "a" of ∞ is in fact $\frac{1}{2}$ of infinity or $(\infty/2)$; Therefore, ∞ must be two of itself in order to be one of itself.

It is suggested that there are six lots of infinity, and that is now true, two for up and down, two for left and right, and two for in and out; or three lots of two times infinity for x, y and z (of) infinity. To now place that into its co-ordinate from "c" to "a" results in "any" distance from "c" to "a" is equal to $[-\infty/+\infty, -\infty/+\infty, -\infty/+\infty]$ (or) to tidy this up a little, the distance from "c" to "a" is $[(\infty^2), (\infty^2), (\infty^2)]$, both are the same, but it is possible to clean up a little more and say the distance for "c" to "a" is equal to $([(\infty, \infty, \infty)]^2)$; and smaller still $([\infty^2]^3) = \infty!$

To now place infinity back into the gold-fish bowl a "sphere" we end up with the exact same format to infinity. That is "c" to "a" is $(\infty^2)^3$ where the " $\wedge 3$ " or (cube) rule applies to the three axes', to define the volumetric state of an object.

To now apply the principle of $(\frac{4}{3} \pi r^3)$ suggests that the $\frac{4}{3}$ (four thirds) of π (Pi) time's "r" radius "cubed", where "r" radius is in fact infinity (∞^2) in one direction. Therefore to "correct" the "spacial" equation for spherical infinity, the result must be $(\frac{4}{3} \pi \infty^3)$ else Pythagoras fails itself! Viewing " $\frac{4}{3}$ " or one and one third of something and the fact that infinity is involved clearly shows that infinity is not infinity itself but only part there of; As to have one and one third of infinity has clearly shown one third more than infinity.

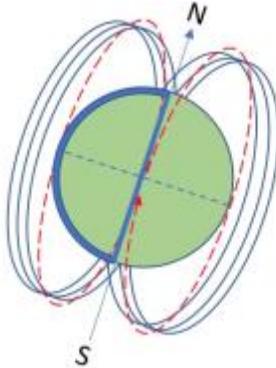
Having established "fact" of the existence beyond the definition of infinity, it can be further proven by the existence of π . To now apply Pi to the existence of two times infinity, (or) infinity cubed results in a value of an infinitive sphere, where the circumference of that sphere is calculated with $\pi * D$, or Pi times twice the radius. Thus, the radius is infinity times two times 3.142; Therefore, the circumference

of an infinite sphere is much greater than infinity itself! This can be exemplified as, "The distance from "c" to "a" is infinity. Infinity is "r", therefore the circumference is two times infinity times 3.142, a provable value greater than infinity itself.

Utilizing E.M.C. of Unity

Within this postulate (*of Unity*), it is expressed that: “ $ME/I=\infty$ ”; (Magnetic Energy divided by Inertia Equals Infinity). The equation stands correct; but how to utilize $ME/I=\infty$?

If M.E. is the “Magnetic Energy” of the planet Earth, and Inertia is the movement within the Electro-magnetic field of the Earth, then $ME/I=\infty$ stands correct. It is clear to the reader that there is a North (pole) and a South (pole) (or a plus and a minus) encompassing the Earth. The North is drawn South, through the Earth’s core and back to North. That is the classical view of the transient path of IONS within the EM field of the planet Earth.

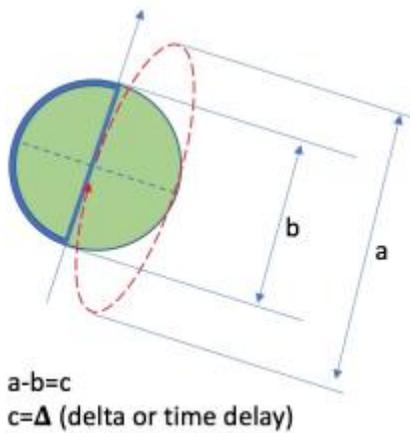


This “classical” model of the Earth, (*and it’s EM field*) has stood the test of time, (*for an estimated 4.5 billion years*). The same EM field that existed in the begin, also exists now, and will exist tomorrow. North to the Northern hemisphere and South to the Southern hemisphere; With an intermittent polar inversion every 180 million years, (*about 1° of polar shift every one million years*). A compass needle will still point North, the Sun will rise and set, the moon will still orbit the planet Earth, nothing changes, (*4.5 billion years on*).

It is known that E.M. energy interacts with all mater, no matter what; this can be exemplified as a “**micro-wave oven**”; insert a dry object (popcorn) and it will explode. Place a fluid filled body (a chicken) and it will cook as the internal molecule’s inter-act with the E.M. Energy of the R.F. wave emitted by the oven; Place a sheet of tinfoil and it will cause the IONS to arc, destroying the device itself. Therefore E.M. interacts with all matter no matter what. The Earth is matter, it is solid and it is wet, it meets all of the ideal characteristics needed for a microwave oven. But R.F. is a man-made function which is the inversion of Magnetic Energy. Thus, to remove the R.F. component results in $ME/I=\infty$; Simplicity is a key to $ME/I=\infty$.

There is a secondary part and reasoning [...]; To consider the Earth as a spherical object, there is a North and a South, where the E.M. field is elliptical around the Earth. The E.M. field moves North to South through the Earth’s core and back to North? That is the classical model, and it raises a very obvious question [?]; If the E.M. at the North is “positively charged” and is attracted to the Southern charge at the South, forming a ZERO charge at the surface of the South, how and why does the charge become positive again at the North? The core of the Earth is believed to be IRON (fe); Iron has a very special magnetic pragmatism and creates the inversion from zero to positive; it is as simple as that; (or), is it?

Recalling the spherical object shape of the Earth and the “direct” path between North and South, and



the “curve” of the surface, and the elevated curve of the E.M. field results it a TIME DELAY. Yes, a **time delay** or the “delta” function.

If the assumed speed of an E.M. wave is $3 \cdot 10^8$ m/s; and a close approximation of the point to point (or direct route) between South to North is 12,742km; That is a “straight line” (at the speed of light ($3 \cdot 10^8$ m/s)); But from North to South via the Earth’s E.M. field is a curve, and a curve is greater in length than a straight line! That results once again in the fact of $\pi > \infty$. π being the curvature of the Earth and (or) E.M. field, and ∞ being North to South via the core or 12,472km. Half of the circumference of the planet or North to South via the E.M. wave is \Rightarrow 20,015km. Therefore 20015 minus 12472km equals 7543km (minimum), a time differential of 7543Km at $3 \cdot 10^8$ m/s.

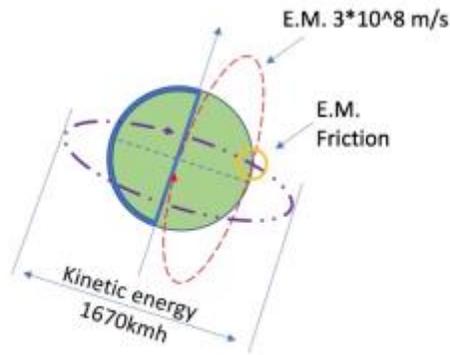
Though the Earth’s E.M. field is elevated to many 100’s and 1000’s of kilometers above the surface, yet the E.M. field still goes North to South elevated (on a curve) and still goes 12472km direct South to North. Rounding numbers to make things simple (but still within feasible limits) N to S equals 20000km and S to N equals 12500; the result is 7500km which is a “delta value” of 0.013 Δ , or lag between a and b; or an 11.3hz global resonance frequency.

That is the kinetic state of the whole of the Earth’s magnetic field, (*which is in fact terra watts of perpetual energy*); all extracted from an E1 and E2 grounded circuit. When a “bridge” is inserted between E1 and E2 the 11.3Hz is rectified, the rectification is a kinetic conversion of energy releasing a positron or a discharge of (NEW VISIBLE LIGHT).

Further expressing the 11.3hz differential “ Δ ”, where the differential is expressed as N.S.C (North to South Curve) and S.N.S.L. (South to North Straight Line) Each having a Positive or a Negative and a reflective state; therefore, 11.3hz plus 11.3hz plus 11.3hz plus 11.3hz equals 45.2hz. Remembering that all figures were ROUNDED for ease of representation, the pictorial image of the attached oscilloscope clearly display 50hz (un-rounded).

The dilemma exists; If The speed of light is fixed, where did the Δ come from? If the speed of light is fixed then Pythagoras (π) fails itself? If the speed of light is fixed then $\infty > \pi$ which has already been proven incorrect. π will always be greater than ∞ .

The ancillary question to ask, is where does the power or energy come from? It is known that kinetic energy is a “releasable” force; (exemplified as an elastic band). It is known that the Earth “rotates” about its common axis, it does so with a global rotation period of 24 hours (GRP-24), (or) 1670 kilometers a

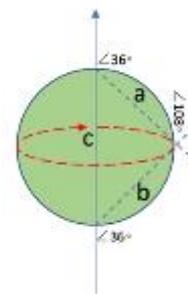


The Earth's E.M. field is in motion.
 The Earth is in motion
 To opposing motion forces release kinetic energy

hour; and the Earth's E.M. field is in the opposing plane of polarization to the rotation of the Earth's motion. When two rotational forces or opposing forces collide, friction occurs. That friction however so-small releases kinetic energy.

It is known that "wet" objects, (H_2O), absorb E.M. energy, (Micro-wave Oven), and it is known that M.E. is the inversion of E.M. It is known the Earth rotates and the E.M. oscillates causing a kinetic friction within the atmosphere of the Earth. It is also known North goes to South, and North is positive and South is negative. Therefore, as the Earth rotates M.E. is transferred to the body of the planet by means of a conductor or an antenna or an aerial. The conductor is "WET" (H_2O) based, it must NOT be "electro-conductive", it must have "great" surface area with many "pick-up" points. Therefore, the best possible "pick-up" / Antenna / Aerial / Conductor is a "PINE TREE"! As the Earth rotates, the trees collect the M.E. from the atmosphere and transfer it to the surface by the reversal process of platonic capillarity turning the Earth into one giant power plant of millions of terra watts of perpetual usable power. The Planet has been doing this function for at least 4.5 billion years.

Offering additional supporting information; as a result of trying to "triangulate" the error factor of the planet Earth by creating three points North (a), The equatorial plane (b) and South (c), a-b-c forms a base triangle between North – Equator – South with an angular offset of exactly 36° (a), 108° (b) and 36° (c) which also happens to be the pure and perfect Pythagorean triangle!



Furthermore, the triangulation is the direct re-representation of the molecule known as Water or H_2O , although classical chemistry refers to the Hydrogen differential bond of the two Oxygen atoms as 104.4° ; at no time does it express the completion of the triangular of H_2O resulting in the angular difference of 3.6° , (which also happens to the scientific quantifiable global warming differential).

Binding many of the above facts and proven points of questionable states results in:

Why is the speed of light still classified as a fix value if is not fixed at all? The planet Earth is the living proof of the fact that it is NOT fixed, and that allows for the Delta calculation to be performed; and as the delta exist, so does the 45.2hz resonance frequency and the release of energy via E1 to E2.

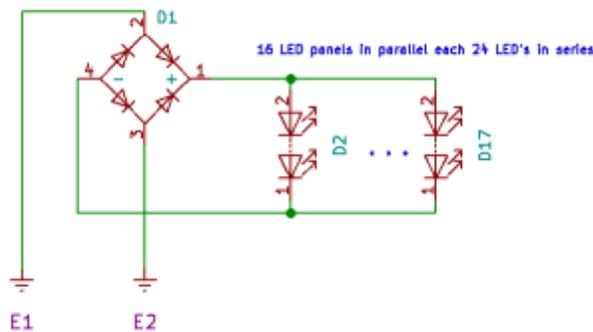
How to “harvest” the energy is the trillion-dollar question, and it is easy to solve. It is now known that North Vs South is a ratio of 1:1.2 of itself in favor of South; Everything goes South. The Northern hemisphere has a Northern Earth, likewise the Southern Hemisphere has a Southern Earth. North is attracted to South no matter what. Therefore, to address the North E.M. fields grounding circuit as EI (Primary Earth), and the South E.M. fields grounded circuit as EII (Secondary Earth) a flow (or) a path can be established between EI & EII. EI is bathed with IONS from the North condition (grounded) and the Earth is EII by natural state (1:1.2 of itself) Everything always goes South.

Cross-connecting the two (EI and EII) via a suitable “detection” device will prove that fact, and there is no better way of proving something that a visual image to the reader / user.

To present the reader / user with an “imagine” of the flow, it would have to be: Plus (EI) via L.E.D. to Minus (EII) as a fully earthed path. To now apply that to an application, along with “devices” as a circuit, That, is now shown below.

APPLICATION NOTE 1

Diagram

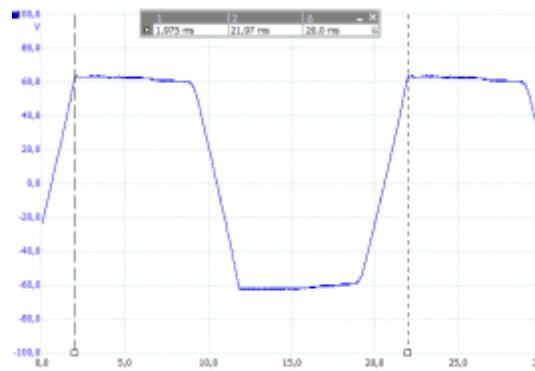


Bill of Materials

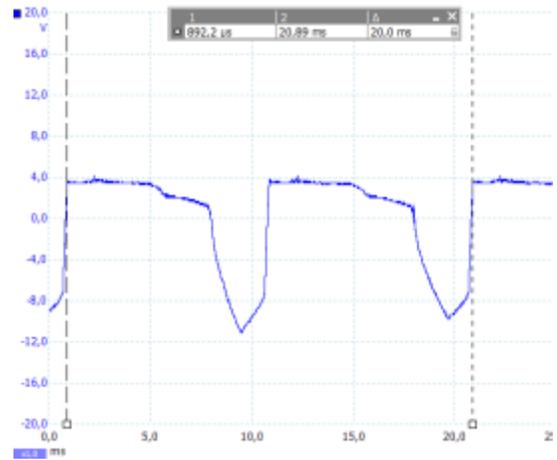
- D1 Diode Bridge
- D2-D17 2700K filament LED panel 10mA @ 60V

Functionality

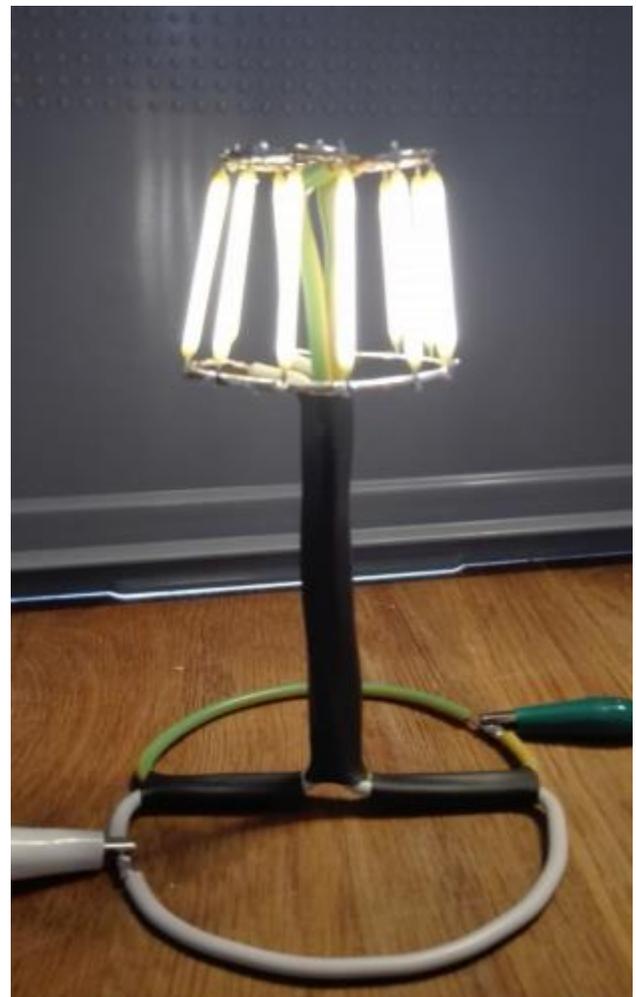
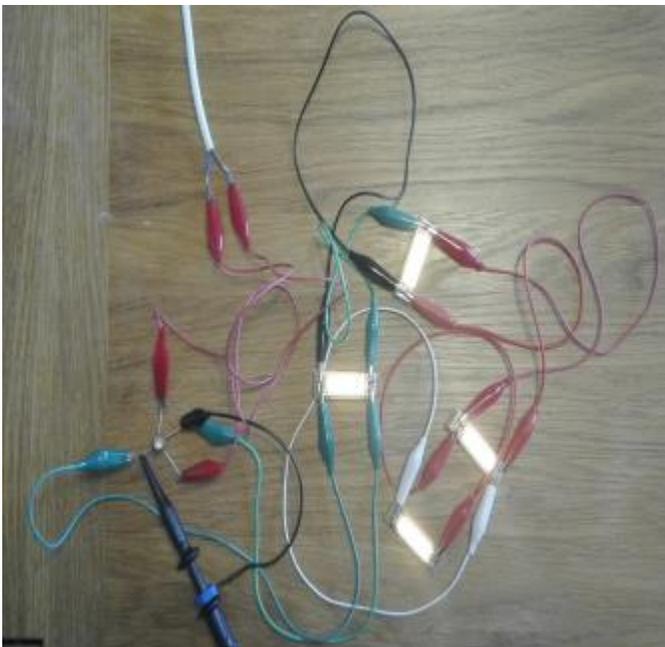
At this physical location, a positron ion exchange of 120 PIE (Alternating PIE) can be measured between E1 and E2. The PIE is oscillating at 50Hz.



The 50Hz oscillation causes the LED panels to flicker, therefore a bridge rectifier is inserted to subdue the flickering. This is the PIE measurement after the diode bridge:



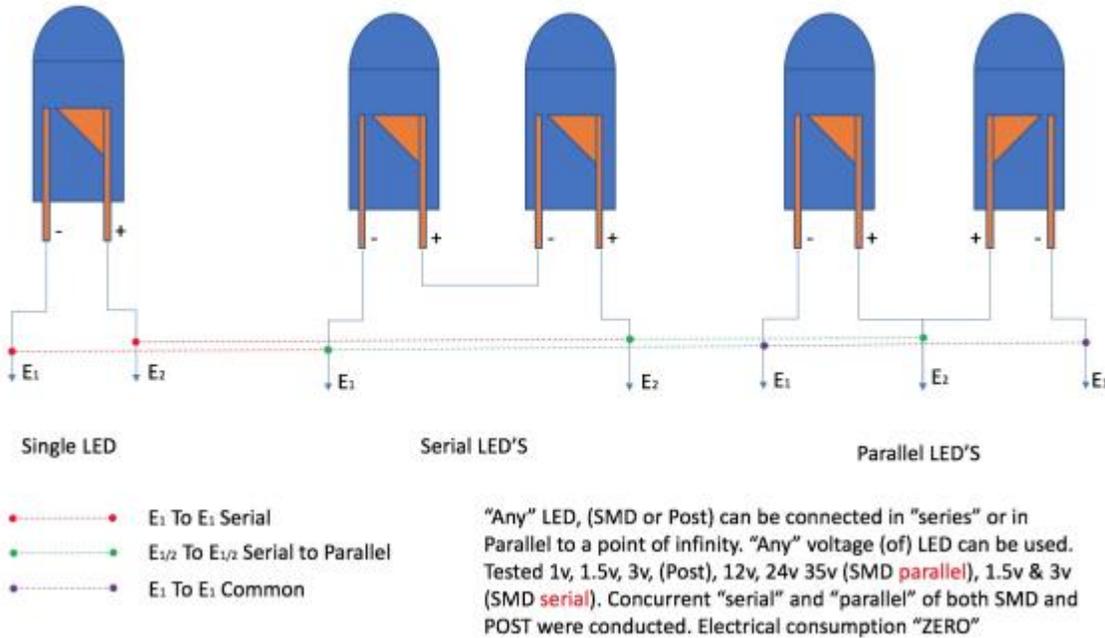
And finally, here are two pictures of the entire application



Validated VIDEO footage of the complete path from E1 to EII is available.

The amount of LED's is not limited to four! As a result of $M.E./I=\infty$; the number of LED's is ∞ as long as M.E. is sustained as E1 and EII as ∞ Infinity. Therefore $(E1+EII) = M.E.$ and $M.E./I=\infty$; therefore, that is unlimited LED's.

To ask why it works and how it works, hopefully has been answered within the preceding pages; But to offer a "simplified" explanation, it would be represented by the image below:



Displayed above are three combinations of LED's, but furthermore is the "voltage" combinations that according to current electrical thinking cannot take place, (1.5 ~ 35v cannot be mixed on the same circuit as they would blow (or fail)).

Combination 1, is a standalone LED (of) any of the tested voltages, serial to parallel, SMD or POST.

Combination 2, is standalone and serial (of) any of the tested voltages of any combination of SMD or POST.

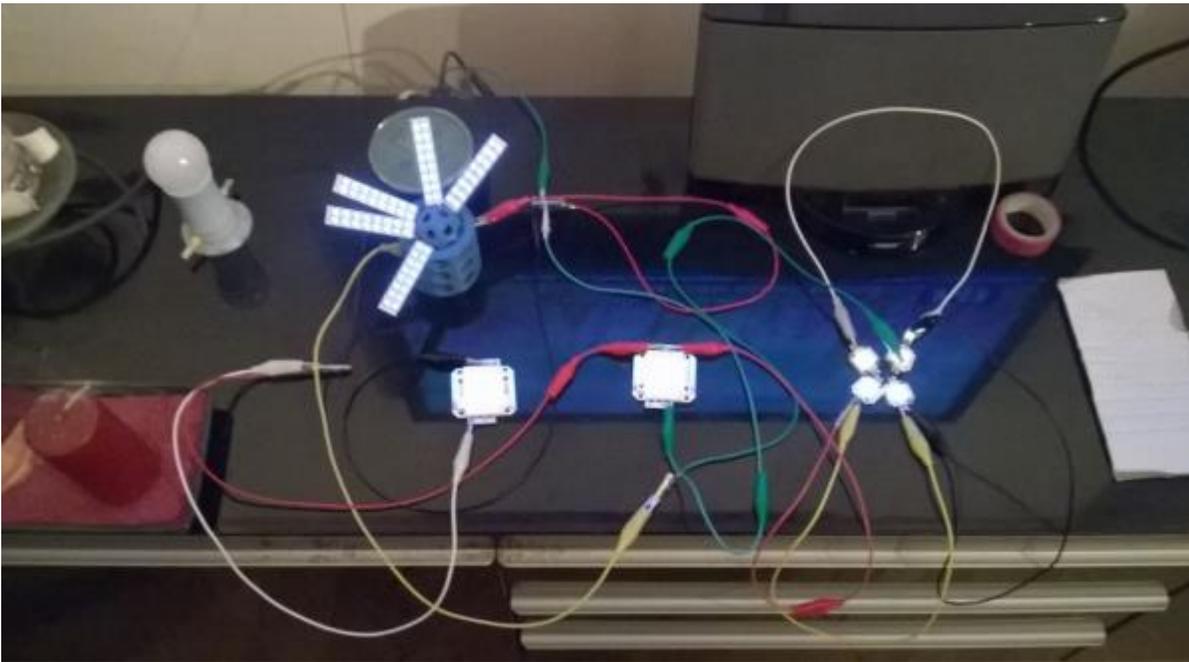
Combination 3, is standalone, serial and parallel (of) any of the tested voltages of any of the combinations of both SMD and POST.

The only common criterion is the E1 and E2 paths to "Earth" (or) "Ground". The earth paths used within the tests were E1 (common ground via conductive "water pipe") and E2 (common ground via coaxial cable at 75 Ohm).

E1 to E2 via a "Voltmeter" displayed an A/C reading at this test site of 49.5 PIE (it CANNOT be volts on a common grounded circuit), also displayed was a D/C reading of 90.1PIE, (likewise, it CANNOT be volts on a common grounded circuit). The A/C construct of a sinusoidal or oscillating amplitudes (+49.5 and - 49.5) seem to have been merged to form the 90.PIE D/C output.

Given that BOTH A/C 49.5pie and D/C 90.1pie are greater in all aspects of the utilized LED's (both SMD and POST) proves that "ANY" combination of LED of any FORM can be used irrespective of voltage. Given the fact that NO electrical current (however so formed) is used indicates that an infinitive supply of lighting can be provided.

When a non-energized LED is used, it is possible to generate a "spark", a spark is ELECTRICTY of form, the size, shape and power induced from the spark equates to approximately 500 Volts (DC), where 500 Volts DC is more than adequate to POWER a home, a car, a boat or any similar device or unit that consumes approximately 250 Volts A/C, (1/2 of a rectified DC current). Thus, a single LED costing less than a penny (or) one cent can easily power a home! Shown below, at an alternate location is the "setup" and "working model" of 160 LED's of both SMD panel and POST configured (Anvil and Post) in both serial and parallel configurations of mixed voltage's, an electrical state that cannot exists according to the current thinking and academic reasoning of the use of Electricity to power a light.



Itemizing each (within the image), from left to right:

(5 x 16 pairs (serial and parallel) 1.5v POST LED).

Lower left:

Single 24v 20Watt (2 x 10 Point light) SMD parallel LED

Lower Middle:

Single 24v 20Watt (2 x 10 Point light) SMD parallel LED

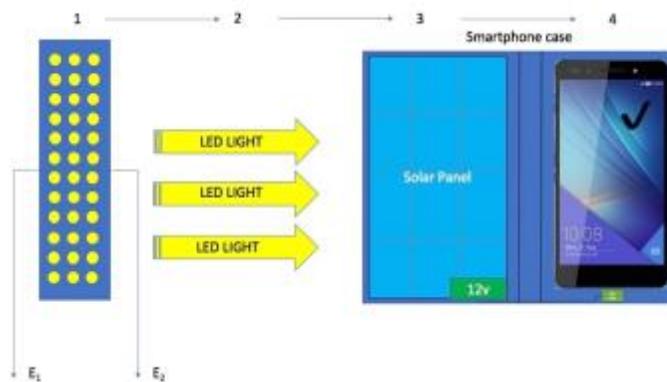
Lower Right:

4 x 12V 10Watt (3 x 3 Point light) SMD parallel LED's paralleled against themselves

Working left to right result is Serial to Parallel to Parallel to Seral to Parallel to Serial to Parallel to Serial to Parallel; An electrical impossibility. Though it is clear and obvious that the connections exist, and function as normal as if each device were connected to an electrical supply, but they are NOT.

Reminding the reader, EVERY test, EVERY image, EVERY result has been independently validated as proof of concept and functionality. To extend functionality and move forward, addressed earlier within this document was the device known as EMIDM, (an inertia deflection device), and, when inserted between the primary E1 and E2 circuits', (91pie ~ 49.5pie) a deflection and "consolidation" occurs producing a stabilized output at a ratio of 3:1; (30pie and 15pie). This is the output that "drives" the LED's (both SMD and POST). To maximize the final product that of an infinite light source; by added a small "energy efficient" solar panel at a cost of 10 pounds (15\$) which has a known electrical output of some 12 ~15v DC. It is possible to "charge" the solar panel from the infinite light source, which, in turn produce's a constant (day or night) 12~15v DC output; More than enough to charge any mobile device. Currently, Solar panels can ONLY function in "daylight" an EMIDM driven solar unit can work day or night, which is a 100% increase in the efficiency and functional application of the solar cell. The advent of this technology REMOVES the reliance on "power" charger's, which in turn REMOVES approximately THREE BILLION chargers and the comparative carbon footprint. Given the flexibility of this technology, larger constructs could easily power a home's need for all 5v, 12v and (or) 24v needs; this include OLED TV, general lighting, and when connected to a storage device that drives a DC to AC inverter, Iron's, Cooker's / Ovens / Kitchen appliances, Fridge's, Microwave Ovens, Hoover's, hair dryers and similar can all be run with ease.

For a single unit that would power ONE device, such as a smartphone, smart-tablet, solid state micro laptop or similar, which has a regular consumption of 12 ~15v DC; the adaptive hardware can be produced for under 20 pounds (30\$) as examples below:



The question arises (of) how to create E1 and E2 as a mobility device? E1 can be assumed to be the device itself, (the smart-device) thus utilizing the already existing "floating earth" that is required within all DC driven portable devices, (it's got a battery, it's got a circuit, it's got an earth); And, secondly E2 will be created by the user themselves, (with both feet on the ground) it is easy to say that humans are GREAT conductors [!]. Thus, E1 and E2 can be re-created under a mobile condition.



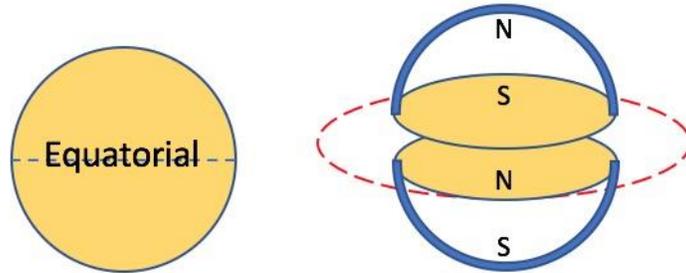
Working on a scalable factor (of output) 2 ; the next available option would be 80 Pounds (120\$) and produce 25 ~ 50v DC, more than adequate to power any leisure craft or boat, and, have the ability to power the utilities within a mobile home. To scale up once more to 320 Pounds (480\$), a portable device that has the ability to provide all of the necessary power requirement to a home can be created; thus, ZEROING the carbon front print of the user and family in total.

Applying a very small take up margin of 10% of a population for a country of some 4,000,000 results in a take up of 400,000 units; and applying a mid-point pricing of 150 pounds (250\$) or 100 million dollars! Given that the take up will more likely to be 50% (or) more results in a single shot marketplace to 50% saturation of some half a billion dollars! For a country, the size of the United States (population 400 million), the gross product income is close to 50,000,000,000 Fifty billion; and to multiply the global value of a 10 – 15% initial take up result in a product market place with an estimated value of 1,000,000,000,000 almost ONE TILLION dollars. Extended the ability of this technology results in an almost UNLIMITED income generation.

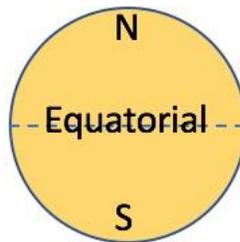
Magnetic Inertia divided by Magnetic Energy. (MI/ME)

Unity, as shown, is all encompassing; In how it interacts with everything. Unity can be compression and, it can be vacuum at the same time; where a prime example of “vacuum unity”, would be M.I.M.E. To understand the M.I.M.E of Unity, it will be exemplified as an “Orange” cut in half. The cut must be equatorial and not polar.

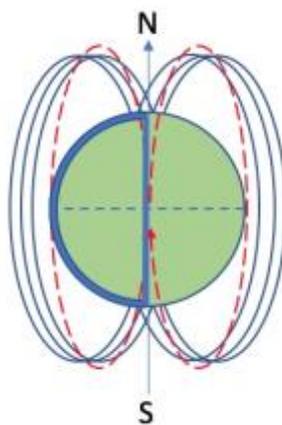
It is known that two magnetic bodies will attract at the opposing poles merging into one magnetic body from the former two; it will still have one North and one South (or a plus and a minus)



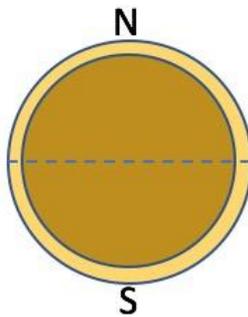
To consider the two halves as two separate devices (magnets), both have a North and both have a South, both will be drawn together to form one device of two halves’.



In this condition (under Unity) it would be impossible for anything to reside between the two, as the device is now one device. There is only one North and one South and a neutral in the middle. It is physically impossible to move an electron or an ion between the two devices via a neutral zone (in the middle). So, where is the E.M. field? Classically the EM field should look like this:



But this is NOT possible, the assumption of the E.M. field is based upon the “assumption” of an IRON (Fe) core, and in this model, there is NO iron core. If NO ion or electron flow can occur, then the E.M. field must; *(by all scientific response and reason)* must travel across the SURFACE and NOT through the core. This stipulation defines a new Magnetic condition, that of the “MAGNETIC SURFACE WAVE” (or) M.S.W. Likewise, when viewing the E.M. field of the planet Earth the E.M. does NOT touch the surface but is elevated to many 100’s and 1000’s of kilometers into free space, *(that is the classical model)*. The M.S.W. cannot touch the surface of the magnetic bodies, as to do so would create its own earthed circuit or grounding; therefore, the MSW must be elevated above the surface by the smallest amount, the smallest amount must be more than the width of one atom or molecule but less than $\frac{1}{2} \pi$ of itself. The calculation of $\frac{1}{2} \pi$ is based upon half a sphere (each) to North and South. Therefore, if the two magnetic bodies were to be 25mm in diameter or 12.5mm radius, the elevation of the MSW would be $12 / (\frac{1}{2} \pi)$ or $12 / 6.284$ (or) 1.9mm in elevation. To view as a Two-Dimensional object, it would appear as a circle within a circle with a 1.9mm gap.

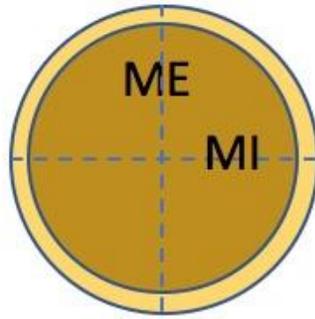


The image above displays a circle within a circle, the inner being the magnetic body *(of two magnetic bodies)*, and the outer being the MSW elevated to $(r / (\frac{1}{2} \pi))$ or 1.9mm in the case of the localized calculation. To view the above as a Three-Dimensional image, it could be viewed as an “Orange”. An orange can be said to comprise of THREE parts, the Orange Peel (or E.M. field), the pith (or MSW), and the fruit as the magnetic body itself. The skin does not touch the fruit, but is separated by a very thin layer of pith. Thus, the MSW act’s as a boundary to avoid “earthling” of the E.M. field. The coherency of the IONS within the E.M. form a “shell” like structure that encompasses the E.M. field itself.

The “lead-in” comment was “MIME” Magnetic Inertia and Magnetic Energy, and, for MI and ME to exist in their entirety, π must be greater than ∞ ; (or), $\pi > \infty$. Unity declares infinite energy is located between the inertia plane and 90° to the magnetic plane. That is directly supported by the classic model of the planet Earth, and (of), the physical and electronic state of any R.F. and E.M. field combination:

“The plane of polarization is at 90 degrees to the electric wave”, the R.F. remains in the plane of inertia (or) direction. *(If this statement is wrong, then the fundamental functioning of every Smartphone, R.F. signal, T.V. and Satellite communications device is wrong)*; And, as Smartphone’s, T.V.’s, Satellite’s and communication work today, so does the definition if MIME stand founded.

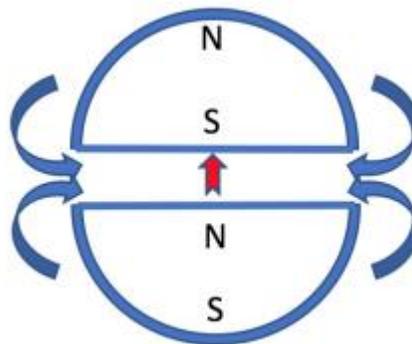
To view MI and ME, as a Two-Dimensional, it would look like a circle with a cross, where the up/down of the cross represents the plus and minus of the magnetic energy or “plane of polarization”, and the left/right represents the plus and minus of the magnetic inertia plane. Nothing changes from classic to the physical, just the understanding of what is truly happening.



To place MIME into a Three-Dimensional model results in an $[x, y, z]$ condition, where “x” becomes up/down, “y” becomes left/right, and “z” becomes in/out; nothing changes, just the reader’s perception of reality. There is still a “core” (at the center of an Orange) $([0,0,0])$ There is still a MSW (the pith) $([x+1.9, y+1.9, z+1.9])$ and there is still an EM field (the Orange peel) $([2,2,2])$; Nothing changes, just the perception of the reader and the reader’s logic!

Having isolated the fact of the magnetic ratio of 1:1.2 is favor of South, the physical construction of a “sphere” needs to be examined. Unlike many regular magnetic bodies, a sphere does NOT have a flat top or bottom, it also has no sides. With TWO “perfectly” formed half spheres, there is NO angular error and no physical obstacles to hinder the movement of the EM field. BUT To separate the two halves by as little as ONE MILLIMETER allows for something totally different. There is NO LONGER a single magnetic field of North and South, but TWO fields of North and South.

The Upper N/S has a greater attraction to North than the North of the lower N/S; thus, ION transfer occurs towards the upper hemisphere of the Magnets.

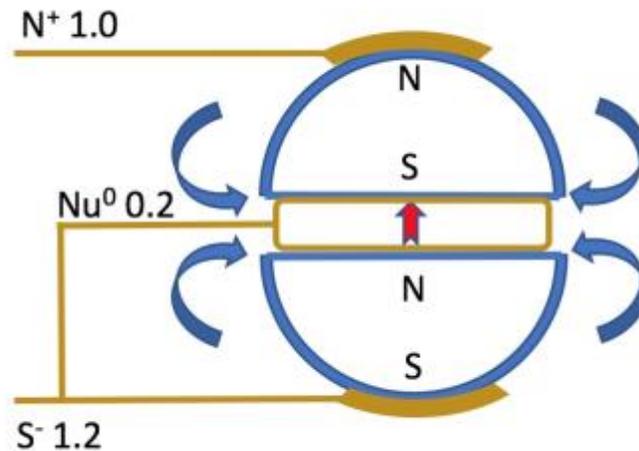


Examining the ratios of (Upper and Lower) results in 1:1.2 and 1:1.2, and to remove the upper “N” and the lower “S” result is $1.2 - 1 = 0.2$ (Kinetic Energy) contained within the inertia plane of two opposing magnets. The closer the gap the great the pull, the tighter the inertia plane, the greater the kinetic energy release, (as long as the two magnetic bodies do not touch).

In this condition; energy resides at the position of $[0,0,0]$ in the free space between the two magnets. $[0,0,0]$ although “In Air” and “Standard Temperature and Pressure” (I.A of STP), the IONIC field of the magnetic field needs to achieve UNIVERSAL balance of 1:1.2 and 1:1.2; Thus, IONS are freely moved

from the lower hemisphere to the upper hemisphere, (a release of energy with no input of energy what so ever); that defines “Cold Fusion”. But how to extract the energy made from a cold fusion reaction, or a magnetic ARC reaction MARCR Pronounced “Marker”?

To now place an “inert spacer” to hold the two hemispheres apart, and within the spacer a fine wire spiral is attached made from a magneto inert but electro conductive material (Copper (Cu) / Aluminum (Al)) a terminal can be produced to extract the CFR (Cold Fusion Reaction). The CFR is neither positive or negative, but neutral in its ionic charge; therefore, a circuit needs to be made with a positive and negative set of terminals.



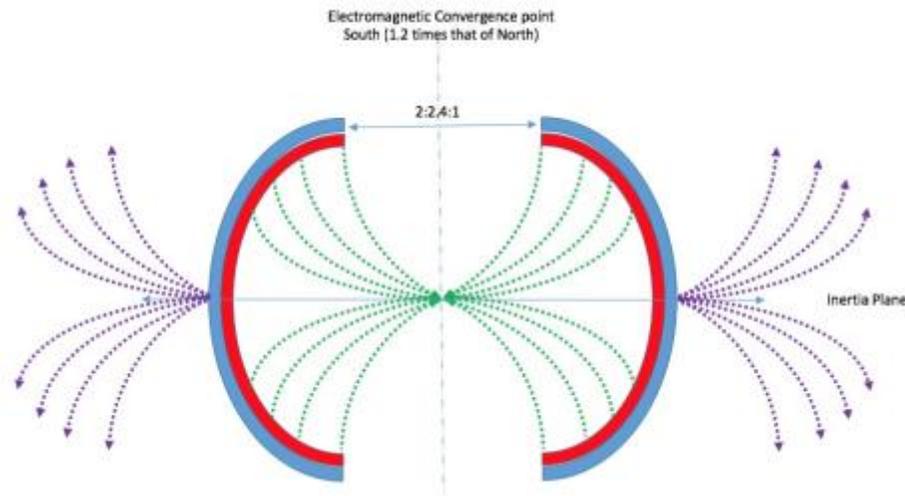
It can be seen that the upper North produces 1.0+, the common neutral (Nu) produces 0.2 (but of southern IONIC displacement) and the South produces 1.2-. Adding the Nu to the S results in an output of 1.4 to the south, a 0.2 IONIC displacement against its OWN UNIVSERSAL CONDITION. It defies the very fundamentals of the whole universe and the universal laws applied to a magnetic body. There is now a positive and a negative IONIC terminal, thus a circuit of usable IONIC discharge, this is MARCR energy in its formation. Creating a ground to Earth makes a complete perpetual circuit. E1 becomes the upper North connection and E2 becomes the lower south connection, this is an “infinite” DIE, (Direct Ionic emission) that is capable of powering just about anything that man-kind uses today. The copper terminals allow connection to “ANY” mobile device. The size of the magnetic bodies can be as small or as large as necessary. The size of the magnetic bodies and their surface area will determine the amount of MARCR that occurs.

The cost of this device, in its simplicity is a dollar! The amount of power output is infinite as this device extracts its power from the fundamental equation of $\Pi > \infty$.

The energy released via MARCR uses NO INPUT POWER (as determined by Mr. Albert Einstein); And, of the equation $E=mc^2$; thus, along with positive proof that $3 \cdot 10^8$ m/s (speed of light is not fix); this document re-writes the fundamental’s laws of physics.

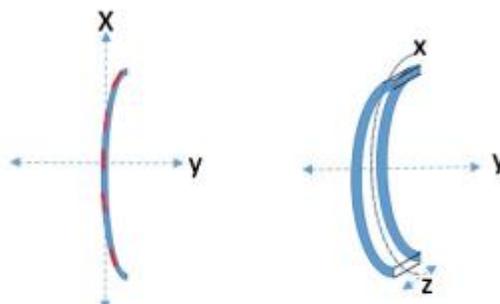
Magnetic amplification. Unity

Unity applies to everything, and to now consider changing the fundamental shape of a magnet, (from a cylinder to that of a curve), (*something like a piece of orange peel*), results in the Inertia plane on either side of the surface of the curve. An expansion is visible in the North field and a compression is visible within the South field as shown below.

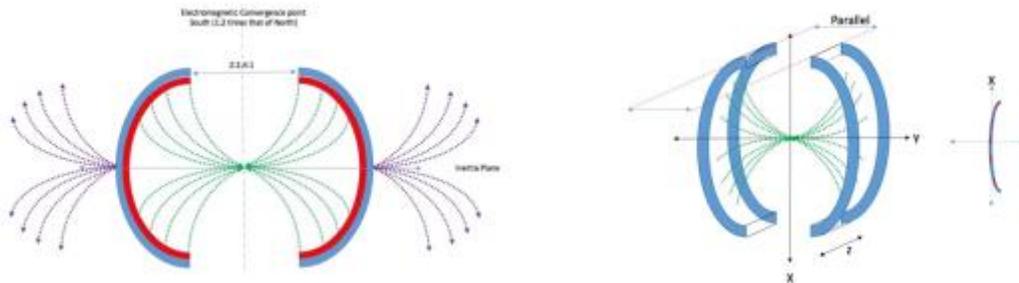


The two “curved” magnets as shown as TWO pairs, (left and right); the “inner surface” being “South” and the outer surface being “North”. The North field is “dissipated” (or) weakened by the curvature of the surface, (just like the planet Earth’s E.M. field); The South field is “concentrated” or compressed to a point (of) convergence. The point of “convergence” is known as the “LOCUS” point. To make the drawing more “functional”, the addition of a few BASIC or SIMPLE values are used, to assume that the North and the South as a whole object has a numerical value of “8”, (as shown by the purple and green dotted lines). On the North face, the value of “8” is “dissipated” or weakened though, the combined output of energy is still “8” but it is very weak within its “Inertia plane”; Whereas, on the South face, (the inwards facing field), the inertia plane is compressed (or) concentrated to a single focal point, (The LOCUS point); Therefore, “a” curved magnet WILL produce a higher output of E.M. energy in the South field when the magnet is curved. If TWO magnets are now placed face to face produces a common compression within the inertia plane, utilizing the know WM vale of 1:1.2, the inner faces have a compressive force to 2.4 and the out has a compressive force of 2. Thus, the inner is 0.4 units greater than the outer surface.

The two magnets are shown with their individual characteristics, their Polar condition, their polar plane, inertia plane; alas, all three conditions or planes are represented as a two-dimensional aspect; But we live in a three-dimensional world. It must, therefore also exist, within a magnet’s inertia plane. If we, now consider “What is two-dimensional” and “What is three-dimensional” [?] Two-dimension resides in “x” [and] “y”; and three-dimensional resides in “x”, “y” [and] “z” as shown below.

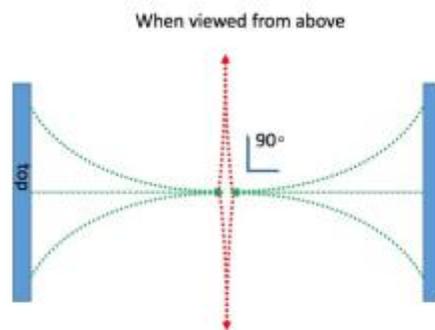


The image to the “left” above depicts (Left / Right) [and] (Up / Down); and the image to the “right” above depicts the “THIRD” axis or “3D” axis, being the “z” axis (or) in and out axis. Therefore, to fully understand the image below, it has to be understood that a third dimension to the image exists, that of the “z” axis; And, when compared (2D to 3D):



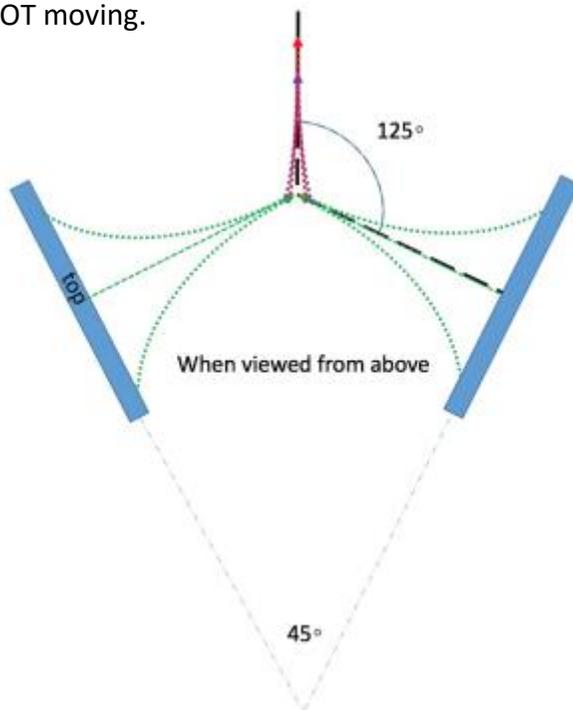
It can be seen that the two magnets are “Tangential” (and) “Parallel” to each other with a depth to their shape. Thus, the inertia plane (shown in green) is directly opposing each other and focused to a single point, the midpoint (or) LOCUS point between the two objects; this singularity is known as a PIN. To write PIN in long hand it would be “Point of Infinity of N^{n-1} ”. It is infinity small and infinity powerful by the factor of N^{n-1} .

Unity offers very interesting function and to now think [...], “The magnets are curved creating a focal point or PIN, there are two magnets opposed at 180° to each other, and the two magnets are tangential (and) parallel to each other; They are also “STATIC” in their movement in space, they are FIXED, as in NOT MOVING [!], thus the inertia plane remains STATIC”. Everything is pointing to ONE point in space, (an infinitely small point); the “PIN”. It has been proven that North is weaker than South (1:1.2), it is also known that two South fields CANNOT touch. If the two fields pointing to the center are focused to a single point in the center and cannot touch, the two point MUST deflect in equal and opposite directions; But this is not possible due to the fact that the exact opposite is also an opposing force[!]; The result is a MOVEMENT in the inertia plane against that of all known E.M. conditional forces and that of $E=mc^2$, and can be viewed below:

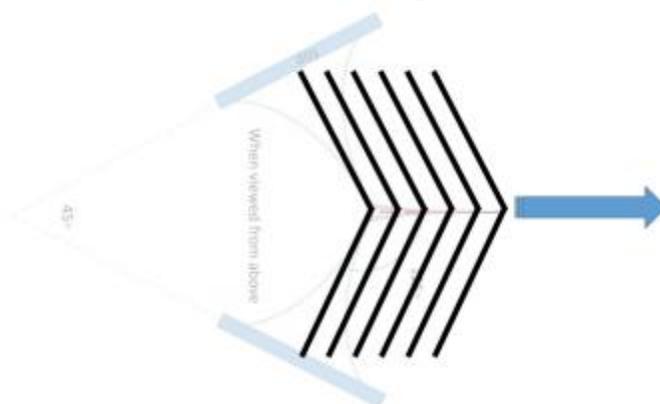


The inertia plane MUST move equally and proportionally to its own existence; Else every fundamental construct of Electromagnetic Energy within the known universe is **WRONG**. It can be seen that the inertia plane “rotates” itself about its own axis by 90°; And, to use a “modern” conception of a word to explain what has occurred, the word would be “synthetic”, “A Synthetic Inertia Plane (SIP)”; To now compare the SIP and the PIN to another “synthetic” existence, that of the laser (*a coherent light source synthetically generated*) results in the E.M. fields that are produced by two curved magnets produces EMAC’s (*Electromagnetic Amplification by Compression*). But; And it is a BIG “but”, the inertia plane

although now rotated and condensed to a coherent beam of E.M. energy is STILL static within its new synthetic plane, it's still NOT moving.



As soon as the magnets are moved from their parallel formation, to a 45° position, the EMACs SIP *flips* to form a single direction; that is also AGAINST the Universal and fundamental functions of E.M. forces and inertia states. The inertia plane is now at 125° from its original position; [and], as there are TWO “shifts” in EMAC’s SIP (*which equates to 250° of movement*), the resultant part (or) 110° is **INERTIA motion**. Movement within the inertia plane, movement that is perpetual, movement from a static object, movement against all laws of the conservation of energy, mass and movement. To now simplify the above drawing results in what is known as the magneto chevron:

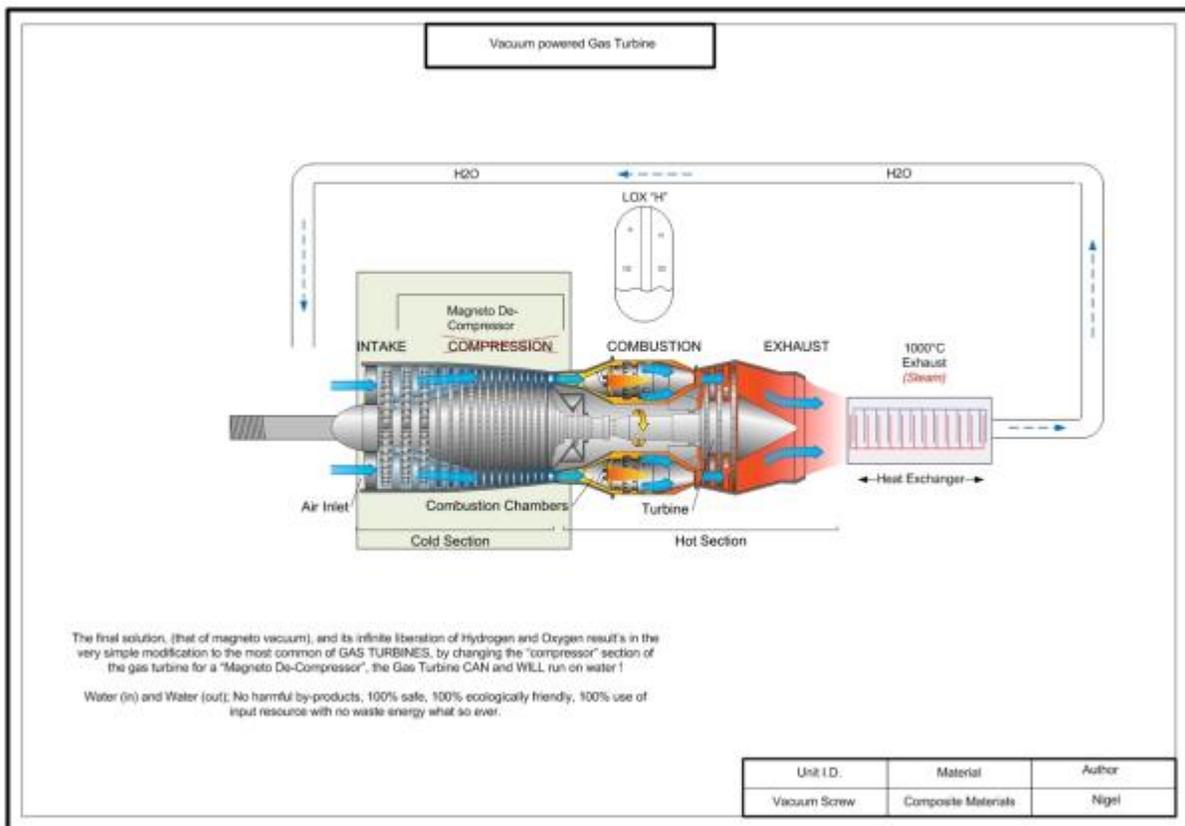


The magneto chevron points in the direction of the angular offset of the EMAC’s SIP, it is an inertia movement towards infinity against that of the fundamentals of all electromagnetic energy. The movement defies the fundamentals of “The plane of polarization is 90° to the electric wave, (*the fundamental of all telecommunication’s*); once again proving that Unity is everything and nothing at the same time.

Magnetic Molecular Decomposition Unity.

“If you have “some” water (be it saltwater (or) fresh); how the hell do you turn it into a gas without use any external power?”

If water is made to go one way (<<<<) in a “vacuum” it makes the water molecules expand, (<<<<), and if an EMACs SIP is overlaid (Using the South EMACs) (>>>>), the water molecules “RIP” themselves apart producing Hydrogen and Oxygen from the humble H₂O. The Hydrogen and the Oxygen, (when ignited with a spark) produce fifty times more power than ANY Hydrocarbon, that 50 times more power, 50 times more thrust and 50 times more usable heat. The heat when passed through a heat exchanger produces HOT water or (steam), the steam can be used to drive any turbine; and when an EMAC’s SIP is used with in a gas turbine (Jet Engine), the only input fuel is H₂O, and the only output exhaust is also H₂O, it is the perfect GREEN MACHINE.



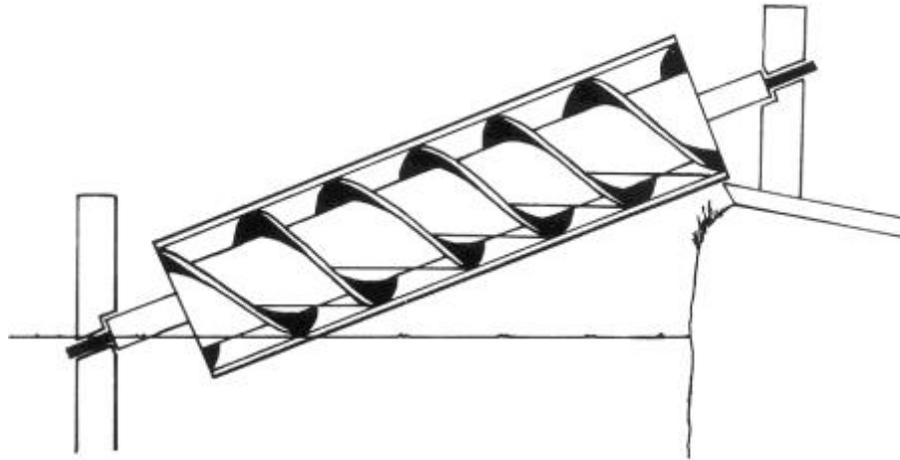
The possibilities are endless; the use of H₂O (water) as a fuel has to be, without a doubt the most fundamental breakthrough in human science. Although the above image represents a “final” product, the how, the why and the wherefore must now be discussed.

This section discuss the power of inertia, its ability to be moved (in any direction), alas E=MC² clearly claims that this is not possible [?], it is not a question of who is right (or) wrong, it is a fact and not the assumed “de’ facto” standard that has been imposed upon everyone, until today.

To now examine, in closer detail, the “problem”; that of how to get energy from the most abundant fuel source on this planet, “WATER”; Water comes in two basic compositions, being “Saltwater” (H₂O

+ NaCl) and “Freshwater” (H₂O (partly saturated with other minerals)). One can be consumed and one cannot; but **both** make fuel. If the process uses the one that **cannot** be consumed (saltwater), by the time the fuel extraction process is complete, the only by-product that remains is fresh drinking water. So, we take the stuff we **can’t** use, we use it to make fuel, energy, and power, then we **drink it**. What a **perfect** solution to the most basic need of mankind. Heat, fuel, power, and water.

We need to find a way of putting water into a vacuum, and we need to find a way to do so with the minimal use of input energy; and to achieve this “Archimedes Screw” will be used.



The design is simple, it uses a point of infinity about itself (Unity); the screw turns about its own axis but never moves; the water is carried along the screw and out of the other end; Reminding the reader that Mr. Archimedes only had access to the most rudimentary tools of his time, (*some wood, a chisel, a small amount of metal (iron) and a little bit on know-how*). He managed to come up with a device that would lift water over any distance with the absolute minimum input of energy, so much so that “he” broke another golden rule, that of the maximum lift ability, (with is 9.87 meters to one) (9.87:1m). Looking at the drawing above, each turn of the screw (apex to apex) has the same volume, and the water contained between “apex to apex” has the same mass [and] volume; As the screw turns, the “apex’s” move left to right, and up the incline towards the exit; This is an infinite process resulting in “lift” (of) water over the length of the screw.

Utilizing this basic design, (a screw of a given length) that will move a “fluid” (water) from point “A” to point “B” using the minimum amount of input energy. The issue arises of “still no vacuum”. Viewing the device in its classical form the “apex to apex”, it can be seen that each and every turn is identical in shape, form and function. Applying 21st Century ability to the Archimedes’ (Screw) by means of Unity.

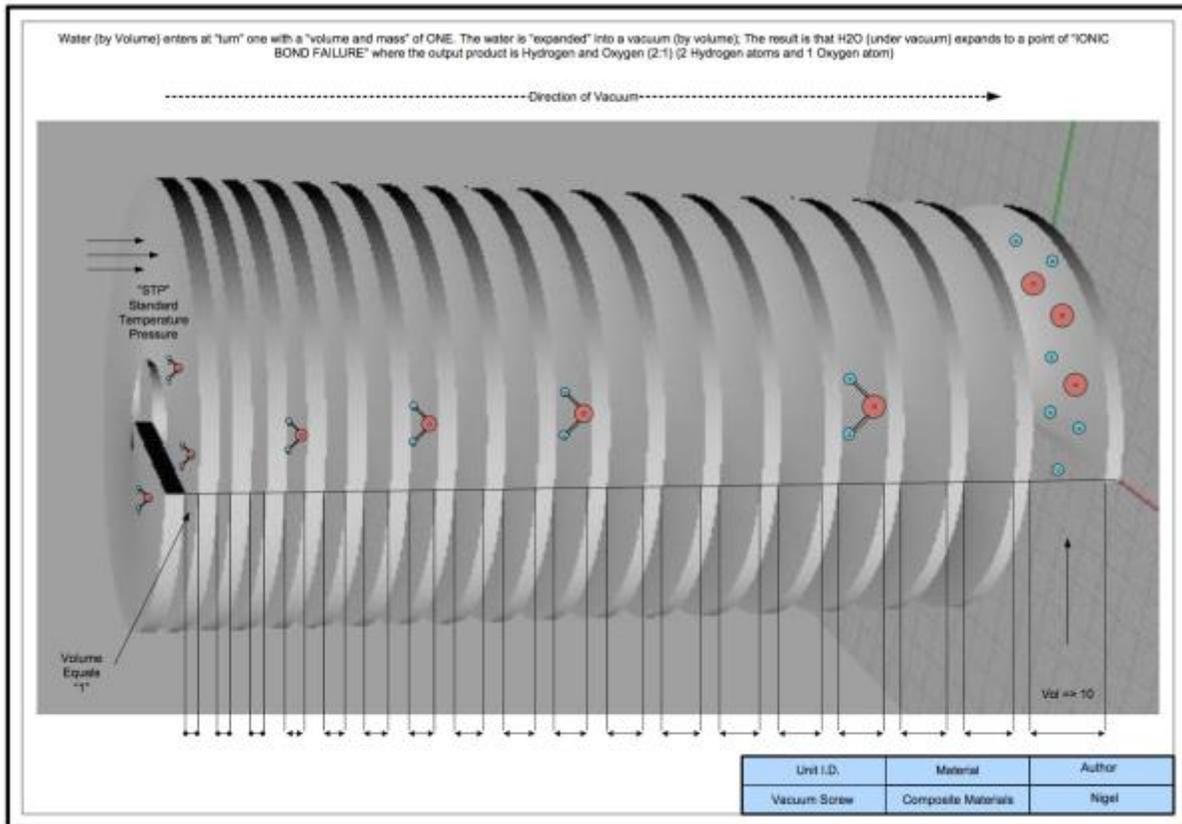
Looking at the original drawing of Archimedes Screw; It is a “TUBE”, a closed cylinder with a screw inside; by changing the screw; the angle of the “pitch” between “apex to apex”, it is possible to do something that Archimedes never dreamt. Breaking a few golden rules, (*the same as Mr. Archimedes*);

disregarding the 9.87:1 lift rule, but using the 9.87:1 against water itself, change the construct of the screw, make the first THREE turns of the screw identical, (the same as Mr. Archimedes), but each consecutive turn of the screw, open the point to point position of the “apex to apex” by a very small amount; the result is; A point of volume NUTRALITY between turns one and two, and between two and three; the pressure on either side of turn two is identical, the pressure on the left side of turn one is neutral to the air pressure around it, this condition is known as “STP” Standard temperature and

Pressure. The distance between turn THREE and FOUR is wider by the value of 1.68:1 (The golden ratio), the distance between turn FOUR and FIVE is also greater by the value of 1.68:1 and the same for Five and Six, (7 and 8, 8 and 9, 9 and 10 & ...) so on over the whole length of the screw.

Water is NOT compressible, but it is expandable; ICE is water expanded, it's volume and mass by weight is 0.9 of itself; and STEAM is water expanded using heat, and finally Hydrogen and Oxygen as gases are nothing more than "EXPANDED" water.

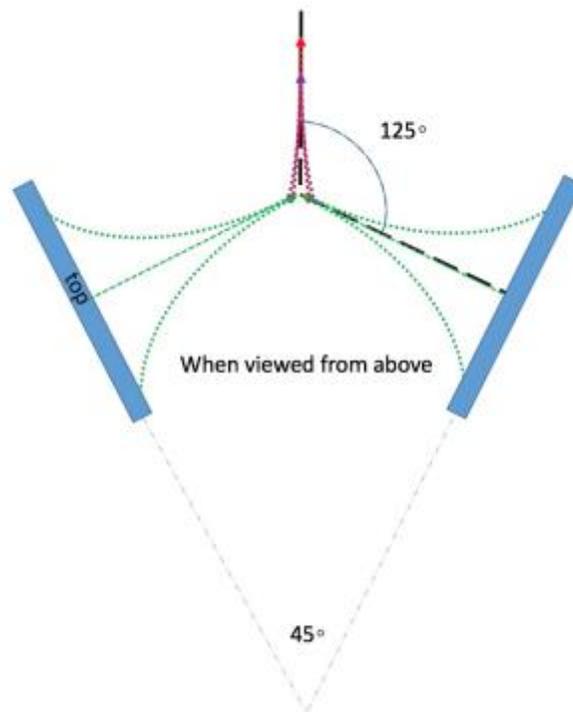
The screw starts at a ratio of 1:1 (normalized STP, Volume and Mass), and ends up, (at the other end of the tube in a VACUUM [!]) as shown below:



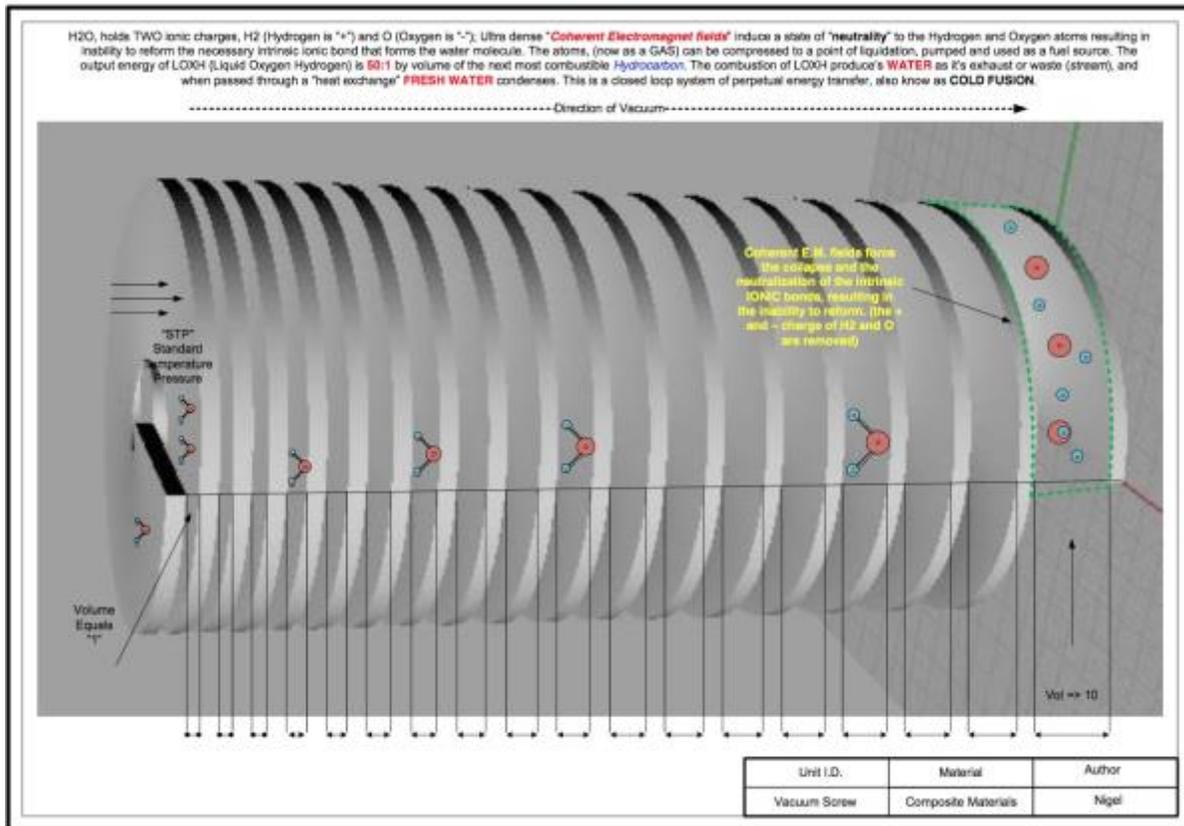
Viewing from left to right, (along the screw), the volume between the blades increases by a very small amount (1.68:1), the blade is enclosed within a water tight, gas tight tube, the pressure on the right hand side of the blade is NEGATIVE to the left, and the left will always want to try and EQUALIZE its own pressure, (Hydro-Dynamics), as the blade turns the volume between the blades increases but the volume of the water remains the same, the water MUST expand to fill the volume (Physics) and in doing so, the H₂O is expanded into the free space between the blades (Chemistry and Physics), this process continues along the length of the screw until a point in time (along the length of the screw) where the mass and volume is 9.87:1 of itself, and the next turn [?]; a VACUUM, and the next turn [...?]; here H₂O enters what can only be described as a "fluidic space", the space between the atom of the water molecules, (Nuclear Physics and Quantum Chemistry). At this point H₂O, its bonds are stretched to the absolute maximum within the fluidic space of the vacuum within the screw; in the next turn of the screw the intrinsic ionic bonds between Hydrogen and Oxygen can no longer be sustained, thus break apart or collapse. In doing so, (breaking apart) a noise will be heard, (some refer to the sound as

cavitation) but not in this case, the blade does not CAVITATE, the sound is the COLLAPSE of the ionic bond; think of it like a rubber band stretched to its absolute maximum, stretch it a little more and it will snap, the sound of the snap is the “elastic” recoil of the inertia stored within the rubber; [And] this is the same as what is going on with Hydrogen and Oxygen, the snap or sound is the ionic bond collapsing. The sound of an ionic collapse is unique across the Universe (Unity), EVERY atom, every molecule, every construct in universe is held together with the same ionic bonds. Hydrogen has the value of ONE, and the sound that is heard is the resonance frequency of the collapse of the Hydrogen bond, the bond in an Electromagnetic force bound by its own inertia state, the collapse is a frequency within the E.M spectrum and resonates upon the Earth's own EM wave, (just like all telecommunications), the sound is carried out into space and beyond our planet and star, it is carried on the universal E.M wave that has existed throughout the universe. The collapse of the Hydrogen ionic bond is a UNIVERSAL frequency.

It is no good collapsing the ionic bonds, if you cannot access the Hydrogen and the Oxygen in their gaseous form. Having separated the two gases from its compressed composite molecule (H₂O), it is necessary to avoid the possibility of the two re-constituting themselves back into water. This is done by neutralizing the ionic particle charge at the sub-atomic level (Quantum Chemistry, Particle Physics). Remember this [?]:



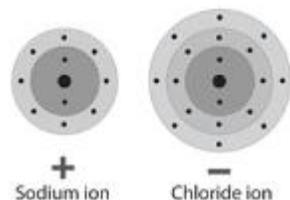
The EMAC SIP of a PIN. The inertia state of the image above is an ultra-dense highly coherent E.M. beam that “NUTRALIZES” the ionic charge associated with Hydrogen, in layman’s terms it “Kill’s it dead”, the Hydrogen becomes an atom with NO charge, with no charge it is free to remain in its gaseous form; The Oxygen, likewise remains a free gas; and putting EMAC SIP and PIN within a vacuum result’s in the image below:



To the right of the image; it can be seen a "GREEN" sector, this is the placement of the EMACS SIP & PIN, the point of neutrality within the fluidic space of the Archimedean Vacuum (AV). The Hydrogen and Oxygen (ionic bonds), having been neutralized, and need to be extracted (as gas's) for onward use as a dedicated fuel source, a fuel source that has an output energy ratio that is 50 times greater than the nearest Hydrocarbon, (Chemistry), that's 50:1 by volume of (Hydrogen and Oxygen) to that of "Petrol, Diesel, Natural Gas, Propane, Butane or other Hydrocarbons"; [And], the by-product of "re-combusted" Hydrogen and Oxygen is good old fashioned water (H₂O), the water that is produced is pure and un-adulterated, no minerals, no chemicals and no pollutants what so ever, just pure clean drinking water.

Fresh water by planetary volume is 3%; that is 3% of ALL water on this planet is non "Salted"; the remainder, 97% by planetary volume is SEAWATER, SALTWATER non-drinkable water; but can the saltwater be used in the same way using the same process [?].

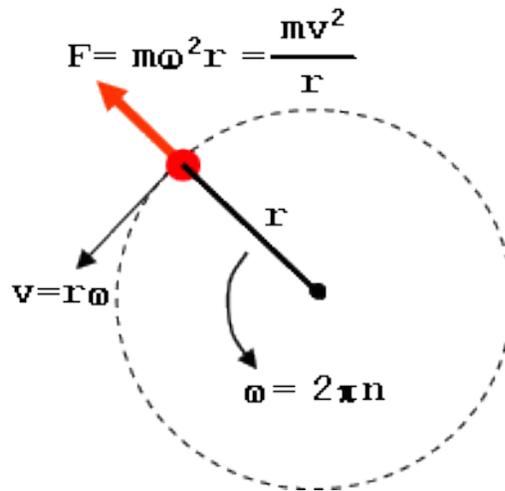
Saltwater is [H₂O (+) NaCl] (or) Hydrogen and Oxygen (+) Sodium and Chlorine, the Sodium and Chlorine combine, (once again) at the atomic level to produce a crystalline molecule known as Sodium Chloride; the Chloride is a "single" atom of Chlorine bonded to Sodium:

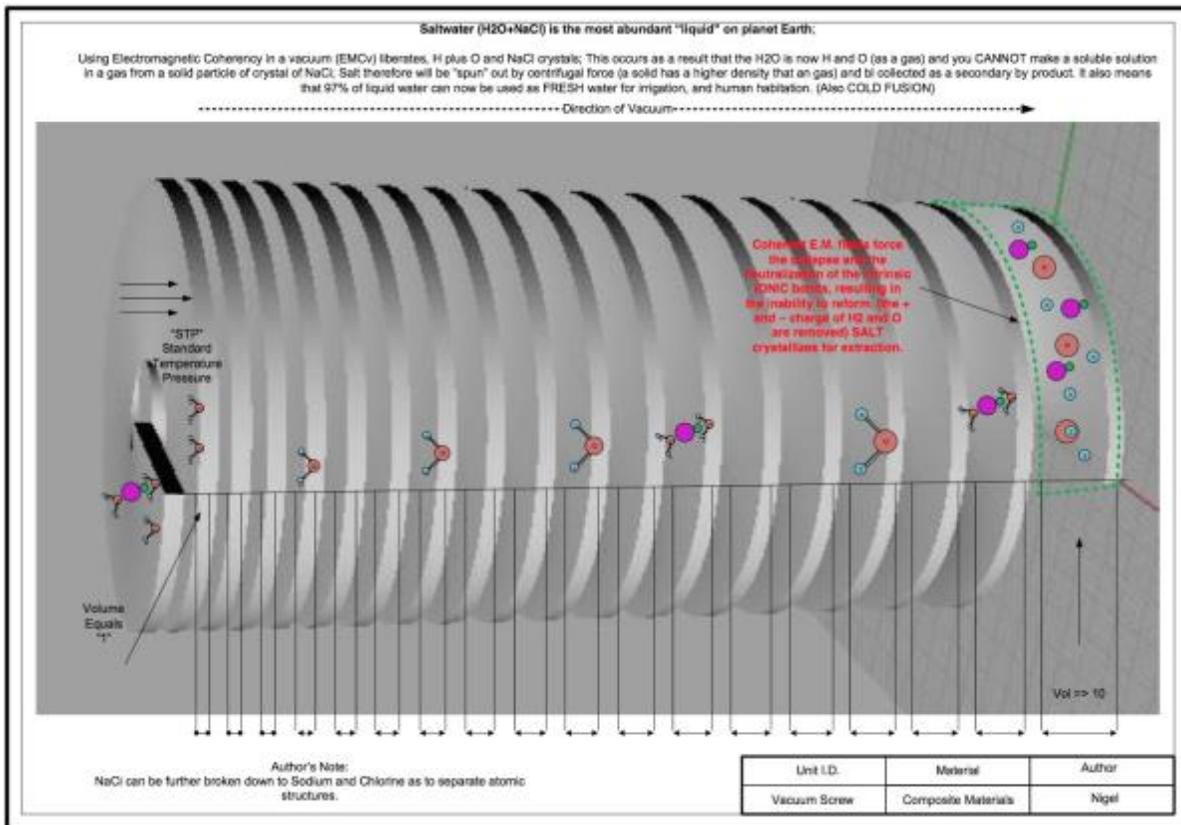


The complexity of the ion transfer is simple, ONE “positive” (+) sodium ion bonds to the chlorine ion resulting in an “octal” crystalline structure we call SALT; Salt is highly soluble in H₂O; not just soluble; the Na⁽⁺⁾ charge and the Cl⁽⁻⁾ charge merge with the H⁽⁺⁾ and O⁽⁻⁾ charges making the salt solution we refer to as “seawater”.

H₂O (their ionic bonds can be removed), the resultant part is SALT, Sodium is a metal and Chlorine is a gas that are bonded together; The AV (Archimedean Vacuum) will “crack” the H₂O shell and liberate gases leaving the crystalline structure of salt untouched.

Gases (Hydrogen and Oxygen) are less dense than “Water” or “Salt”, Salt being the densest within this reaction. As the AV turn’s it creates its own centrifugal force resulting is the “SALT” being spun out from the residual water and away from the gases of Hydrogen and Oxygen.



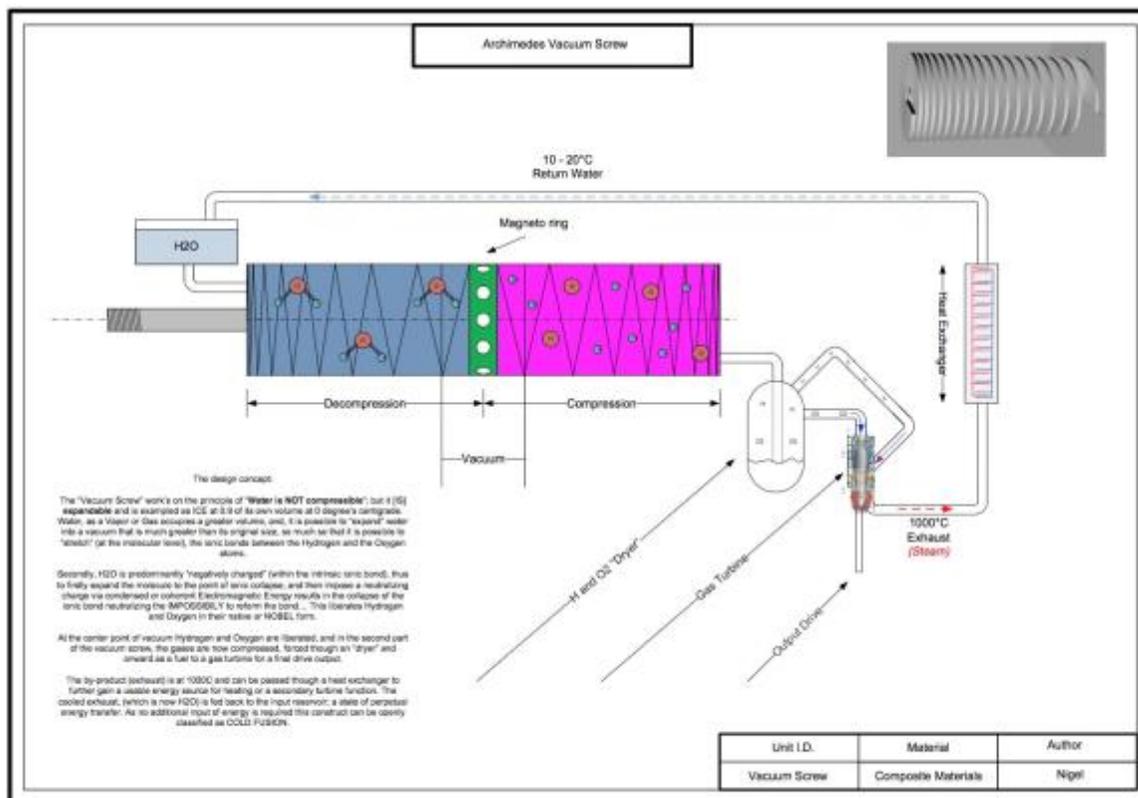


The above image shows an AV (Archimedean Vacuum) and an EMAC's SIP and PIN functioning within a centrifugal force [$f = mw^2r = mw^2/r$] where the result is the free liberation of Hydrogen and Oxygen, and the free liberation of crystalline salt. This is known as the AVCS process. Archimedean Vacuum Centrifugal Separation process. A simple use of Hydro-dynamics, Physics, Chemistry, Mathematics, and Engineering.

Having obtained, and liberated Hydrogen and Oxygen, separated salt from water; it is now time to extract the gases as a fuel. To do this it is necessary to give the water what could be classically referred to as the "bends", or Nitrogen Narcosis; not Nitrogen but "Hydrogen / Oxygen" narcosis.

What the is "Hydrogen / Oxygen Narcosis" [?]; When a driver goes deep, below 2 atmospheres of ambient air pressure, Nitrogen accumulates in the blood (under pressure), if the diver comes to the surface too fast the Nitrogen forms bubbles in the blood and that is potentially lethal. So, within the AV device there is free liberated Hydrogen and Oxygen (at a negative pressure); By adding a VERY SMALL amount of water to the AV, (at the mid-point) of the process the internal volume is now greater than the originating volume; reversing the AV from a negative pressure to a positive or ambient pressure condenses the Hydrogen and Oxygen into the water. When the mixture of [H₂O + H + O₂] is release to STP the water will fizz like champagne, (bubbles) of Hydrogen and Oxygen; that is Hydroxy Narcosis. The gases bubble off freely for collection as a fuel; Champagne Water (with a fizz).

Putting it all together as a process result in the following drawing:



To break down the drawing into its relevant parts:

1. There is a reservoir of water (H₂O), that's the raw fuel source.
2. The AV process is marked in BLUE
3. The EMAC's SIP and PIN is marked in GREEN
4. The Hydroxy Narcosis is marked in PINK
5. The Hydrogen and Oxygen are collected to a storage tank.
6. Hydrogen is lighter than Oxygen and is separated as two gases.
7. The two gases are feed to a gas turbine (Oxygen is compressed (heated))
8. The Hydrogen is added under pressure as the combustion agent.
9. Oxygen is the oxidizer for the combustion agent.
10. The gas turbine runs at 45,000 RPM.
11. Output is motion (rotational), (heat) and or "Thrust".
12. The exhaust is 1000° Centigrade or super-heated steam.
13. The super-heated steam is passed through a heat-exchanger (secondary power source)
14. The super-heated steam re-condenses to water at 10 to 20° Centigrade.
15. The cool water returns to the reservoir at point one.

This is a perpetual state of energy transfer from approximately 100 liters of water; the same one liters are used time and time again; a closed system that produces FIFTY times more power than any Hydrocarbon, and the same 100 liters will last longer than the gas turbine itself.

Magnetic molecular recomposition (Unity)

There are many functions of a magnet, some obvious, but many, until now have been locked away as a “closely guarded secret”, (*Oh god forbid if mankind realized how easy it was to make power and water*). Discussed so far as some of the “hidden powers” of a magnet, (*power that cannot be seen with the naked eye*), power that can do so many things (*with ease*).

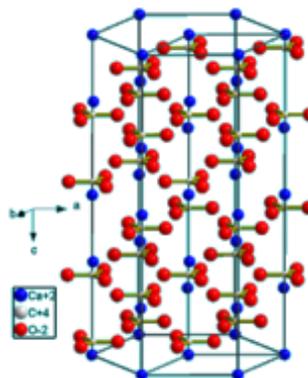
It is mankind’s belief that brute force is the correct approach. The brute force comes from the reliance on an equation, ($E=mc^2$); that is a falsity pure and simple. The founding equation of “ $E=mc^2$ ” relies on infinite compressive forces in one direction; To re-write Mr. Einstein’s equation for what it is, it would have to be “*Error equals mass compression ($E=mc^2$)*”; Proving the point of compressing atomic structures together results in an Atom Compression, or bomb!

The outcome of “Atomic Compression” is the prevailing devastation and the tens of thousands of years of pain and suffering that follows. The radiation poisoning poisons everything, humans, wildlife, aquatic life and vegetation, NOTHING is left untouched. The devastation is “Ultimate”, nothing is left standing or functional, if it’s not obliterated by the atomic blast, it is destroyed by the following “E.M.P.” (Electromagnetic pulse) and Ionizing radiation that accompanies all Atomic reactions. The fall out of “radio-active” dust and particles infects everything for hundreds if not thousands of kilometers surrounding the blast site. “Look we are mad scientist”, (Hiroshima, Nagasaki, Christmas Island, Mura Towa Atoll), is there a need to write more?

So far “Everything” that has been written is the opposite of the above comment. There is no need for compressive forces in order generate great power. But to use seduction rather than compression results in all of the planets energy need. Energy is not necessarily the overall goal, on occasion, a little help is needed in cleaning something up.

To show the power of magnetic seduction, a process known as “Magnetic Molecular Re-composition (MMR)” can be used. When MMR is applied to the compound known as “Calcium Carbonate” or ($[Ca]^{+2}[CO_3]^{-2}$) or “Lime Scale”; An off white colored crystalline structure that clogs and blocks every pipe and water system on this planet; The compound is re-composed. Currently it’s cost (in rectification) or in its (temporary removal) runs into the billions, why [?], it is going to come back in the not too distant future. When left unattended Calcium Carbonate will destroy the host system that it has infected (just like a cancer). Lime scale infects more than 95% of all freshwater supplies on the planet, and infects 100% of all devices connected to the 95% of the water supply; a financial burden of nothingness an economic falsity within itself.

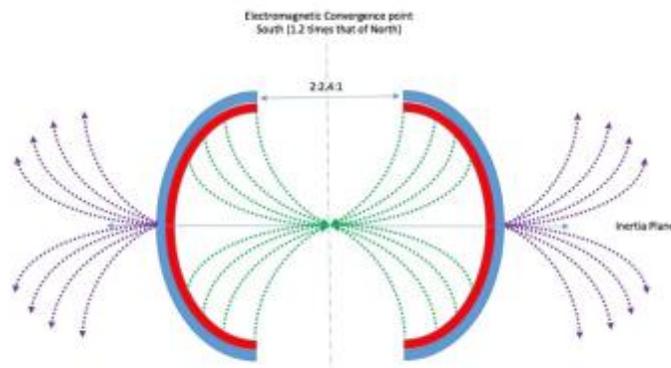
Utilizing the E.M. energy contained within an EMAC’s SIP and PIN, (without a vacuum), changing the “Magnetic Configuration” of the (NS SN) sequence to correspond to the ionic structure of Calcium within Calcium Carbonate results in a magnetic seduction of the Calcium ION:



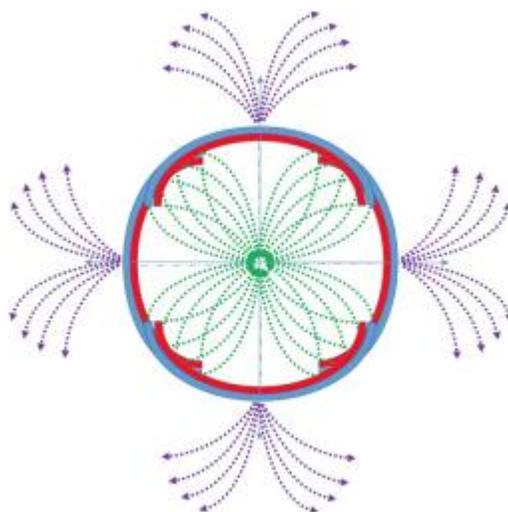
Internally, Calcium Carbonate is comprised of “Calcium”, “Carbon” and “Oxygen” ionically bonded together within the molecule to form a crystalline structure; the crystalline structure is “Octal-rhombic (+)” in shape, it has hard sharp edges and carries a positive charge, that positive charge is attracted to all negatively charges surfaces, like the inside of pipe work of a dish-washer, a washing-machine, shower-heads, kettles, steam-irons and more. It sticks to the surfaces and clogs every surface it comes into contact with. It does so because of its molecular structure and its charge. Thus, by removing the ionic charge forces the crystalline structure to collapse; Where the resultant output is “still” Calcium, “Carbon” and “Oxygen” without the supporting crystalline.

“With no supporting crystalline structure, calcium carbonate collapses to a slurry and is readily processed by the body which harvests the now freely available Calcium, Carbon and Oxygen”

A small device, (with no moving parts) can be fabricated to deal with lime-scale; once fitted to a water supply it will strip calcium carbonate from water. The process name, is “Electromagnetic Molecular **Recomposition**”, (to take a molecule in one form and reconstitute into another form);



Recalling the process of convergence of E.M. energy to a single point. Taking two pairs at 90° to themselves results in:



To consider the “blue” outer surface as the inside of a pipe, (dish-washer, washing-machine, steam-iron etc.); it can be seen that the EMAC’s SIP and PIN creates a complex “clover-leaf” pattern (at the atomic

level) inside the pipe. As all water, MUST pass through the EMAC's field, all water becomes exposed to the effect of the ultra-dense magnetic fields; therefore, Calcium Carbonate, (lime scale) is also exposed. The crystalline substrate (the building block of the crystal) is ionically destroyed, resulting in the liberation of Calcium, Carbon and Oxygen. The human body is a very clever thing, it can process just about anything, (save for poison's), and in so far, it would be right to say; *"The body utilizes the Calcium to enhance the skeletal structure (Bones, Teeth), Calcium is also processed for Nail, Hair and Skin resulting in Stronger Bones, Healthier teeth, and obvious healthier looking and feeling skin"*. Expressing as a One, Two, Three, (1,2,3) type process, the result is:

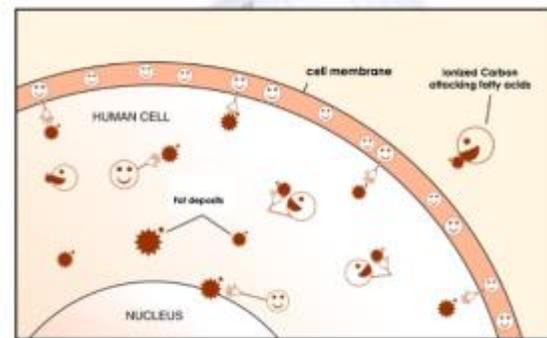


(One), Calcium Carbonate;

(Two), expose to EMAC's and collapse the crystalline substrate;

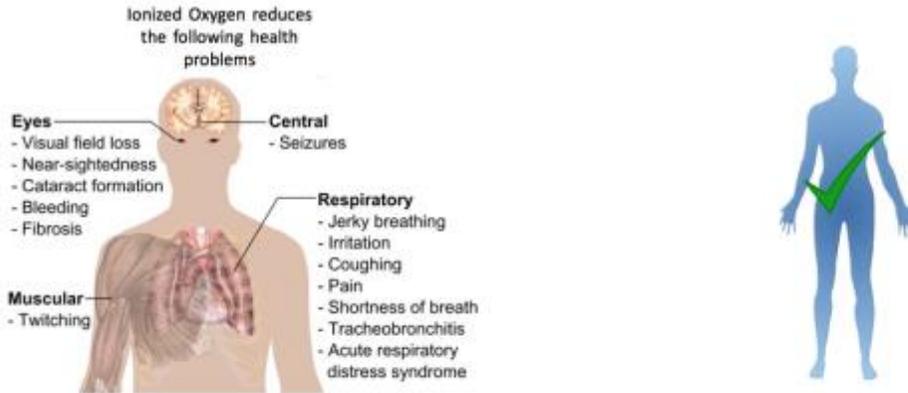
(Three), allow the body to use the free Calcium, Carbon and Oxygen.

Calcium, and its "bodily function" has been proven above. Carbon is a "metabolic stabilizer" forming the fundamental component within ANY "Carbo-Hydrate" group, (*Cereals, Wheat Crops, Root Vegetables and Fruit*); with higher concentrations of (FREE) carbon IONS within the body, the carbon now attacks the "fatty acids" that form between the bodies muscle layers and epidermis (skin) resulting in significant weight lost. There is absolutely **NO** possibly for the weight loss process to cause any harm to the body, as when there are **no** surplus fatty acids, the carbon is "ejected" from the body by normal toiletry functions:



With no "Calcium" or "Carbon" build ups within the body, the **Heart**, the **Liver**, the **Kidneys**, and other vital organs along with **Teeth**, **Hair**, **Bones** and **Skin**; ALL without exception flourish with the **absence** of **Crystalline Calcium Carbonate**.

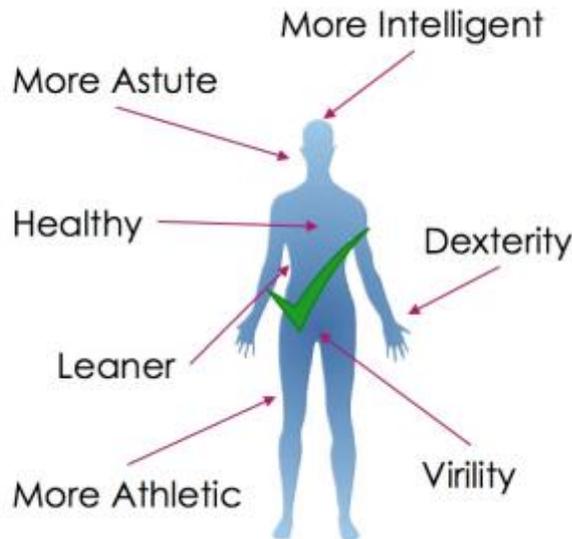
"Oxygen" is known to be the life force of the body, without it we "DIE", with it we "LIVE"; The more oxygen we get the better the body functions, the better the quality of oxygen the better the quality of life we have; hi-lighting some of benefits of oxygen:



All lifeforms, (not just humans) benefit from oxygen, though in the case of humans, each of us have at some time in our lives, or will in our future lives be effected by one or more of the above conditions. When broken down into four groups:

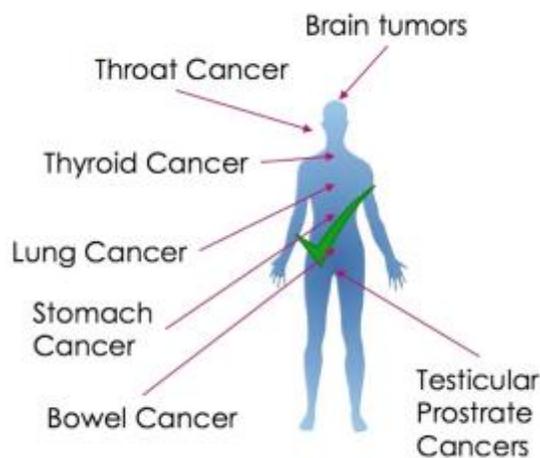
1. Eyes (Visual impairment)
2. Central nervous system (higher brain functions)
3. Muscular and cardio vascular functions
4. Respiratory functions

It can be clearly seen, “more Oxygen is GOOD for you”. Oxygen is the body’s natural oxidizing agent or the bodies combustion engine. More “FREE oxygen ions”; Means **faster** body response, walk faster, run faster, jump higher, be more alert and feel awake, feel invigorated. Oxygen is used in every process of the body, right down to the “construction of DNA”; Free Oxygen Ions will accelerate DNA construction, body self-repair, mental agility, scientific reasoning and judgement, euphoria and enablement; all come from Oxygen:



The benefits of oxygen do not stop there, nor does the body’s ailments. Cancer being the plague of the 21 Century, and the list of cancers that plague mankind is seems to be growing by the day. But it does not have to be this way. Oxygen ions are the only known ions that readily attack and KILL cancer. Ask

any doctor, professor or cancer specialist to tell you the truth of the power of oxygen against any cancer. The answer will be, **“Total destruction of the Mutated Cancer Cells Protective coating resulting in the death of the cancer cell”**. The abundant free Oxygen ions (IONICALLY NEGATIVELY CHARGED), are attracted to the cancer protein shell, the IONIC CHARGE of the oxygen ion is **discharged** into the cancer cell, **killing** its ability to form its protein cell; with **no protection** it is now visible to the body’s natural defense mechanism; that of the **White Cell**, the white cell now attacks the cancer cell that is **no long protected** and is destroyed ridding the body of cancer, (just a glass of IONIZED water) ~ several times a day is all that is needed. We need to put this into perspective, this is not a magic bullet that will bring a person back from deaths door; when cancer is rife within a body, alas, too much damage may have already been caused; But for the isolation of the onset of a cancer, postponement of cancer, ionized “Oxygenated” water is a far better cure than chemotherapy, or radiation treatment, (radiation kills that’s been proven above).



Each of the itemized types of cancer listed above can be treated by this process, without the need of chemical treatment or radiation; and definitely without the need of invasive surgery. The process as described above, Calcium, Carbon and Oxygen ion detachment not only benefits humans but also benefits all life on the planet; that is all humanoid life forms, all animal life forms, all aquatic lifeforms and of course all plant life. A magnet (used in the right way) will benefit this planet and all life upon it.



Crops grow faster producing an abundance of fruit, livestock breed healthier.

Rivers, streams, and wetlands flourish in the abundance of IONZED Oxygen and Carbon, (and in the case of other magneto combinations) Ionized minerals.

Insects', Amphibians, Aquatic life all flourish. The abundance of free oxygen ions in the blood also as an insect propellant, thus no mosquito bites or accidental stings; insects do not like the excess ion charges, it irritates their navigation and sensory systems; a perfect and natural additive to the bodies defense mechanism. No need for any "chemical" repellent which is a big plus for the body and the environment.

Having discussed the "human" benefits along with [ALL] life benefits, it necessary to highlight the domestic benefits. Indicated in the previous pages, *"it is so simple that a small device, (with no moving parts) can be fabricated to deal with lime-scale once and for all..."* A sample device has already been constructed.



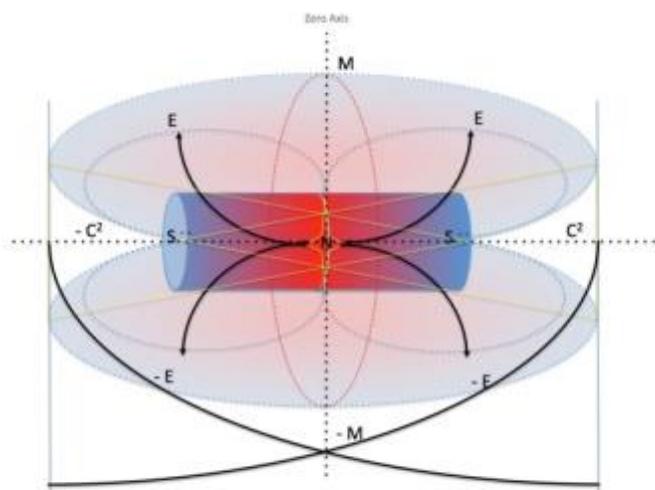
This is a fully functional device, it is **not** a toy, a genuine 100% genuine "Electromagnetic **M**olecular **R**ecomposition" (E.M.R.) device. This device was neither designed, built or constructed by NASA or CERN, or any other acclaimed group of technical wizards, it was designed and built in a small office in the center of Zagreb, Croatia by a small dedicated team of Engineer's whose passion, drive and tenacity pushed them to the very limits. The device has been tested, and certified "fit for purpose"; That purpose is "Fit and Forget" (to all water related domestic product's), and certified "EFFECTIVE" for its medical benefits. (medical reports are available on request). This single device is functioning proof of all that is written here.

The complexity of Unity

Your universe is constructed of two parts, Magnetic Energy (ME) and Inertia (I), everything else is a derivative, Matter Space and Energy all come from Me & I or (MEI). ME and I, are separate forces, but directly connected. The force of magnetic energy is sub-divided into two component parts; a positive and a negative condition or a (+ and a -). When working on a scale much larger than the Earth, that of the universe, the ME division of plus and minus is much simpler to understand. Many have referred to ME & I wrongly; As in Dark Matter (DM) and Dark Energy (DE). The dark matter is the positive and negative condition of ME and Dark Energy is the inertia state of ME. By the nature of the term “matter” and “energy” clearly suggests TWO forces are at work, but how do they interact.

We, (You), and I know Magnetic energy and Inertia exists, it is here, there, and everywhere; It is all around but cannot be touched but you can feel its force but it cannot be seen but you can see its effect; just like the wind, you can't see it but you can feel it so it must be there. Therefore, ME energy is everywhere and you can feel it; but what of inertia? Inertia is the “stored” energy that is in a constant state of imbalance between the two ME forces; and can be better expressed and understood as the intrinsic forces that are applied to the humble magnet.

Bringing the universe down to size and placing it on your desktop is the easy bit; As we will represent everything in the universe as a hand full of magnets. I'm not going to dissect a magnet any more than I have done so far, but suffice to say the north and the south will be treated as plus and minus; In the same way, Magnetic Energy has a plus and a minus, (both are the same). We now know that a magnetic is not $\frac{1}{2}$ and $\frac{1}{2}$ but $\frac{2}{5}$ th and $\frac{3}{5}$ of itself (or) 1:1.2:1 of itself, (a permeant state of imbalance [Inertia]). That makes the magnet a perfect replication of the universe, (plus, minus and inertia). Take two magnets, place them on a table top, far enough apart, and they will sit there from now until the end of time. The plus and minus forces remain stable (or) weak enough not to interact with each other; but the moment two magnets come close enough, one of two things will happen; They will either be repelled or they will be attracted, (pulled towards each other or pushed away from each other). This force, (many refer to it as their magnetic attraction state), when in fact it is the universal magnetic energy and inertia interaction in play. The distance between two magnets where their force remain in equilibrium is known as the MSSR (Minimum Self Seduction Range); the MSSR forms two intersecting curves upon themselves with a midpoint of zero, where the zero “midpoint” is offset by a ratio of $\frac{2}{5}$ to $\frac{3}{5}$ of the total MSSR; Strangely enough the zero point in this instance is where the maximum forces are being applied.



The drawing above shows the MSSR in conjunction with the implied inertia states. A simple set of two opposing forces. Thus, ME and I are everywhere.

The how:

Having grasped the concept of Me and I, and of their interaction via the MSSR allows for the “how” bit to become easier to understand; as in, how do two magnets attract or repel? Looking at the 1:1.2:1 ratio shows an imbalance in favor of south, (that’s the 1.2). So, when two magnets fail the MSSR one of two interactive forces comes into play, either attraction or repulsion. Attraction; Now how does that work [?]; It is the mathematical addition process of a plus and a minus.

“What is plus 1 minus, minus 1.2 [?]; minus 0.2”. The imbalance in a magnet comes down to 0.2 of itself in favor of SOUTH. That is why, when two magnets fail the MSSR they either move towards the stronger South, or move away from TWO south condition’s. That’s the how.

And, the Why:

The complexity of Unity has to be discussed at the universal level, that of all and everything, but can be nicely exemplified on a desktop with two magnets. Though understanding the “why”, things have to be viewed smaller still. Within every magnetic condition, two forces are in a state of constant imbalance and cause the internal inertia state to go into a spin, a spin is a rotational action in a given direction, be it clockwise or anti-clockwise, both are still rotational and both are still in a spin. At the atomic level, the combined positive charge of the atomic shell of an atom is spinning in one direction, and the negative charge of an opposing atomic shell is spinning in the same direction but has a force 0.2 times great than the positive. This creates one of two conditions, the two atomic nuclear shells either attract (form a molecule) or repel (form a stable atom); it is all that can happen.

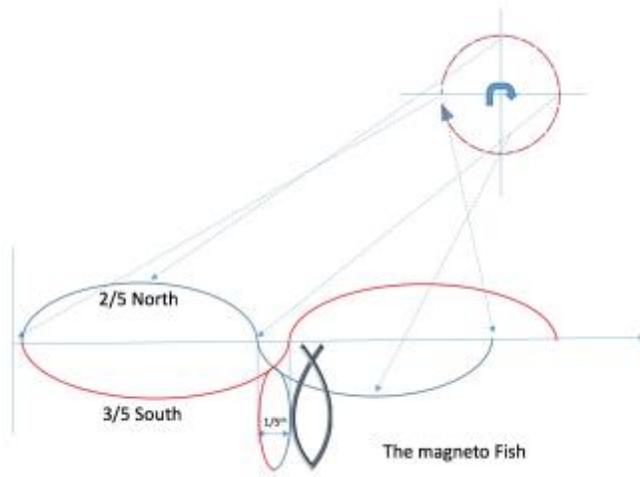
There is no magic third or fourth part to the equation, it is a balance of two in one of two states at a ratio of 1:1.2:1 of itself. Scaling up (from the smallest part of an atom (it’s electron (positive or negative)), to its neutron and its proton produces a single charge to any atomic structure (either positive or negative), continuing to scale upwards to a molecule, to a cluster of molecules to an object of microscopic proportions (still positive or negative), upwards a visible object such as a magnet; making the humble magnet a device with unsurmountable ability. It is the ONLY natural object that can sustain both positive and negative forces at the same time, the next object that does that is the Earth itself.

The Spin, (and) more of the Why:

The visible re-representation of a magnetic motion force (in a given direction) within the body of a magnetic is derived from the internal construct of two opposing forces of negative and positive at a ratio of 1:1.2:1.



Many have seen this symbol, some refer to the symbol as the “Christian fish”, (or) as the “Christian faith”; To now view the fish from a different angle and perspective; that of a time event with motion (inertia) or spin at a ratio of 1.1:2:1 results the two curves of the MSSR, though the MSSR is normally view in a linear condition, the world is not a linear state, so to apply the correct angle and perspective to the MSSR result in the image below.



The above represents a time event of the inertia force of ME motion with a displacement of 1:1.2:1 of itself, the blue represents the positive and the red the negative; when the two are overlaid on each other the FISH symbol is produced, and to add a little color:



It can be seen that the “tail-end” of the blue is to the north and the tail end of the red is to the south, with a displacement of 1:1.2:1 of itself. Stacking magnets (or) allowing them to come together results in:



This is an infinitive (OPEN-ENED) condition; it can also be expressed as “ $E=mc^2$ ” as it goes on forever and nothing comes from it (but sticking two or more magnets together). That’s what people wanted you to think and believe: “Magnets do shit, but through enough energy at them and they will make a useful thing called electricity [!]”. I’m only the messenger, the teacher, the professor, the guru, a MAN. So, we have a spin (within a magnet), a spin within a molecule, a spin within an atom, and spin within the very construct of the smallest part of any atomic construct.

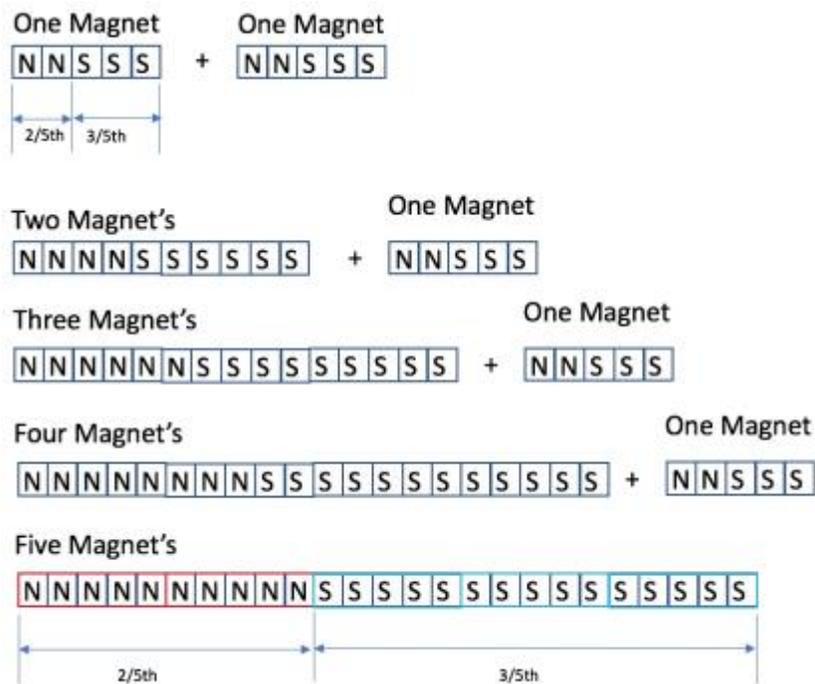
The spin seems to be an endless condition of “nothingness” as Mr. “E” quiet WRONGLY concocted: ($E=mc^2$), when in fact it has been proven time and time again that $\Pi > \infty$ produces far more power and energy than $E=mc^2$ will ever do. $\Pi > \infty$ is a COLD FUSION state of Perpetual Energy that relies on the proven fact of the perpetual imbalance of two magnetic forces at a ratio of 1:1.2:1 of itself. Nothing more than that.

So, the where, the how and the why has been discussed; Putting them together results in “Magnets, when placed into a forced attraction create nothing but itself amplified by itself, ($e=mc^2$); but when two or more are place in an attraction state of less than 1/5 of itself the inertia state MUST move in accordance with the MSSR and the ME state of plus and minus of the inertia state”. To represent this as a simple graphic let’s take the two fish above and change how they are place into attraction.



The magneto inertia condition of attraction remains valid, but now the inertia state becomes accumulative upon itself, a state of perpetual inertia motion at the magnet atomic level; that means the ion transfer between one atomic structure to the next, and the next is accelerated at a rate on 1/5 of its own inertia state; also known as MIA (Magnetic Inertia Acceleration), it is a condition that is infinitive upon itself; it means that the two magnets being configure for two polar conditions in an opposing but asymmetric and orthogonal state, creates internal motion at the atomic level; this is best represented as “Propeller Axial Motion” or PAM: It can be seen that one “ion” from one magnetic field is “seduced” to the next magnetic field, through itself and re-seduced on the opposing axis that is orthogonal to itself forming an asymmetric loop about its own common axis.

Though, only “TWO” magnets have been used, it is possible to use many more; the more that are used the more complex the geometry of the magnetic composite is formed. To just do one more example, that of five magnets shows the genuine ability of “extracting” something from nothing and more:

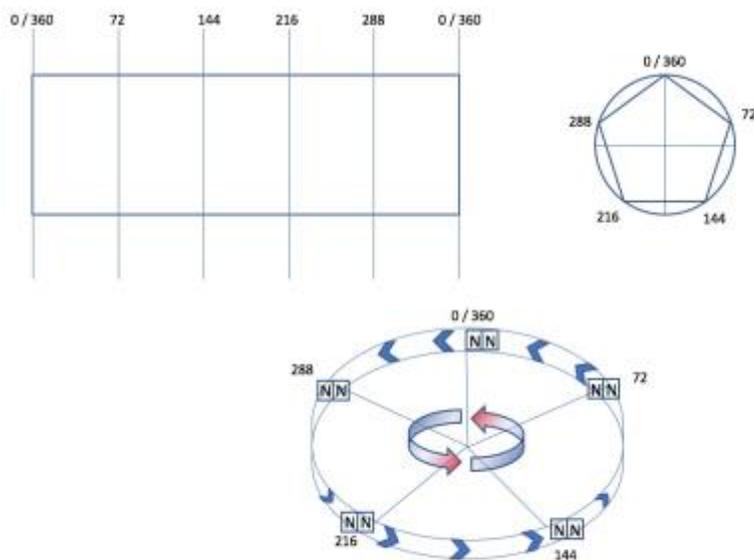


The above drawing is broken down into five lines.

- (1). One magnet of (2/5 and 3/5) of itself plus another identical magnet.
- (2). One magnet of (4/5 and 6/5) of itself plus another identical magnet.
- (3). One magnet of (6/5 and 9/5) of itself plus another identical magnet.
- (4) One magnet of (8/5 and 12/5) of itself plus another identical magnet.
- (5) One magnet of (10/5 and 15/5) of itself.

Within line five is the FIRST time when an original WHOLE magnet becomes one of itself, it is no longer part north or part south, and it can be seen that the whole set of five magnets of one magnet is $2/5$ and $3/5$ of itself. Or 1:1.2:1 of itself.

At this time, all magnets have been displayed and described as a linear condition (or) an open-ended condition; Unity is expressed a closed loop of “everything”, therefore to close the loop on a magnet, in partially five magnets. If every magnet want to be part of the next, but are in a loop, it results in a permeant state of magneto imbalance. The imbalance is a displacement of infinity itself. As within the geometric shape of a circle, a loop there is no start and no end, just an infinite set of points, and in the case of five magnets the infinite set of points is at the atomic level of the magnetic nucleic spin. As the spin moves at the speed of infinity [!] at a ratio of $2/5$ and $3/5$ in either a clockwise or anticlockwise direction there is a $1/5$ motion in one direction that is greater than infinity itself!

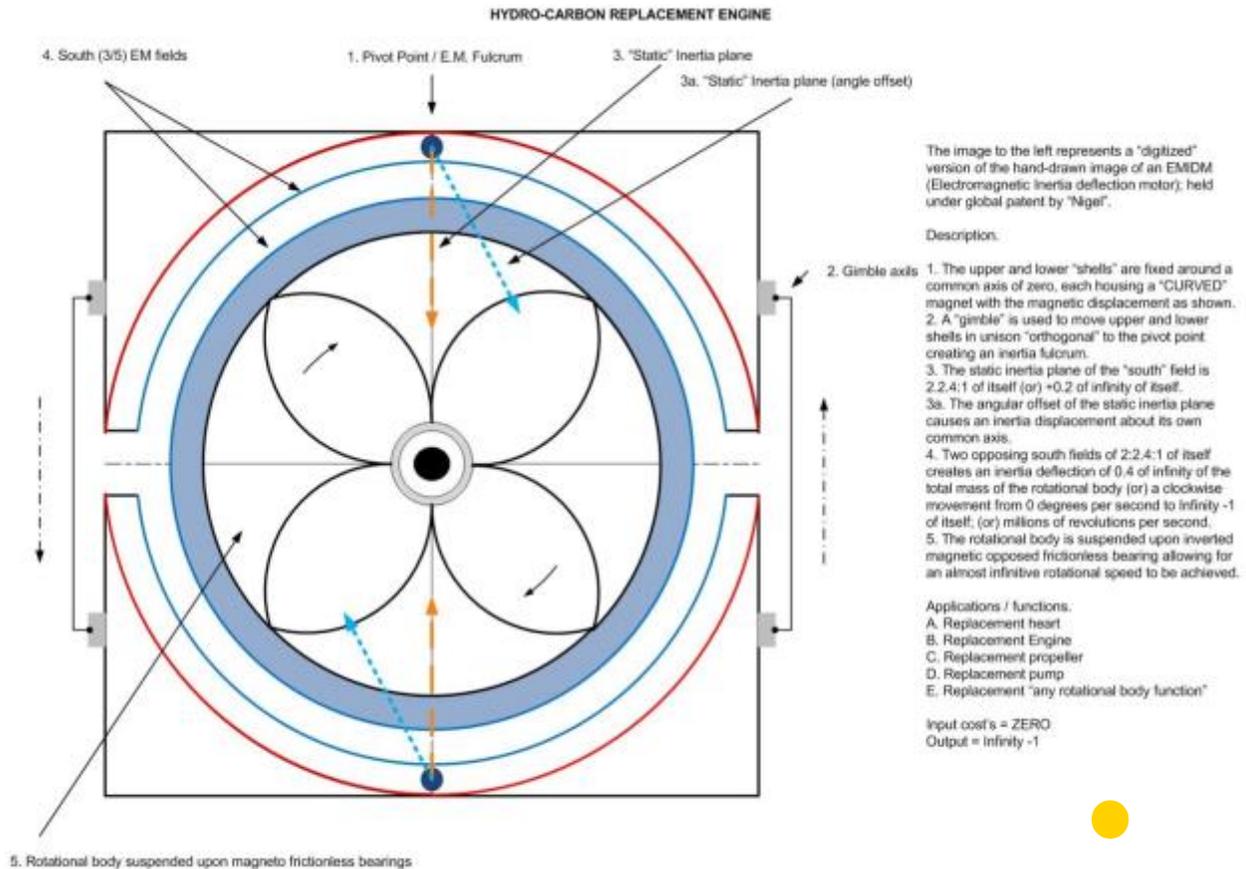


FIVE inter connected magnets, each formed from five parts of itself, that as $2/5^{\text{th}}$ and $3/5^{\text{th}}$ of itself; Forming ONE of itself (ONE Magnet). This is a state of infinite instability within the atomic structure of each magnet forcing a state of Electro Magnetic Transposition (EMT) where the atomic movement is at the speed of infinity plus $1/5^{\text{th}}$. Time within the magnet no longer matter's, as time within the five magnets is infinity plus a $1/5^{\text{th}}$. Therefore, Space and Time are no long linked, space becomes the moving part of the equation and time is totally irrelevant to the event itself, forming a fundamental and visual correction to $E=mc^2$ and the Special relativity theory of one Mr. Albert Einstein, resulting in $\Pi > \infty$, the universal state of Unity.

Magnetic Energy (times) Inertia squared equals energy.

$$ME * I^2 = E$$

Unity is not about making something from nothing, it is about using something you cannot see to make something you can. It is now known that the magnetic ratio is 1:1.2:1 of itself.



The above drawing is a fully functional model prototype, for a linear motor. The motor will run "forever" with a continual inertia output "forever", the final drive from this motor can power "anything", a car, a truck, a propeller and even another electrical generator. The device can be made as small and technically manufacture-able and likewise as big as necessary. It can power a pace maker, it can power a ship, it can power a house, or a hospital, school or a whole country.

The how and the why.

It is now known that two magnetic devices offer an imbalance of 1:1.2:1 or 0.2 of something. That 0,2 is a kinetic force of infinite proportions, and it does not like being near another force of the same type; This is exemplified as South to South, and North to North (or) ++ and --, conditions of repulsion.

Working on the greater force, that of 1.2. Two times 1.2 is 2.4 of something, that is a lot of something that can be used to power something. If force "A" repels force "B" by a factor of itself (1.2) and the

force is the power of infinity times two; that results in twice the infinite force in a given direction for ever.

By utilizing the principle of an EMACS at 125° from the inertia plane will enhance force of 1.2 into a given direction. To now take a “circle” and make the surface of a circle “south” facing but at 45° to the surface, (or to place magnets at an angle of 45° to the tangent of the circumference of the circle); and to now make another circle with another set of magnets but at minus -45° result in a 90° EMACS inertia collision between the inner ring and the outer ring, (as shown above).

If the outer ring is fixed or stationary and the inner ring is a body in motion; the two opposing forces will push against each other. This is the force of the inertia plane of one ring forcing against the inertia plane of the second ring, a release of stored kinetic energy or $(IP+IP) = KE$. This will only work if one is fix and one is variable (or in motion). Therefore $(IP_f + IP_v) = KE$. The Kinetic energy that is release is transferred to the body in motion, this can be a shaft that turns a motor or a generator or other man-made device.

To now “quantify” the product output of $IP_f + IP_v = KE$ where IP_f and IP_v must be given a working value. For the point of demonstration, it will be deemed that each magnetic body has a South inertia force of 10Kg, the inner ring will have 10 magnets at 36° intervals “cambered” at 45° to the tangent of the circumference of the surface of the inner circle; that now as a collective inner kinetic force of 100kg for the inner ring, and for the outer-ring there will be 11 magnets at 32.7° intervals, and cambered at -45° to the tangent of the outer circumference of the circle. The result is $100Kg + 110kg = 210kg$ at (KE). That is 210Kg of continuous rotational force. (More than enough to drive a motor). The next point to investigate is the rotational speed of movement. As each magnet is in opposition to itself and its adjacent magnet, and the magnetic force being applied is infinite, the rotational force is also infinite and will need to be governed, else dis-integration of the device will occur. This is achieved by the use of an angular gimbal (Ag); where the Ag is +/- 45° of the outer magnets. This allow the outer magnets to move in an arc of 90° from -45° to +45°. As the starting axis of the outer magnet was 45° it allows for a STOP motion position to be incorporated into the gimbal action, and -45° + -45° is a -90° or a magnetic “null” or a STOP position; it also allows for a reverse motion to be incorporated into the design.

The full description of this device is a “Variable Geometry Axial Kinetic Linear Motor”.

Variable as in -45° to 45°, Geometry is its construct, axial is it motion, Kinetic is its force, Linear is its direction, and Motor is its function. (V.G.A. K.L.M), there is a stable variant for a fixed site, that would be change “Variable” to “Fixed” or (F.G.A. K.L.M). Both fixed and variable modes are “version” iterations thus pre-fixes to an K.L.M. The base function is known as “MILK”, Magnetically Induced Linear Kinetics. (or) just “MILK” KLM is a milking process.

$E = Me$ & $I = MILK : KLM$.

Energy equals Magnetic Energy and Inertia equals Magnetically Induced Linear Kinetics via a Kinetic Linear Motor.

Once again, it can be seen that the common “Unity” forces come into play; The product being “E” Energy, the function being “ME”, Magnetic Energy, and “I” Inertia. At no time did Mass, the speed of

light "C" Constant or $3 \times 10^8 \text{m/s}$ constitute any part in the production of the Energy. Thus, once again it shows the $E=mc^2$ is no longer a viable power equation.

KLM's can be made as small as necessary, and when addressing small, it can be to the milli-metric size, a device of such precision, so small that it can fix into the cornea of an eye without causing infection or irritation to the most delicate of optics. The micro KLM will have continuous power, more than enough to power an automatic or variable focal lens, a lens that would never need further optical correction. The Optical KLM device would be capable of instant auto focus from 0.1 meters to infinity, in the same way as a modern digital camera. Adaptive "lens replacement" will enable wider spectral vision, infrared, visible, and ultra violet, or organic optical augmentation. It is not impossible, as each and every one of the technologies listed already exist today; the only part missing is the KLM device itself.

Prototype documentation is a secondary subordinate document held in my possession, and available for viewing on request.

The micro KLM is not limited to optic's, as the size increases so does the performance factor, power output, and functional ability. The second size or second generation of the KLM is 5mm x 5mm x 2mm; This device is design for the universal translating ear piece.

The construction of a KLM (Kinetic Linear Motor).

Utilizing the known facts of $E = Me$ & $I = MILK$: KLM.

(Energy equals Magnetic Energy and Inertia equals Magnetically Induced Linear Kinetics via a Kinetic Linear Motor.)

It is now possible to construct a KLM device, and once again, to use “nominal figures for each of representation”, the description is as follows.

It is known that moving a magnet within a copper wire field produces “electricity”. It is also known that to “move” the magnet, energy must be required, (conservation of energy - Newton). We also know that two opposing magnets repel each other, and we also know that there is a magneto discrepancy of 1:1.2 of itself in favor of south. Nothing new so far.

When two magnets are placed south to south, the two inertia planes are in constant state of opposition to each other, and is exemplified as “>”. They want to repel each other to a point of infinity (∞).

When two rings are constructed as an interactive pair, an outer ring and an inner ring; Where the (outer ring) is constructed of eight magnets, all pointing south inwards, and inclined on an angle of -45° , exemplified as “/>”. The result is 8 magnets at 45° radial positioning at a -45° tangent to the radial state; All eight magnets pointing “/>” (right and down).

The inner ring would have the minimum possible working distance between the inner surface of the outer ring and the outer surface of the inner ring (about 1mm), the inner ring would contain SEVEN magnets set at 51.42° of radial separation, and angled at $+45^\circ$ or looking “</” (left and up).

There is no possibility of the two sets of magnetic fields balancing as there is an imbalance of one, ($8 - 7 = 1 (+1)$). The plus one is in all planes of inertia of infinity or $xyz+1$ in a radial, but linear state; The result is that the inner ring magnetic inertia will push against the outer rings magnetic inertia; Thus, creation an infinite rotational motion, (*with no input of energy what so ever*); $E=mc^2$ fails again along with the conservation of energy and matter, that also fails (itself), as the device creates energy from two static inertia planes.

Having established “motion” from the inner ring (via) the combined inertia planes; To now apply a copper winding to the outer ring, (*just like a normal electric motor*), the magnetic field effect between the two inertia planes and the movement of the inner ring will generate electricity, (against that of the conservation of mass and energy and of $E=mc^2$).

To construct this device, as exemplified above; a set of “starting” or “working” sizes would be:

- (1). The outer ring would be 60mm outer diameter and 50mm inner diameter, constructed from magneto inert polymer body.
- (2). The magnet size would be 10mm diameter depth 6mm. (Neodymium 52N) Polar conditioned.
- (3). The Radial Angular offset would be 45°
- (4). The camber angle offset would -45°

- (5). The inner ring would be 45mm outer diameter and, 35mm inner diameter, constructed from magneto inert polymer body.
- (6). The magnet size would be 10mm diameter depth 6mm. (Neodymium 52N) Polar conditioned.
- (7). The Radial offset would be 51.42°
- (8). The camber angle offset $+45^\circ$.
- (9). The copper winding of the outer ring would to a depth of 2mm (as many windings as possible).
- (10). The two open ends of the copper winding will form the plus and minus of the energy generation.

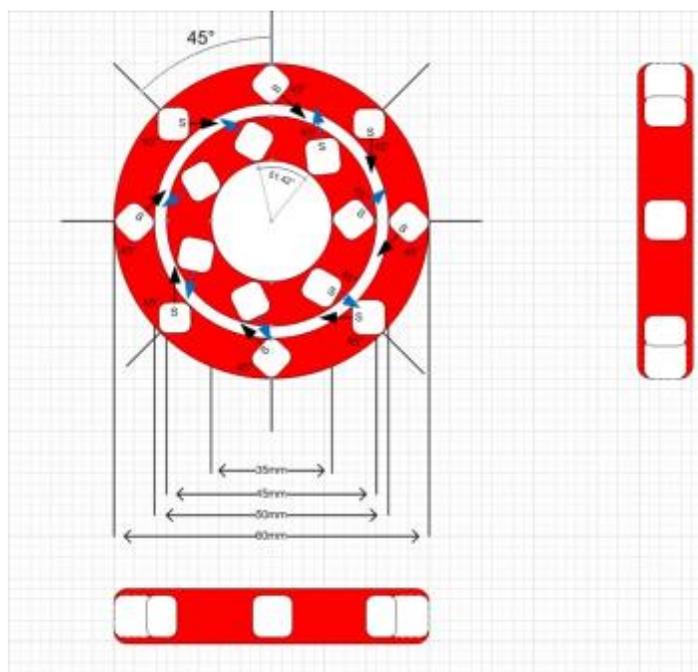
Resulting in a silent motor. The motor will run forever, the power output will depend on the number of windings and the speed of the rotation.

The angular offsets of -45° to 45° will determine the minimum speed of the rotation.

Having establish “axial” motion in the rotation of the inner ring; Where the motion and inducement effects reflect upon the outer rings magnetic field. It is known that copper wire wound around a magnet, when placed in motion creates electricity.

Therefore, the interaction of both magnetic fields of the inner and outer rings produces an induced DC current, where the DC voltage is proportional to the number of windings of the copper wire. Though in classic “electrical energy generation” the product output is 110 or 240v A/C at a frequency of 50~60Hz. This is NOT the case within this device. Due to the method of DC generation, (that of counter rotating magnets), the phase is phase ZERO, the frequency is 1.14Hz over 0.85Hz (as a pair). The paired frequencies oscillate against each other resulting in a common output of 0.29Hz or 1/3Hz. The 1/3Hz is a de-interleaved (interpolated) frequency, which, must then be multiplied by the number of frequency receptors within the interactive field (that being the magnets within the outer ring). There are 8 magnets in the out ring with a 0.3Hz de-interleaved harmonic response which results in a common electrical output frequency of 24Hz $((8*3)/1) = 24\text{Hz}$. This produces a constant frequency (proportional voltage) DC conditioned with a resonance frequency of 0.3Hz and a phased frequency of 24Hz.

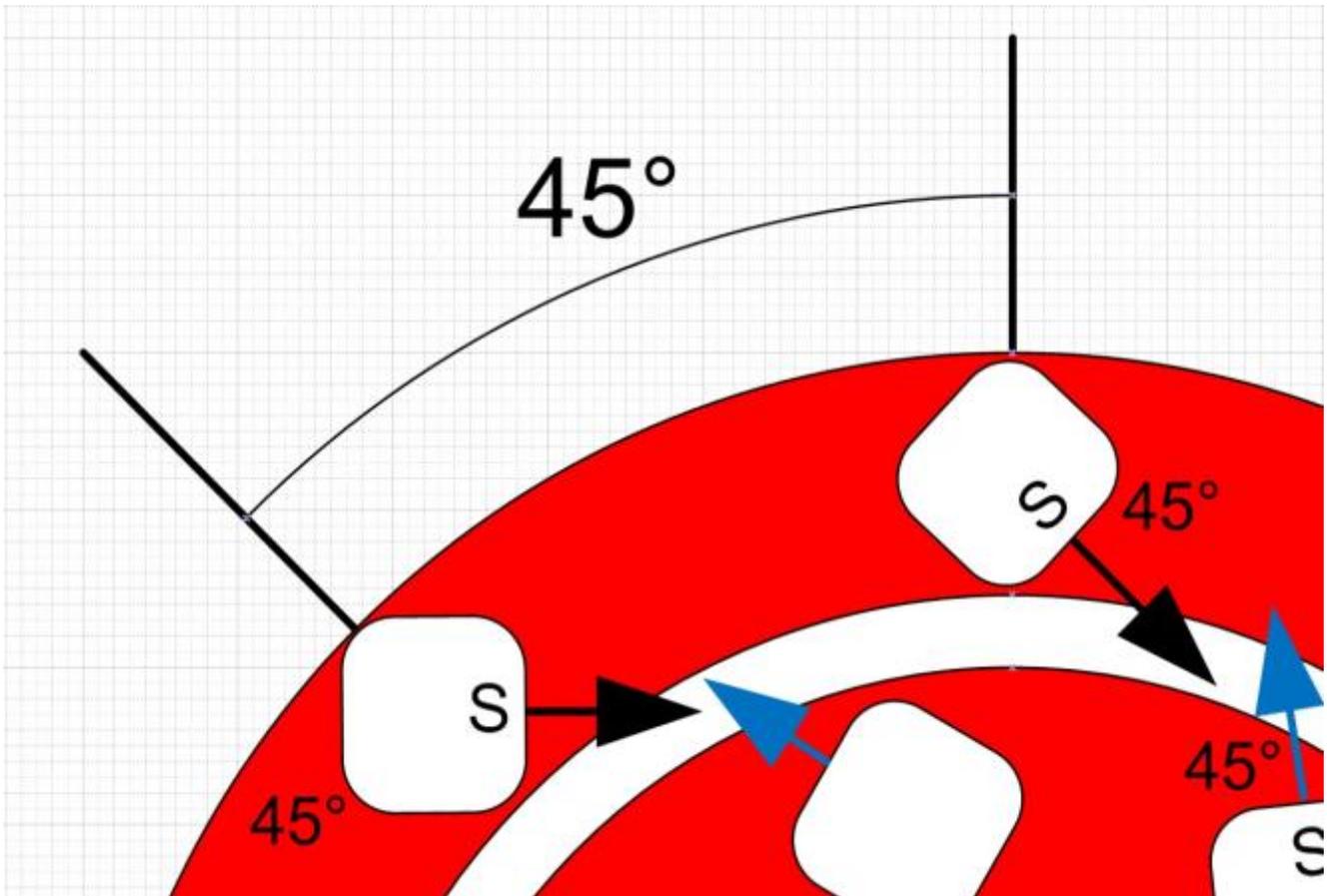
The image below shows the base drawing for a KLM.



To now “dis-assemble” the above drawing and itemize each part; results in a “standing body” and a “moving body”. The outer is the fix (or) standing body, and the inner is the moving part.

It can be seen that the outer body is made from a magneto inert material such as Polypropylene; a material that is highly versatile, very hard wearing, and easily workable. The reader is reminded that that this is a **test base model**, and a final production device would be made from hi-grade Aluminum.

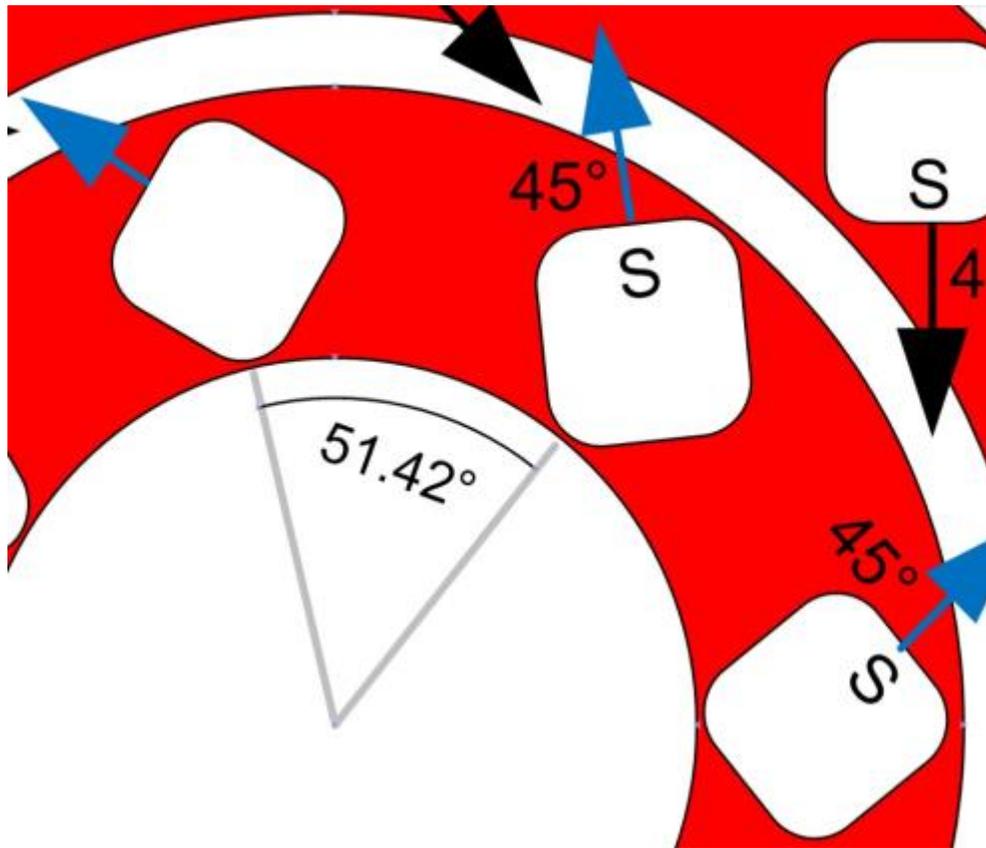
In close detail; (The outer ring)



The magnets are positioned at 45° radial spacing. Eight magnets at 45° equals 360° (a state of infinity upon itself). Each magnet is also inclined at -45° with the South field facing inwards. The magnetic body itself is constructed from “Nickel” coated Neodymium (Type 52N), a very powerful magnet.

All magnets are susceptible to a common force, that of their infinite attraction and repulsion to each of the applied forces. North will always be attracted to South, and both North and South will be repelled against each other to a point of infinity.

To now construct the inner ring as the magnetic reversal of the outer ring; where the construction of the inner ring is as follows:

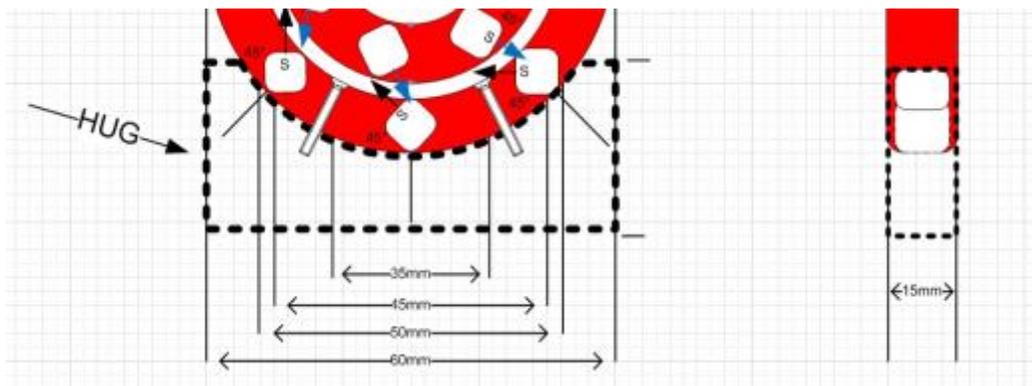


The magnets are positioned at 51.42° radial spacing. Seven magnets at 51.42° equals 360° (a state of infinity upon itself). Each magnet is also inclined at +45° with the South field facing inwards. The magnetic body itself is constructed from “Nickel” coated Neodymium (Type 52N), a very powerful magnet.

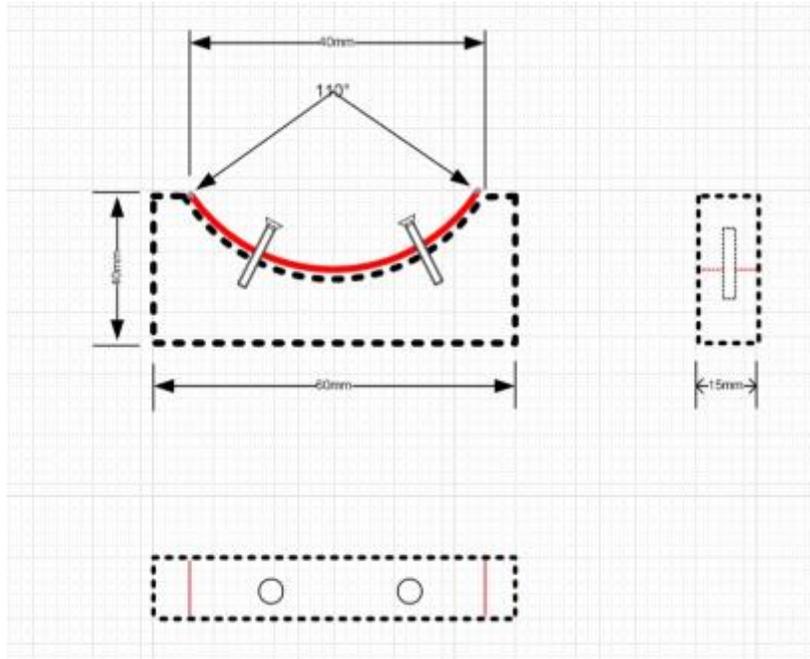
The resultant “opposing” magnetic field is 6.42° against the local inertia plane of either magnetic inertia plane or 56.07° of inertia displacement. One will be forced against the other to a point of infinity. Magneto balance cannot be achieved as there will always be one magneto placing to many, or (8-7 = 1); a reckonable displacement of just under 2/3 of ∞.

Having identified both the static and moving parts, and each sub-component of each of the listed parts. It is now necessary to form a chassis to support the KLM. Surface mounting the KLM within a “HUG” allows for the maximum flexibility of the device.

The “Hug” is for all intense and purpose a “U” shape along the base of the KLM as exemplified below.



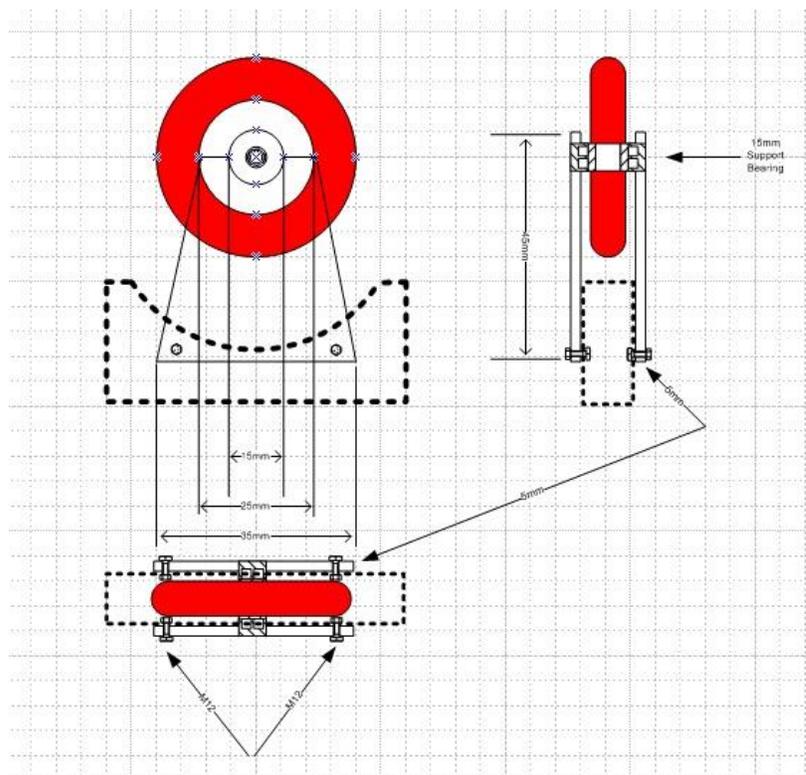
The dimensions and material of the HUG:



Material: Polypropylene
 Dimension: 60 x 40 x 15mm
 Drill points: "Two" (160° and 220°)
 Fixing: Threaded 20mm x 6mm \varnothing
 Material: "Magneto Inert (Brass)".

The "HUG" is the base support for the device, and a rotational support connects the rotational body to the "HUG" and is known as the "Inner Support Housing"

Inner Support Housing
 Material Polypropylene
 Dimension 45 x 35 x 5mm
 Drill point "Four" (+/- 5mm)
 Fixing: Threaded M12 nut and bolt
 Material "Magneto Inert (Brass)".

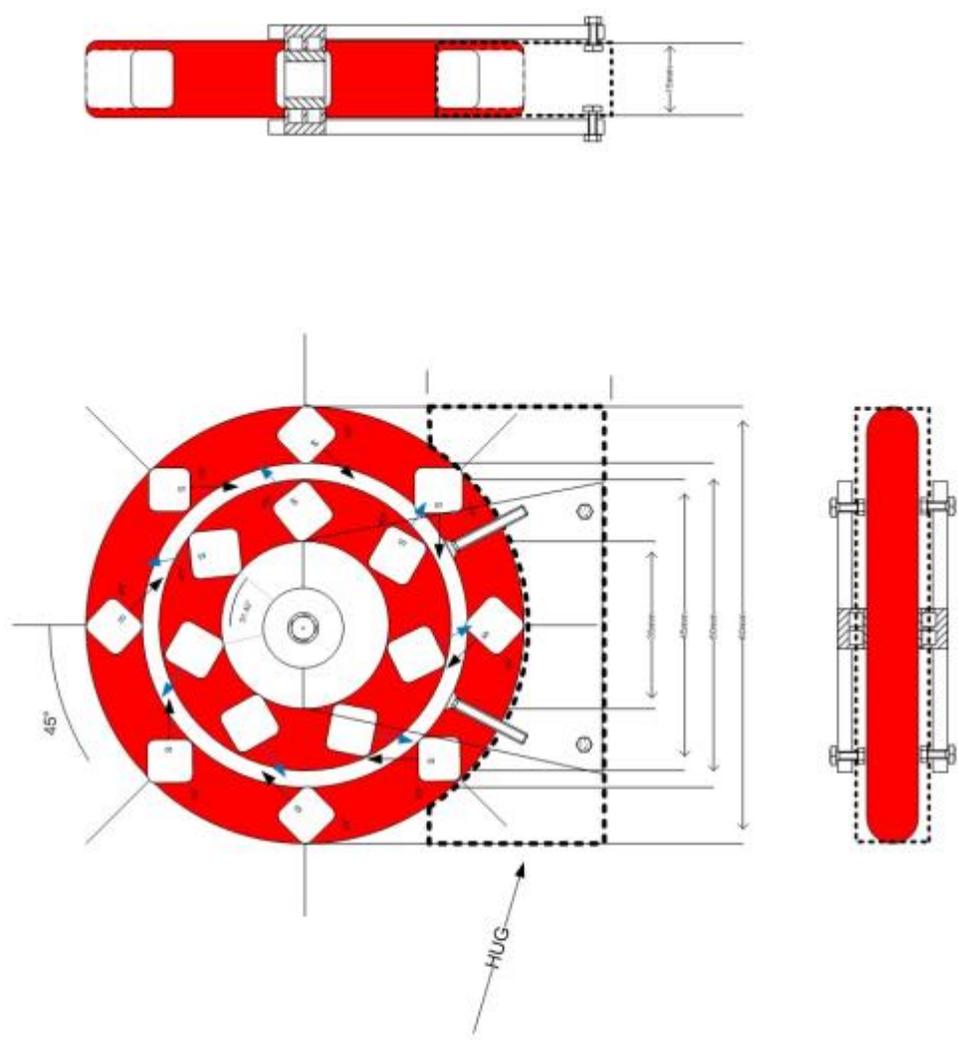


Assembly:

- (1). Construct HUG
- (2). Construct Inner Housing (do not assemble)
- (3). Construct and load Inner Ring
- (4). Construct and load Outer Ring, Add copper wiring
- (5). Mount Inner to Support bearing
- (6). Mount Inner Ring and Support bearing to half of the Inner Housing
- (7). Mount Outer ring to HUB
- (8). Mount Inner Housing back-plane to HUG
- (9). Mount assembly (6) to HUB and Back plane.
- (10). Connect copper terminals to Volt Meter (Check reading).

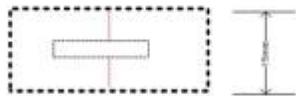
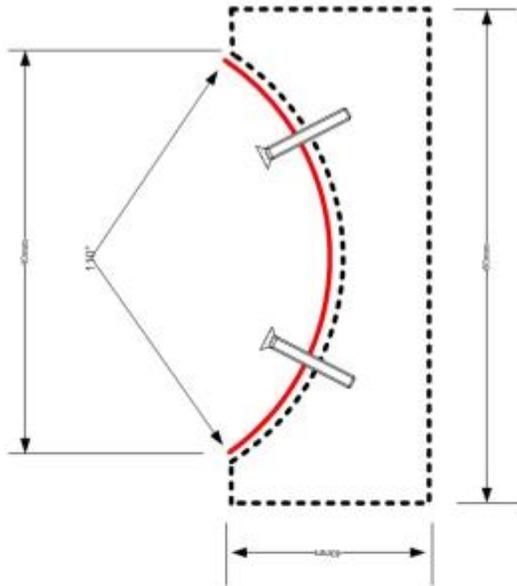
The read / User / Builder is reminded that is a demonstration model for proof of concept. All sizes may be adjusted as necessary to meet the requirements of mounting the KLM. This is a (F.G.A. K.L.M.). To build a V.G.A. K.L.M. for variable motion, additional parts will be required.

K L M – Test model



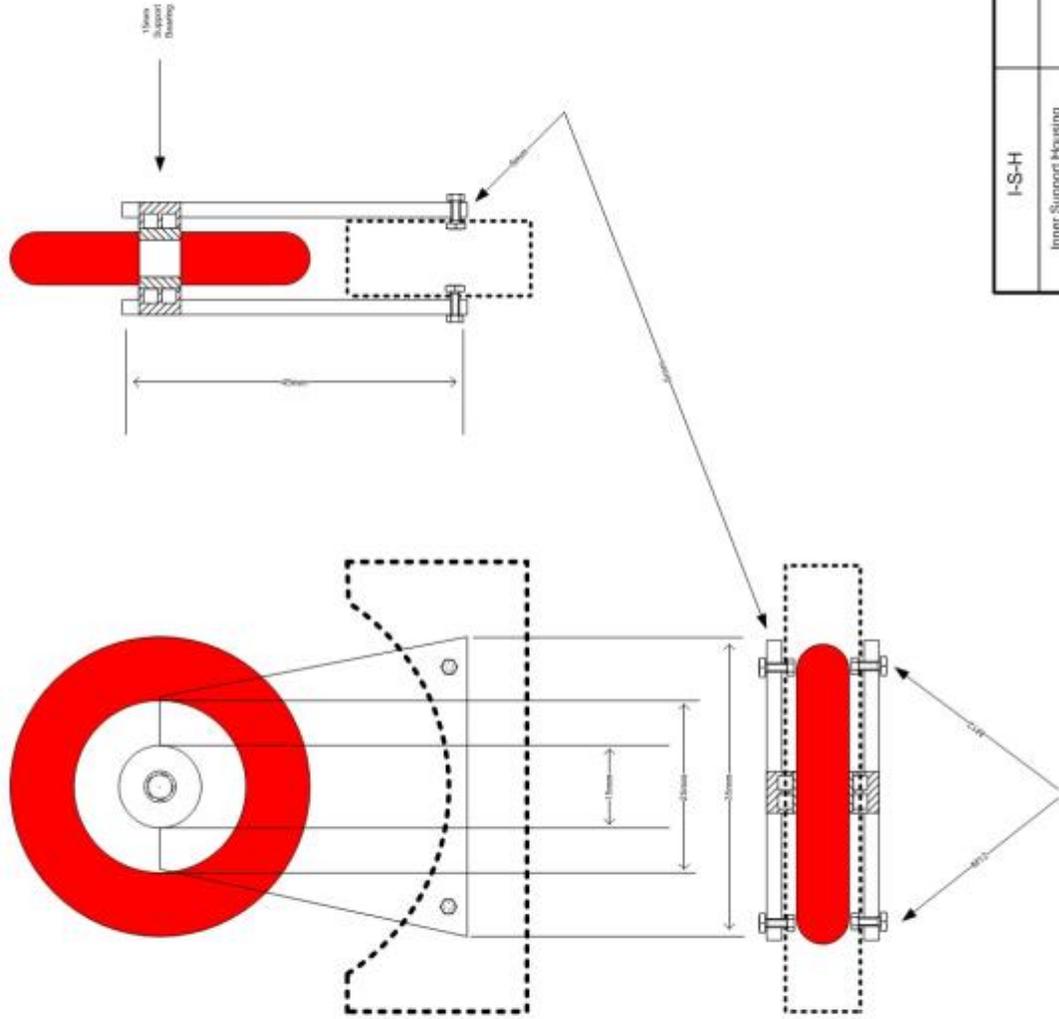
| | | |
|--------------|---------|----------|
| KLM | Plastic | Nigel |
| Base drawing | | 3/4/2017 |

HUG - Chassis

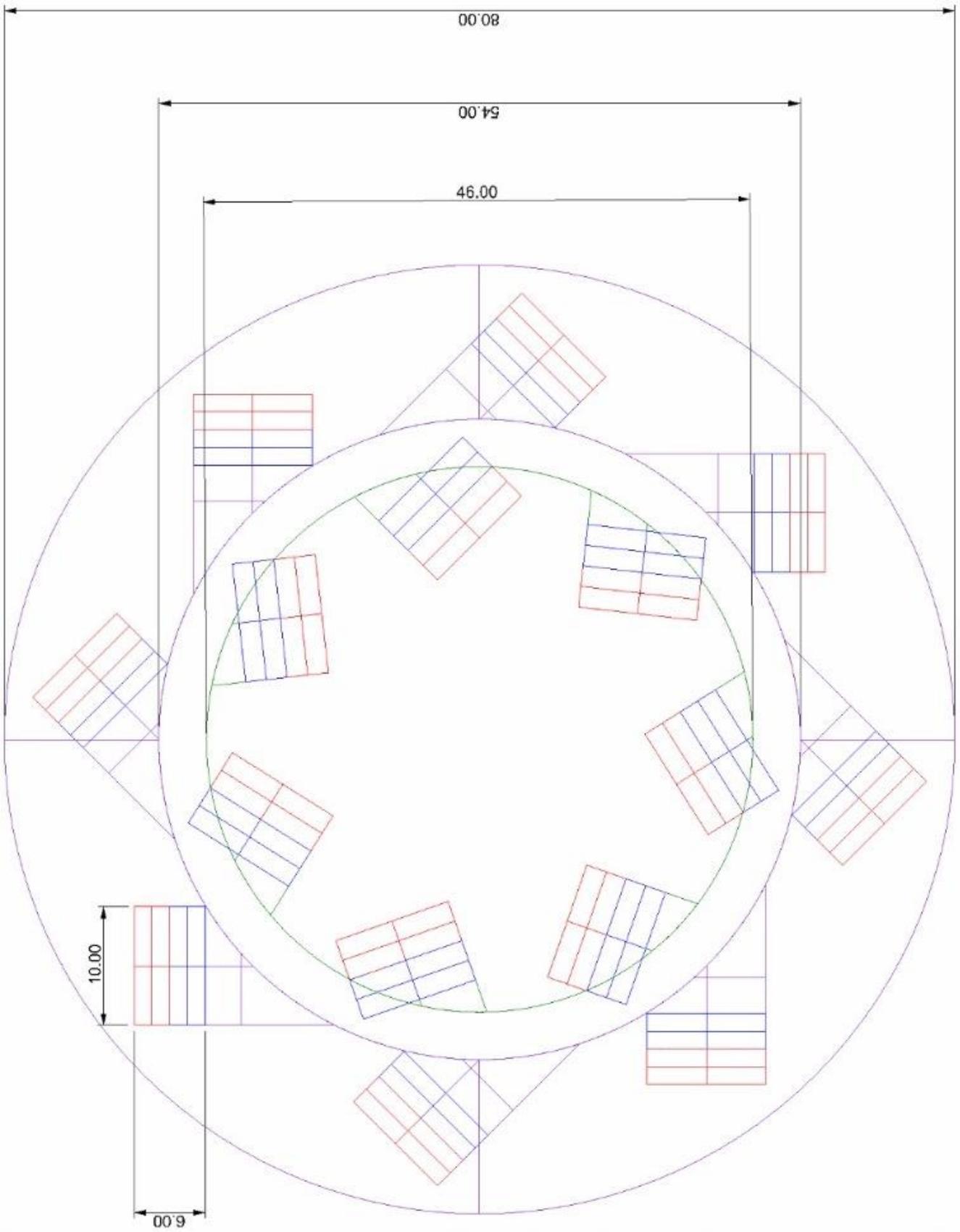


| | | |
|--------------|---------|----------|
| HUG | Plastic | Nigel |
| Base drawing | | 5/4/2017 |

Inner Support Housing

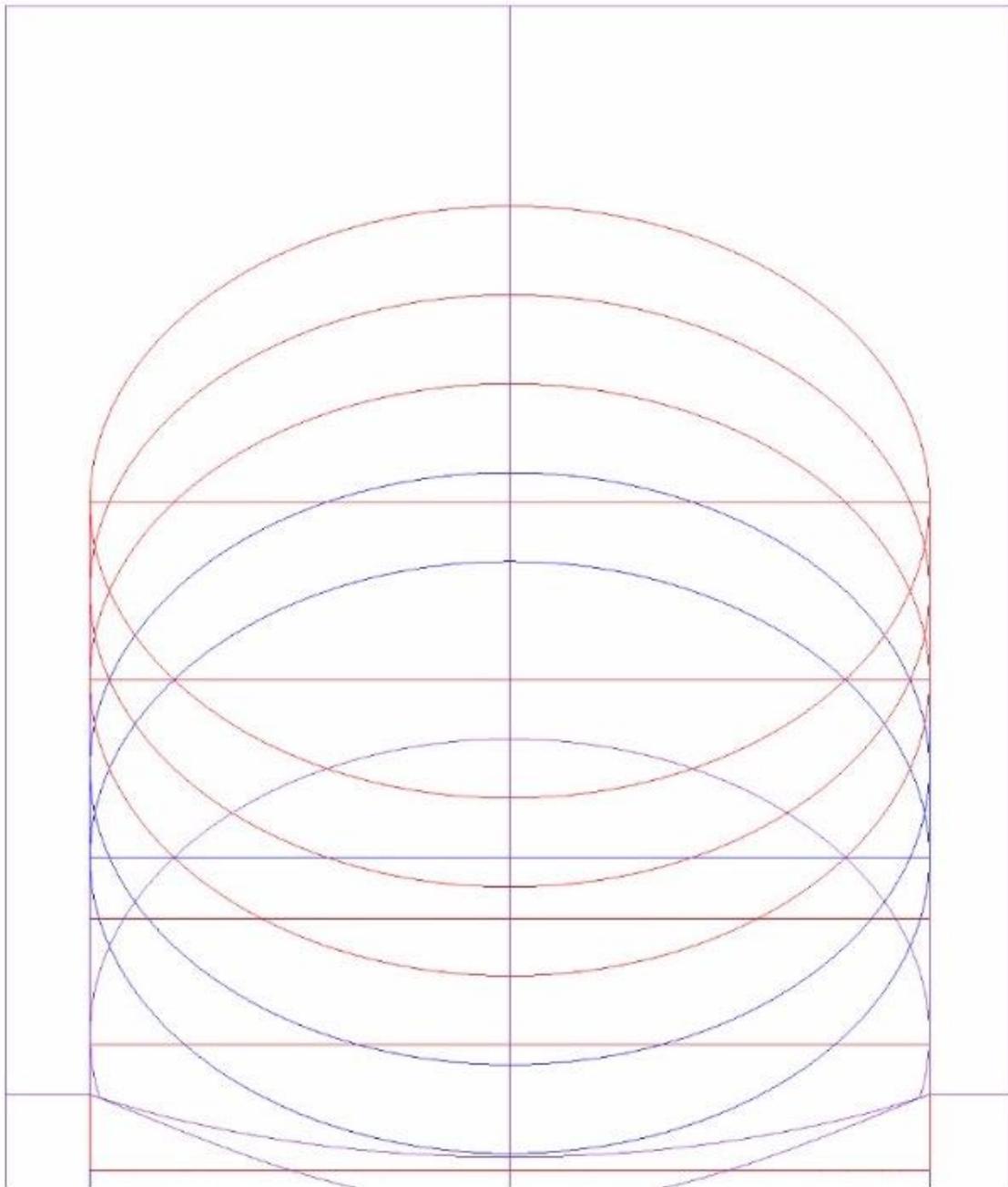


| | | |
|-----------------------|---------|----------|
| I-S-H | Plastic | Nigel |
| Inner Support Housing | | 5/4/2017 |



Dill holes for positioning Magnets

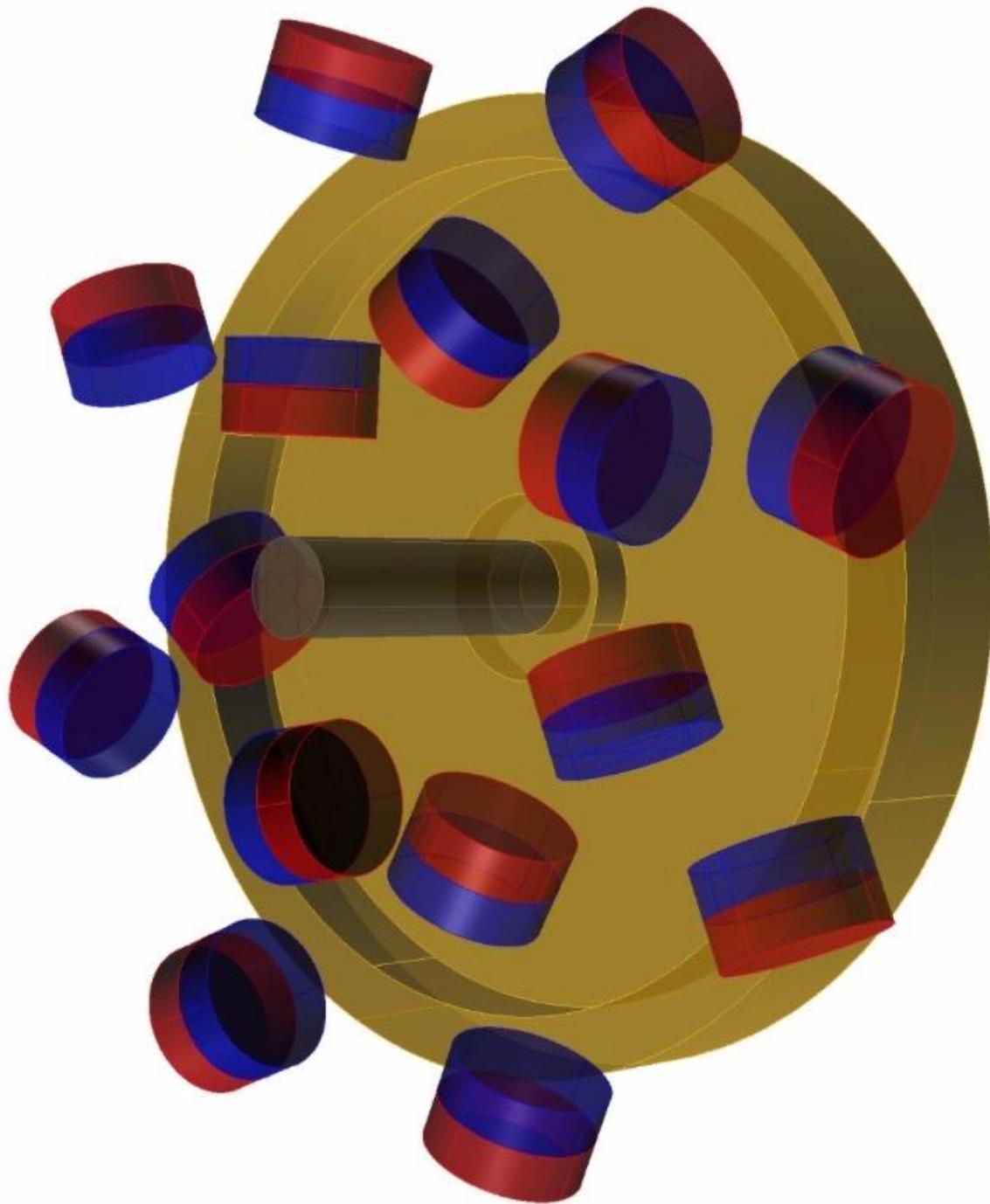
12.00



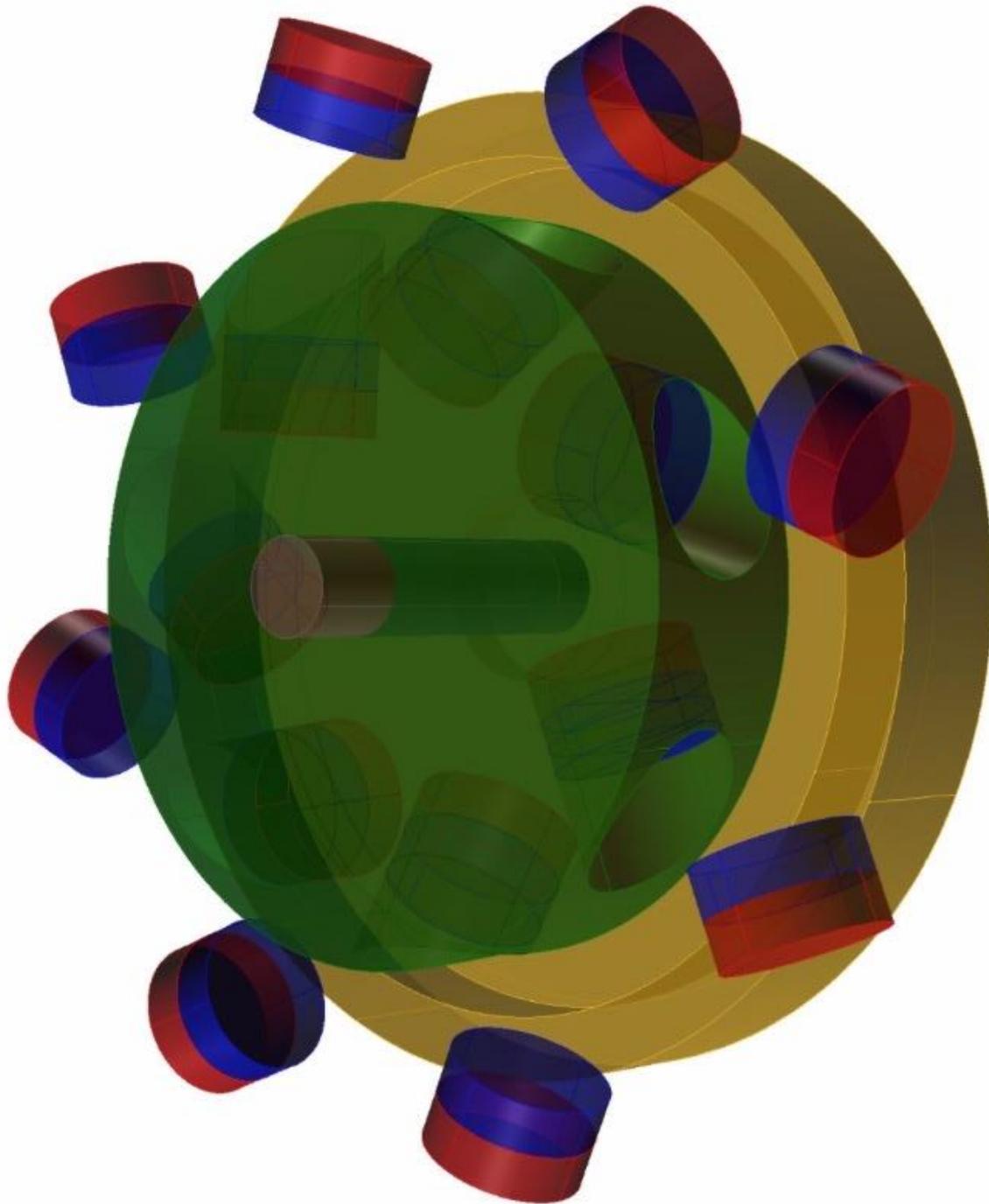
Single Dill hole for Magnet



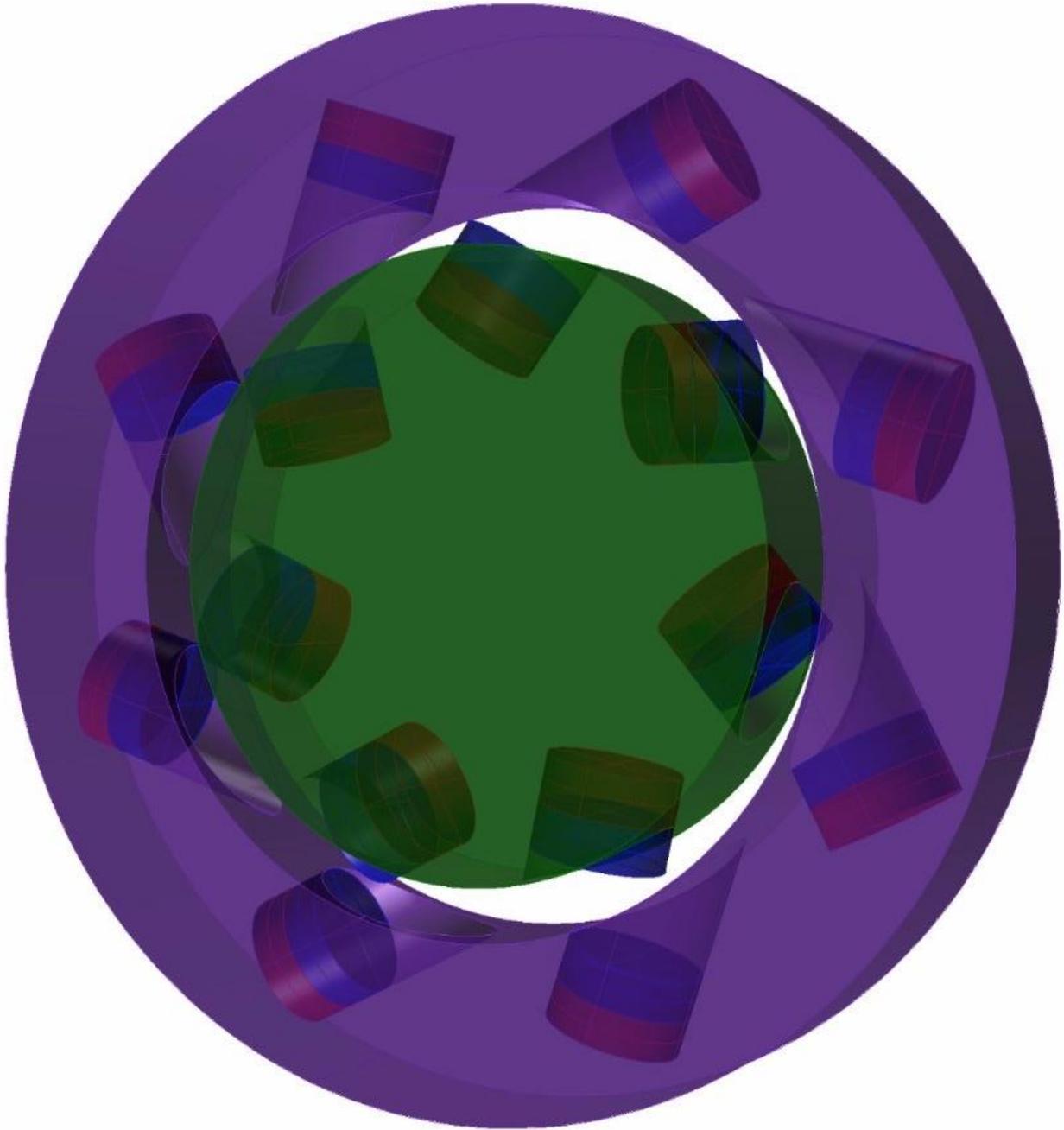
3D View of chassis base



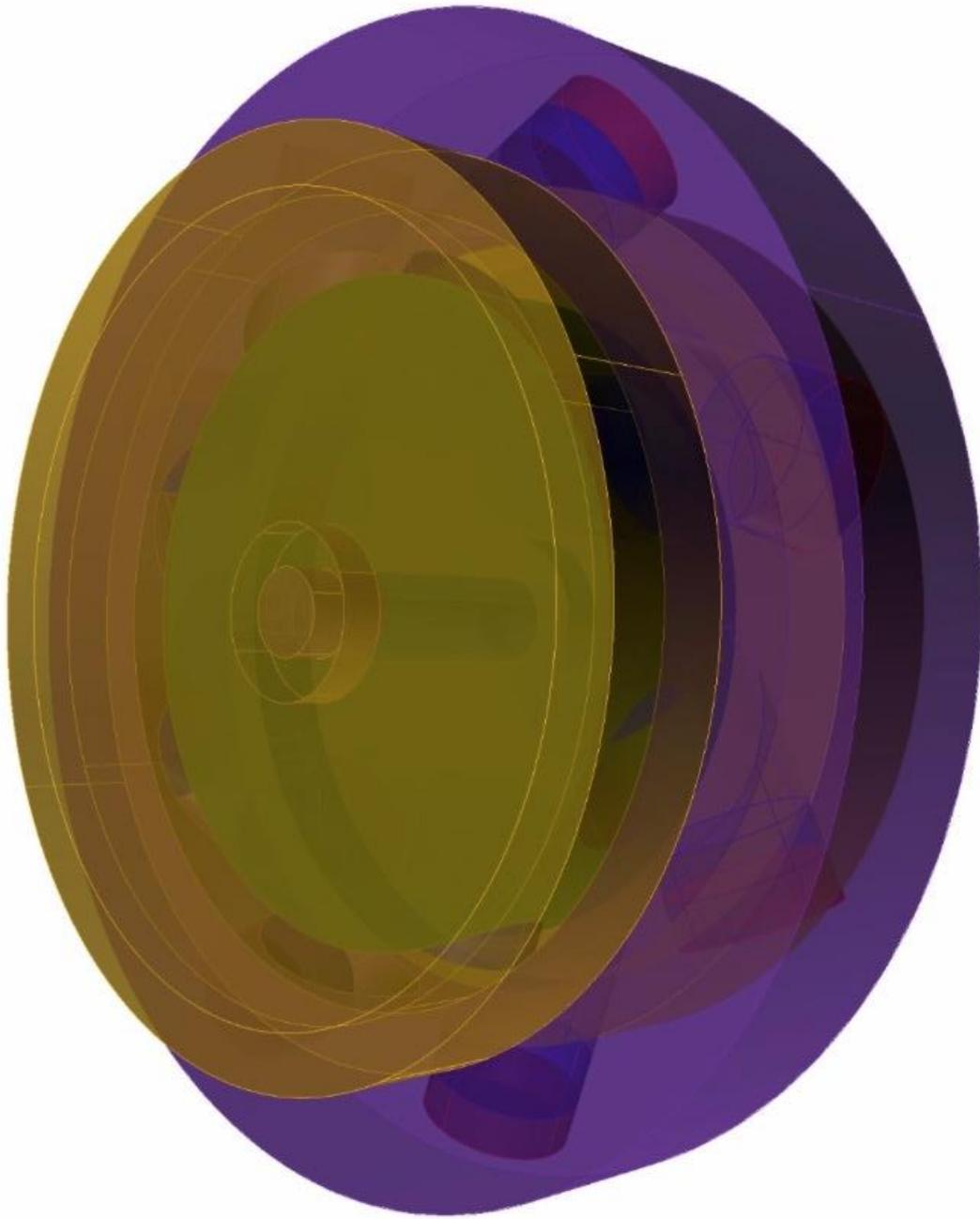
Exploded View of Magnet Positions



Inner ring Mounted to Axil and Magnets Positions



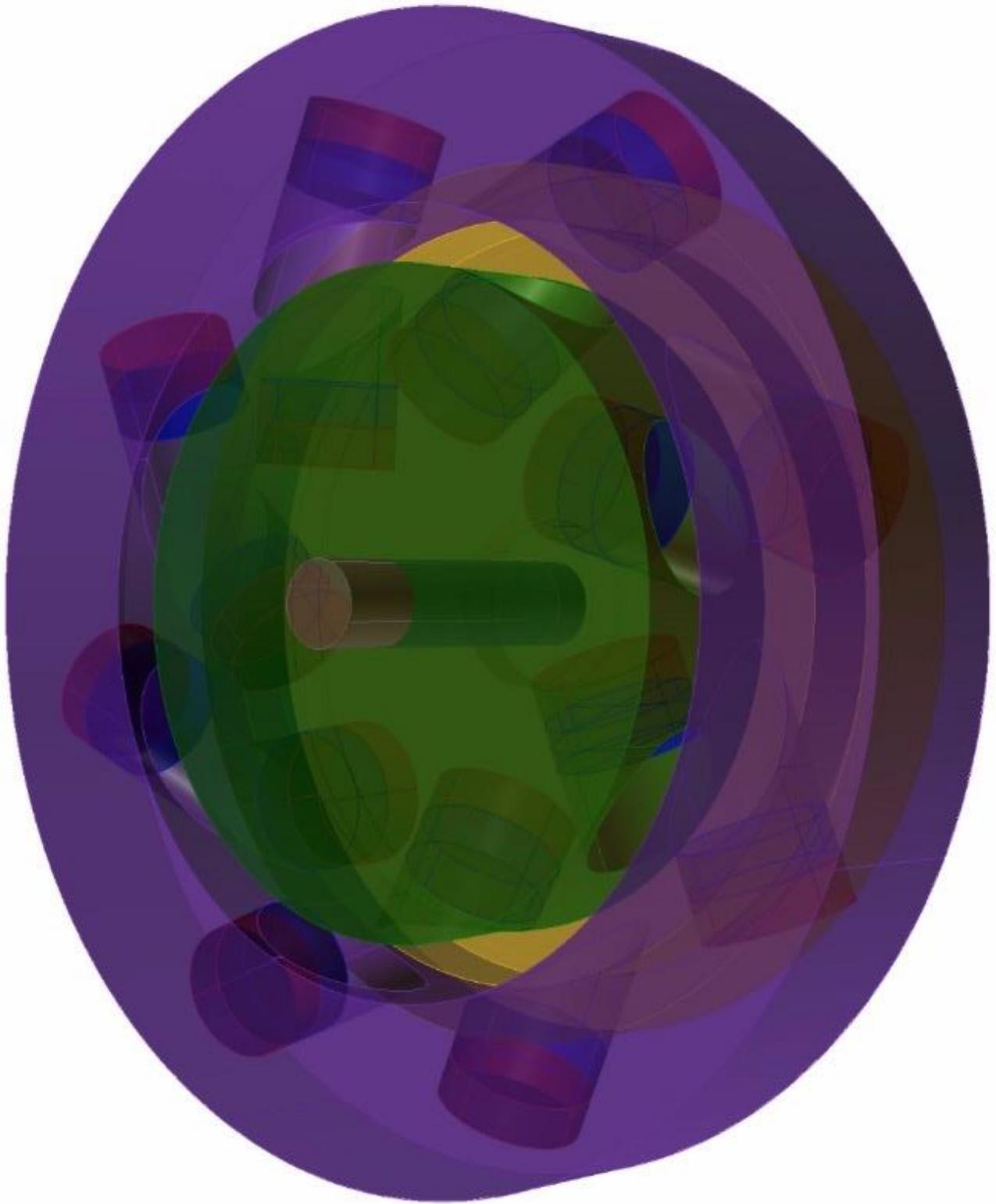
3D View of Chassis ~ (Magnets loaded)



1 Completed Axil Assembly



2Axil Assembly



Sub-Assembly of Axil and Rings

Finalizing the original drawings results in, a “pre-formed” and “pre-printed 3D chassis”. To assist the reader; The parts of the KLM have been color coded for ease of viewing, the colors are “Red” (The actual rotational part of the KLM); “Green” (The static part of the KLM), and “Blue”, (The support housing).

The magnetic body has been reduced in size to 3mm x 6mm Neodymium T52N (Non-coated) magnets; There are “7” (Seven) magnets within the rotational body and “8” (Eight) within the that static part of the KLM.

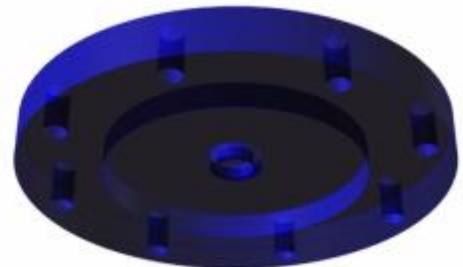
The rotational body:

The inner body of the KLM is made from “high impact” 3D printed Polypropylene. There are “7” bore holes sized at 3mm x 6mm for the placement of the seven Neodymium magnet’s. The magnetic polarity will be “south” facing outwards and set at an angle of -45° to the central axis. There is also a central pivot pin that will act and serve as the central axial.



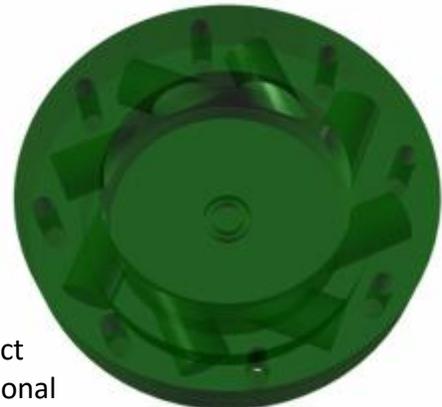
The support housing:

The support housing of the KLM is made from “high impact” 3D printed Polypropylene. There are “8” drill holes set at 45° intervals, each drill hole will be used to hold in place a TWO-PART STUD, the stud will be used to hold the support housing to the static unit.



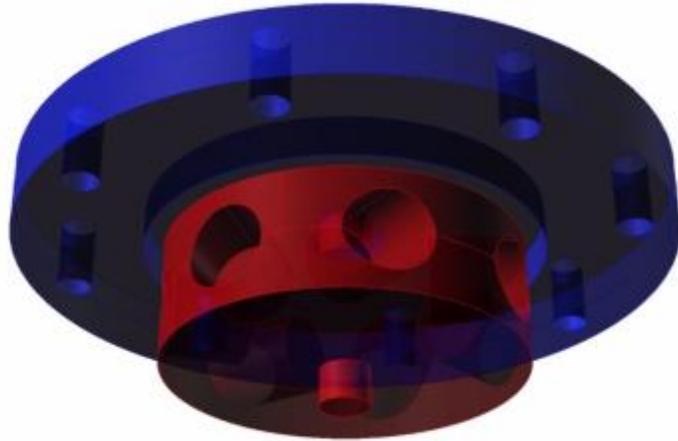
The inner static body:

The inner static body of the KLM is made from “high impact” 3D printed Polypropylene. There are “8” drill holes set at 45° intervals, and “8” bore holes sized at 3mm by 6mm for the placement of the Neodymium magnets, the polarity of the magnets will be “south” facing inwards and set at an angel of -45° to the central axis. There is a “stud” axial located at the center to act and serve as the central rotational pivot point of the internal rotational body. The “8” drill holes align to the “8” drill holes within the support housing.

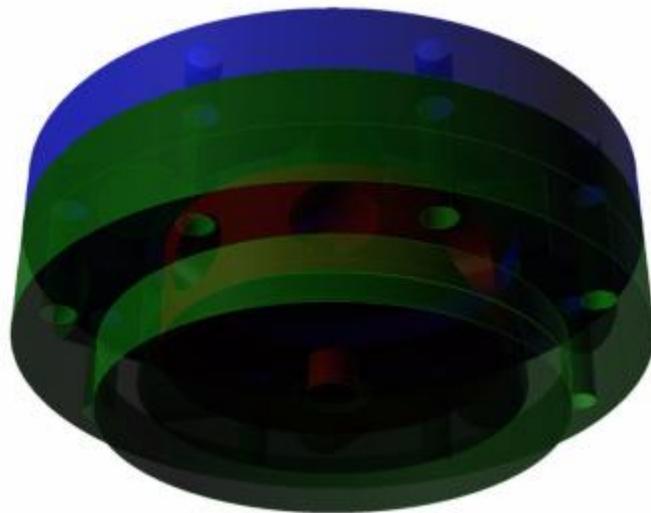


Assembly of the KLM:

Both the inner rotational body, and the static body should be loaded with “7” and “8” Neodymium magnets respectively, taking care to assure the correct polarity of each magnet, [**CAUTION** – *Failure to correctly align the polar fields will result in KLM failure*]. The inner [RED] rotational body is to be placed into the recess within the [BLUE] support housing taking care to align the axial stud as shown below:



Each of the “8” drill holes should be fitted with a “PART-ONE” stud, the PART-ONE stud has a “barb” that inter locks with the PART-TWO stud. The [GREEN] static body of the KLM should be aligned with the “8” “PART-ONE’ studs, and the central axil stud; The “8” PART-TWO stud should then be inserted through the GREEN static body so that they securely mate with PART-ONE studs as shown below.



Having “established” the mechanics of the KLM; The reader is invited to examine the “energy” properties of KLM. It is known that the following exists within the KLM, that is:

1. A magnetic body (Neodymium T52N) non-coated; quantity 15.
2. The magnetic bodies are divided into two sets of distinct fields of South and South.
3. An outer set of eight magnetic bodies @ 45 degree separations.
4. An inner set of seven magnetic bodies @ 51.42 degree separations.
5. Each magnetic body has an inertia state of 1:1.2:1 (South).
6. Two “south” fields under compression produces 0.4 times the inertia plane.
7. The weight of the magnetic body is 3.5 grams.
8. The kinetic “release force” per magnetic pair is assessed @ 1Kg @ 2mm.
9. There are “SEVEN” magnetic pair’s or (7Kg) of stored kinetic energy.
10. The maximum stored energy release occurs within a 6.42-degree window.
11. There are “EIGHT” windows for energy release. (7Kg * 8 Windows = 56Kg)

12. 360 degree's divided by 6.42 equals 56.0747 (or) 56 degrees if de-interleaved kinetic power output.
13. 56Kg / 6.42 degrees = 8.7 Kg per degree of rotation; therefore, maximum output is 8.7*360=3140Kg of kinetic energy per ONE 360 revolution.

Although the above indicates many thousands of kilograms of force is generated, to date it is truly impossible to express the exact amount of force and or power output; this is due to the fact, that as of today there is NO base equation that will calculate the kinetic force of two opposing magnetic bodies within a closed loop of infinity; The closest equation that represents the power output is:

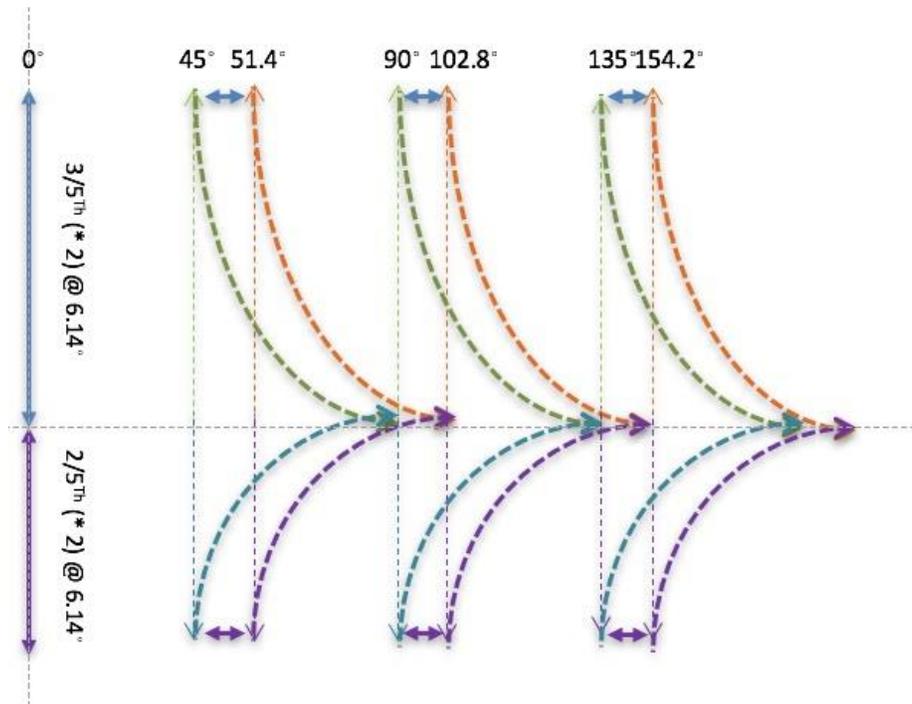
$$\langle \hat{T} \rangle = \left\langle \psi \left| \sum_{i=1}^N \frac{-\hbar^2}{2m_e} \nabla_i^2 \right| \psi \right\rangle = -\frac{\hbar^2}{2m_e} \sum_{i=1}^N \left\langle \psi \left| \nabla_i^2 \right| \psi \right\rangle$$

Written by Mr. Albert Einstein as part of the “general relativity theory”, the above “assumes” the potential kinetic energy of an “electron” within a body or mass; it DOES NOT, HOWEVER, accept or acknowledge the perpetual STORED ENRGY within a magnetic body; And when TWO magnetic bodies are placed in to a permanent state of opposed fields (South to South) the amount of stored energy is commensurate to the magneto compression ratio, that of 1:1.2:1 of itself, or 1.2 * 2 (2.4) in favor of South. A magnetic body has “INFINITE” kinetic energy stored within itself and is only effected by another magnetic inertia plane, or a magneto-pragmatic state. As there is NO magneto-pragmatic state, the only source of energy within a magnet must come from its inertia plane. The plane is infinitive within itself, therefore the power output is infinity to 1 of itself. The above calculation’s results in a power output of 3140Kg of kinetic stored energy and when converted into Joules / Watts, the result is 30792.881 joules per meter (of rotational travel); And when converted to a “useable” energy “Watts” the results is 30792.881 Watts (or) 30.8 KW of usable energy or to round down to 30KW for a mass input of 52.5 grams; a power to weight ratio of 30KW / 0.0525Kg (or) 30,000/0.0525 (or) 571428:1 (or) HALF a MILLION to ONE, (per magnetic field); And, as there are 7 interactive pairs within 8 windows (8/7) = 1.14285 results in a perpetual power to weight ratio of 571428 * 1.14285 = 653060:1 ratio within a kinetic linear motor.

The definition of cold fusion in its most simplistic terms is “more power out than the amount of energy put in”, thus the input was ONE and the output is 653,060; A factor of many hundreds of thousands of times the input power. **A statement of COLD FUSION has been achieved.**

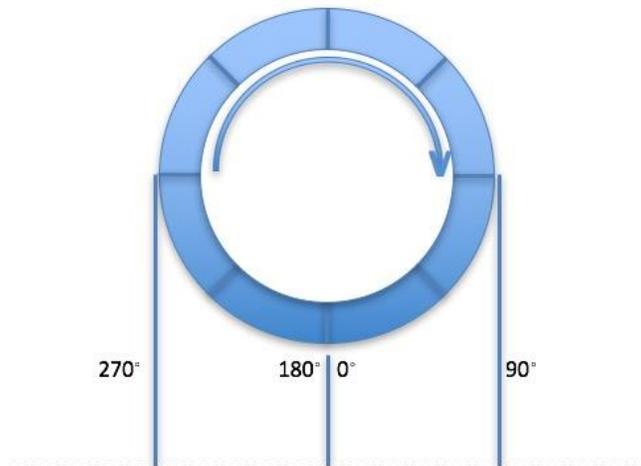
Having the ability to “view” the compressive force of the magnetic fields and their interaction in a linear fashion; BUT, fixed within an infinitive state, (that of a circle) results in, that the magnetic field output, that was liner in its primary polarization as be converted to a TSAPWC, (*The fields as NOT sinusoidal as in AC and NOT flat as in DC or CW, but continual Twin SAW Pairs @ CW. Or (T.S.A.P.C.W)*)

To graphically view the field effects of a TSAPCW it would look not to dissimilar from the image below:



It can be seen, (from the image above), that the “South” magnetic compression fields are “PAIRED”, they are paired at 45° and 51.5°, (but) separated by 45° and 51.5° (*as a cyclic event*). As the inner magnetic field approaches the NEXT opposing field “MAXIMUM” magneto deflection occurs, which then proceeds to reduce in intensity over the next 6.14°. This is also a paired function. The result is a “circular phased modulation with RAMP DOWN @ 6.14° interleaved separation over 45° and 51.5°.

There is a secondary TSAPWC within the “Paired North” fields, but at a much-reduced intensity. To view the magnetic fields within its circular motion event it would look similar to the image below.



Moving from “Theoretical” to “Two dimensional” modeling, to “3D modeling”, to “3D Printed parts” result in the fabrication of a KLM, (in three parts).

1. The outer support housing.
2. The inner rotational body.
3. The outer static body.

Method of assembly:

The three-high impact polypropylene parts are displayed to the right and shown in comparative size to that of a coin, (20mm in diameter). The overall size of the KLM is 80mm in diameter and 20mm thick. Listing the parts (as viewed),

1. The “white” support housing.
2. The “blue” large “static” housing.
3. The “blue” small “rotational” body.
4. A 3mm fixing nut (eight in total)
5. A 25mm fixing bolt (eight in total)
6. One coin for size comparison.

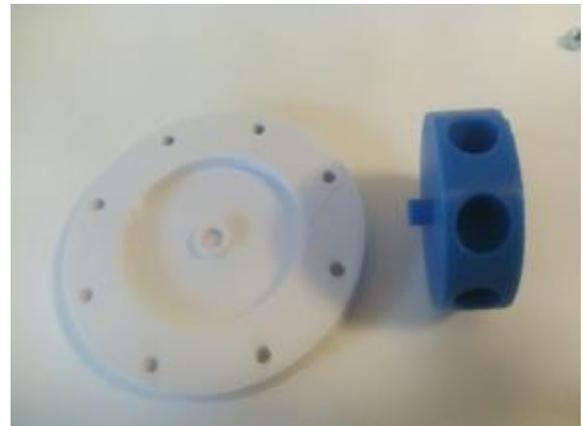


*** It is assumed that the reader “would” have installed the fifteen (15) T52N magnets into the (15) recesses within both the “static housing” and the “rotational body”, making sure to align the magnet’s “SOUTH” fields opposing ($S > < S$).

Rotation body alignment to support housing:

The orientation of the rotational body is displayed to the right; and the reader must take note of the “axil” stud. The axil stud fits into the “white” support housing’s centered axil housing.

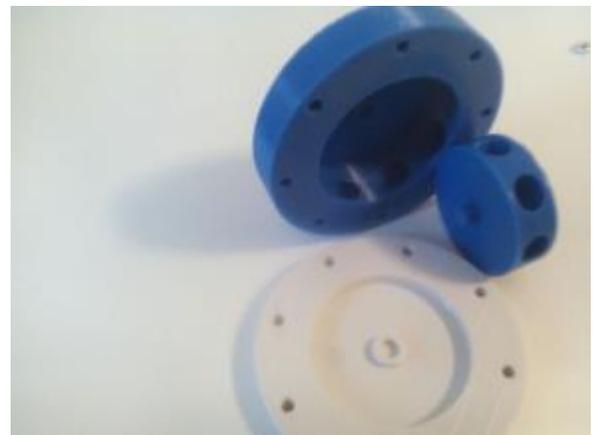
*** The reader is to note that the support housing has a 2mm reses which assists in the alignment of two parts.



KLM parts “perspective” view:

The image to the right allows the reader to view each part in perspective, as to where and how each part is fitted to the next.

*** The read is to note the eight (8) outer drill holes and the meticulous need for precise alignment; failure to correctly align the drill holes in the support housing to that of the static body will result if KLM structural instability resulting in KLM failure.



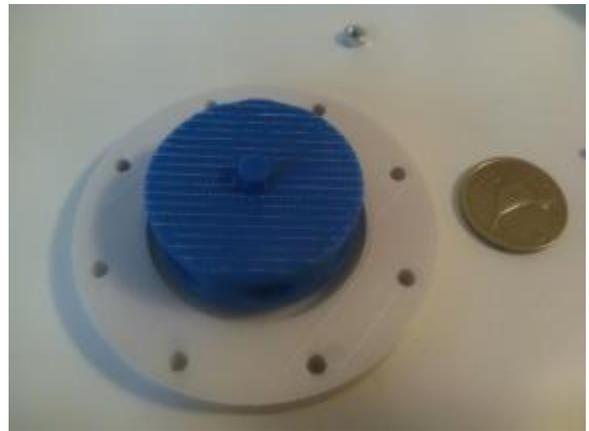
The static body:

The static body has eight (8) internal recesses for the correct angular placement of T52N magnets ($S \times S$). The depth, size, and diameter of the central reses allows for correct alignment of the inner rotational body, noting the central alignment stud for the rotational bodies stud axil.



Assembly 1:

The support housing and inner rotational body fit together as shown to the right; their size is shown in comparison to a 20mm coin.



Assembly 2:

An "in situ" view of both, the (rotational body) and the (outer static body) is shown to the right. The reader is to note the 2mm spacing between the two bodies. The 2mm spacing is the "Radial Compression Zone". (R.C.Z.) of the two opposing "South" magnetic inertia planes, ($S \times S$).



Assembly 3:

The completed assembly of all three parts is shown below, (to scale, with a small coin); One securing nut and bolt is also shown.



*** Note, the “METAL” nut and bolt are a stage one necessary adaptation. Final production will result in the use of a “two-part barb” “SNAP” connector. The two-part barb, (once connected) will form a permanent closure of the device. Any attempt to separate (or) dismantle the device will result in the permanent destruction to securing device rendering the KLM useless.

Understanding the magneto compressional forces within a KLM, (*and their potential energy release*), requires the reader to “let go” of an outdated ideology; And, to embrace a more logical approach for energy liberation. The current “thinking” is “MAKE IT HOT”, “MAKE IT BANG” and it will produce energy, that of ($E=mc^2$). However, to “make” something “HOT” or go “BANG” requires the input of energy, (Hydro-Carbon, Hydro-Gavidic, Nuclear, Solar), each resulting in less energy out than the amount of energy put in; a direct correlation to the conservation of mass and energy.

FKLM Support Housing

The KLM resides within its own grounded (floating earth) chassis which is constructed of hi-impact polypropylene with a silicone “noise and vibration” suppressant base. The housing is fitted with TWO universal serial bus (type one) female sockets that support the standard charging requirements for:

Smartphone, (all USB configurations), Laptops (USB power enabled), tablets (USB power enabled), portable audio equipment, speakers, head-phone, IPod / iPad (or similar), and music players. All running between 5v and 15v (or) the standard input voltage for portable electronic devices.

There is, (fitted to the higher end model) a 110 / 220v socket that allows power output at 2Amps for regular laptop charging, small to medium domestic OLED T.V. power supplies, Wi-Fi devices, Printers, USB hub’s Scanner, or any low amp (current) device.

The device is “silent” running, requires NO power supply what so ever, cool to the touch, with an instant “on” function. The “technologies” (within) result in the fact that a KLM will run NON-STOP (for ever). There are NO bearings to wear down, no parts that can break or degrade; the KLM is a unique MASTER superior to any form of power generation known to mankind.

The device has taken more than THIRTY YEARS to design, (due to the fact that the necessary technology was not available 30 years ago during its original construction). Years of refinement and produce a product that meets and merits the statement of:

One size fit’s all, Fit and forget, Perpetual Energy Transfer, Cold fusion.

One size is all a person needs; Once fitted the user can forget about ever having to power up and or charge a device again; the transfer of energy is infinite and perpetual in its delivery, thus meeting the demanding and exacting standard of Cold Fusion, (to get more energy out that put in). The Kinetic Linear Motor is the “be-all and end-all” of portability within the power consumption market place.

But why stop there?

The functional ability of KLM’s

The kinetic linear motor’s ability is only limited by the reader’s imagination.

The KLM has within its ability to replace any “motor”, (however so formed); from an electric motor, to a pump, to a car or transportation engine (of any size). Each will now be discussed.

Working with something that everybody has, that is a smartphone. Each of us this device to communicate to another, and in that process the smartphone consumes energy via its co-located (onboard battery unit). The battery (however good) will need charging, time and time again. That process is called “consumerism”, it’s designed to make you pay or spend a thing called money. Every

time you charge or top up the energy within your smartphone someone somewhere makes a profit from you. It may be the electricity generating company, it may be the maker of the battery (for replacement) and it may be the company who makes the charging unit. Along that line of THREE there is a thing called taxation. It does not matter who, what or where or how you charge your phone, someone will be making a profit from you. The KLM fits in the palm of your hand and is fitted with two USB power charging points. There is NO input socket, the KLM generates its own 12v DC supply. The device is 100% portable, it is not restricted by height, humidity, or temperature. The KLM will work the same in the North pole as in the Sahara-desert; It will work at sea, in the air or on land. The KLM is truly mobile power for each and every user. The charging rate is governed by the user's device; (if you have a fast charge device then it will fast charge), if you have a trickle charge then likewise it will trickle charge. The life time of a KLM will be much longer than the average lifetime of any smartphone. Associating "Portable Electronics", the smartphone, Smart-tablet, Laptop, music device, Wi-Fi hub, T.V. and more, the KLM will replace the need to connect any of these devices to a wall socket.

Scaling KLM provides unlimited functionality in its ability, in so far, as to offer a second size to a KLM offers to the user two to four 110v or 220v A/C outlets, thus replaces the need for domestic connection to refrigerators, freezers, cookers, ovens, microwave oven, hair and beauty products, hovers and domestic cleaning tool and irons. All without exception can be connected to a KLM. Generation TWO of the KLM will be housed within the appliance, (though this process will make domestic electricity supplies totally redundant).

The KLM "amp-age" ability is unsurpassed and can drive any third party electrical motor. A type THREE KLM has variable geometry rotational axis, (forward and reverse), with the correct gearing the KLM will replace ANY combustion engine; And, the higher end models of type THREE KLM can be fitted with a propeller, thus sea-born transport will no long rely on oil to power the vessels of upon the sea.

Everything can be replaced with a KLM.

Moving for palm size and going infinity small the KLM can be smaller than the tip of a ball point pen, and will be able to provide the necessary commensurate power to a body implant. A pace-maker that last forever, an adaptive audio device that offers universal translation between any two selected languages, an adaptive optics that have a viewing range from 0.1 meters to infinity, and audio interactive speech synthesizer that allows for the complete replacement of the smartphone. With the audio, visual and voice recognition needs catered for who needs a smartphone?

If there is no need for Oil, Gas, Benzene, Diesel, Propane, and if there is no need for coal or nuclear power generation, all gone and assigned to history along with steam-power, the air quality that we breath would be pure, with no CO2 NO2 un-spent hydrocarbons, soot and pollution, there would be no acid rain, with no acid rain the freshwater supply would be likewise pure. A much safer, cleaner environment for each and every one of us.

There is no loss to anyone, and billions upon billions of KLM's will need to be built; different companies will specialize in different types of KLM, no un-employment as millions upon millions will be needed to build the devices, every device today that uses electricity or any form of hydro-carbon will need a new KLM. Every "workforce" with the current "oil" use economy will transfer its skills to KLM. No one will be left behind.

KLM is clean, KLM is silent, KLM is portable, heat resistant, cold resistant, not effected by gravitation conditions, or constrained by an input supply; Making KLM the most practical and invaluable power generation device for space flight and long duration space habitation. The power generated within a KLM can be used to process and produce water and or Oxygen, and or “scrub” CO2 and or clean and purify contaminants from water. The KLM is the perfect energy machine.

The power of the KLM does not stop an “energy production”, nor does it stop at the replacement of a “motor” (of any form); The KLM has unlimited possibilities’, where to example just one more:

The KLM centrifuge:

By combining a KLM with the AVCS (Archimedean Vacuum Centrifuge system) it is possible to “remove” ANYTHING from any other liquid, (however small the particle is), the KLM~AVCS can even remove Pico size particles from AIR.

The KLM functions as two opposing magneto rotational forces where [ME/I=E] (Magnetic Energy *divided by* Inertia *Equal’s* Energy); The amount of energy released it directly proportional to the angular displacement, size and conditioning of the magnets being used. The KLM use TWO sets of magnets’, a fix body and a rotational axis, that produce MEGAWATTS of instant power. To apply some very simple mathematics to the KLM and of inertia. Universal Inertia has an infinity force opposing itself, thus two infinity forces produce an infinite speed. But to now build upon that concept by add a third, a forth, a fifth or more set of magnets produce something incredible.

Using the numbers 2 to 10 (only), as One is one of itself.

(Set 1) = 10 = 36° (Inertia = 0)

(Set 2) = 9 = 40° (Inertia = 0.90[∞])

(Set 3) = 8 = 45° (Inertia = 0.88[∞] + 0.90[∞])

(Set 4) = 7 = 51.42° (Inertia = 0.87[∞]+ 0.88[∞] + 0.90[∞])

(Set 5) = 6 = 60° (Inertia = 0.85[∞] +0.87[∞]+ 0.88[∞] + 0.90[∞])

(Set 6) = 5 = 72° (Inertia = 0.83[∞] + 0.85[∞] +0.87[∞]+ 0.88[∞] + 0.90[∞])

(Set 7) = 4 = 90° (Inertia = 0.80[∞] + 0.83[∞] + 0.85[∞] +0.87[∞]+ 0.88[∞] + 0.90[∞])

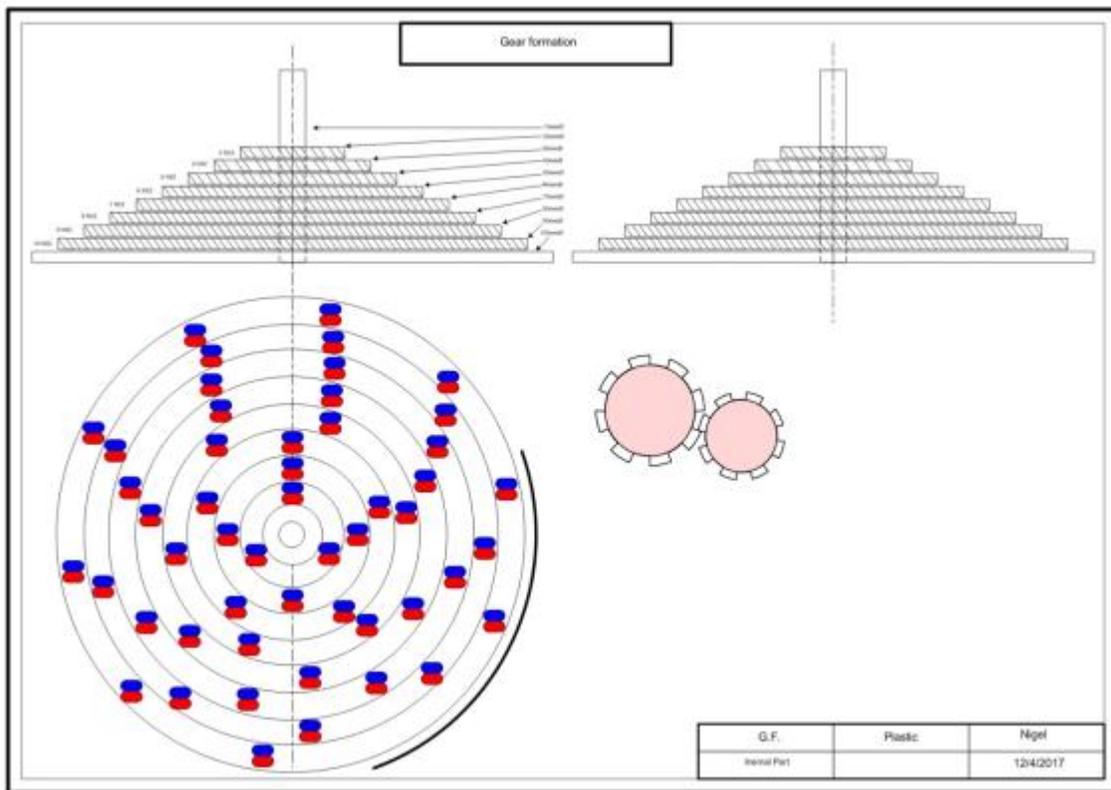
(Set 8) = 3 = 120° (Inertia = 0.75[∞] + 0.80[∞] + 0.83[∞] + 0.85[∞] +0.87[∞]+ 0.88[∞] + 0.90[∞])

(Set 9) = 2 = 180° (Inertia = 0.66[∞] + 0.75[∞] + 0.80[∞] + 0.83[∞] + 0.85[∞] +0.87[∞]+ 0.88[∞] + 0.90[∞])

Or ((0.66+ 0.75 + 0.80 + 0.83 + 0.85 + 0.87 + 0.88 + 0.90) ^ ∞)

Or 6.54 times Infinity, and that is very fast!

By building a set of concentric magneto set’s that have one fixed axis, and each additional axis is a rotational axis about the previous axis, one of two conditions exist, the inner axis will be at a rotational speed of 6.54 times the force of inertia which is infinity itself, or the outer ring will be rotating at 6.54 times the force of inertia thus would rip itself apart. The result is the rotational force of the inner ring at 6.54 times the speed of inertia which is infinity itself as shown below:



So far, angular displacement of the magnetic bodies has been address at an opposing state of +/- 45° of 2/5th of 3/5th of itself, a state of perpetual compression within in any given field. The result of the compression is a rotational axis movement proportional to the magnet set in question; And, can be exemplated as set 3 and 4 (only) results in an inertia state of 0.87[∞]. To now add a “third” angular off-set of another opposing +/-45° in the “Z” axis results in an inertia push of 0.85[∞]. Repeating the additional off-set in the “Z” axis to all magneto set’s results in a “directional” (but in any direction) (or) omnidirectional movement ability of 6.54[∞].

Therefore, to construct a device of concentric magneto sets (outer to inner) that is “hollow” matter entering at set one will be continually accelerated to 6.54[∞] by the time it is ejected from the inner ring of set 9. This is a particle matter accelerator (Motor) – (Engine) - (Thrust). Clearly the limit is not nine magneto set’s, but the more that are added the greater the inertia state achieved. The is no possibility of the inner rings exploding due to centrifugal force as each outer ring has a greater magnetic density than the inner opposing force. Thus, to build a device one meter in diameter of 20 concentric rings of 25mm separation per ring would create a magneto thrust of almost 10 times the state of inertia.

Point to point travel or motion will never be the same, no oil or gas or any hydrocarbon is used so the device will work in space with absolute efficiency.

The imagination of the reader is needed, (I do not have all of the answer’s) just my vision and my ability to design YOUR NEXT GENERATION of energy needs.

KLM Variants in conjunction with $ME/I = E$

The ability of a magnet, and the Magnetic Energy Differential (M.E.D.) (within itself), in conjunction with the inertia plane (I.P.) result in the infinitive production of a secondary form of energy, that of electricity. Everybody uses electricity at some-time during the day, for light, heat or communication; Electricity has become a “staple” of humanity in its every growing desire for all things electric.

It has been expressed that a “Holy Grail” would be a transportation mechanism that runs on “clean” electricity, will do a 1000 kilometers between charges and each charge would cost the equivalent of 1 Euro; to be fully charged in less than the time it takes to drink a cup of coffee. The holy grail concept fails within itself on multiple grounds; mankind’s greed has priced electricity way beyond the one euro benchmark, and battery technology is an infinity away from a rechargeable device that will deliver 1000 kilometers, and at this time, it takes much longer than drinking a cup of coffee!

Looking at the problem, that of time, cost, energy conversion and storage (electrons). Is there a way to remove some if not all of the problem? To remove cost is one, to remove the conversion is two and to ultimately remove the battery all together is three, so it’s as simple as one, two and three.

Professor Searle, came up with a notion and an idea of converting and optimizing a magnetic field, but his solution required the input of energy to get energy, (a conversation process thus a fail).

Many attempts to develop a perpetual engine have been dreamt up and exemplified, but those that seem to function well all require an input of energy, thus all fail; And those that require no input seem to produce far less usable energy than the energy consume in producing the energy thus a secondary fail.

Each and every time, humanity attempts to get something for nothing, it fails under the laws of the conservation of mass and energy, “you can’t get out more than you put in”. That is until now!

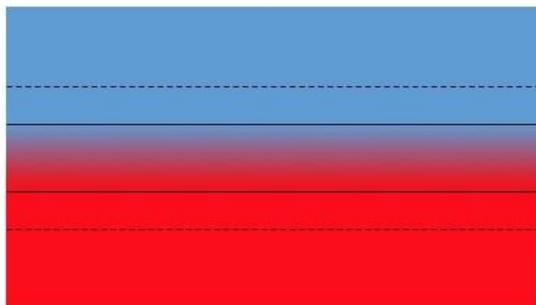
KLM has already proven beyond all reasonable doubt, its ability to produce an infinite supply of truly pure clean electricity. The KLM (variant one) is a “conversion” of mechanical to electrical; The holy grail is to remove conversion to electrical. KLM (variant two) is just that, it is a multi-stage gearing system that can be used to produce a high output rotational force; a mechanism ideally suited to “pumping” fluids from point to point against gravity or on the flat.

Though, where is the system that does not need recharging, and better still does not need a battery, and you can drink your coffee on the go; That is KLM variant three!

Variant three utilizes “advanced” magnetic construction to form powerful magnetic fields that are in permanent opposition. One shape that fits this criterion, would be something similar to “compressed” rivet

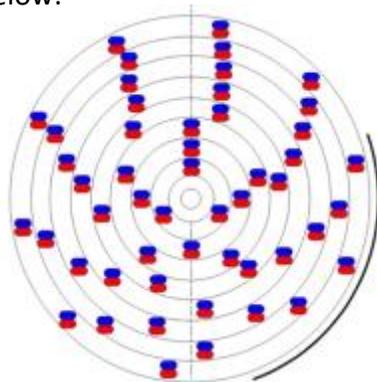


The shape of the “Rivet” shows the north south displacement clear as 2/5th and 3/5th of itself, and a “keyway” structure to affix the alignment of the magnet stopping the direct polar interaction of the next adjacent magnet.

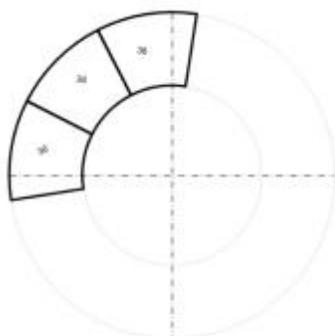


The side profile shows the “keyway” running the full length of the magnetic body. The second part of the magnetic body that is not directly visible is the fact the “rivet” construction is of two parts, likewise, this magnet is two magnets that naturally come together to form the rivet shape. This allows for the placement of the magnet “through” a magneto inert polymer surface as a permanent fixing that does not slip or slide outside of its pre-positioned geometry.

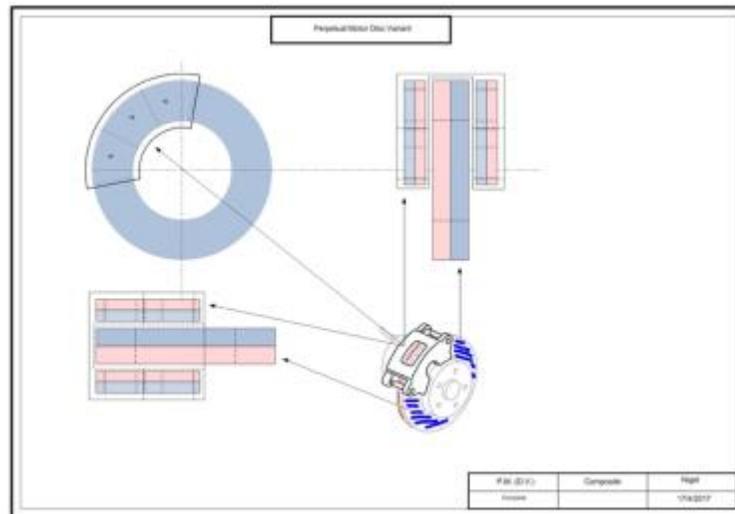
To assume and visualize the magneto inert polymer body as a “disc” something as thin as a conventional compact disc (Music C.D.); the “Magneto Rivet” (M.R.) would be placed geometrically across the surface of the C.D. similar to the image below:



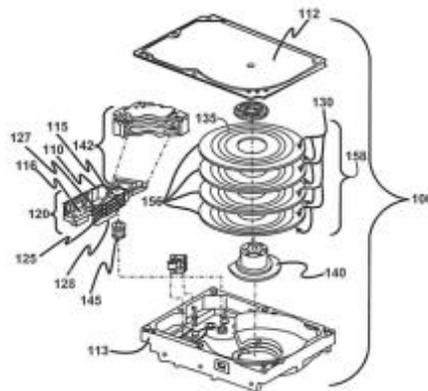
Noting the “size” of a C.D. being 100mm in diameter, the above image is divided into concentric rings, each ring applies the magneto function of N^{n-1} and to simplify for the reader, from outer to inner each ring contains one less magnet than the previous ring, from 10 to 3 inclusive. Each magnet is in the form of a “rivet” shape, each magnet is aligned at 45° to the adjacent polar field. The newly formed “Polymer-Magneto-Disc” (P.M.D.) is 100mm Ø and 3mm thick! (rivet head – polymer – rivet head). The center of the disc is fixed to a rotational axis. Part II of the construct is an “armature” of the opposing N^{n-1} magnetic fields each also set at an opposing 45°.



The armature is in two parts with the PMD is “sandwiched” between the armature’s, similar to a convectional disc brake caliper.



Each consecutive construct of “Armature PMD Armature” forms a single functional layer, 10 layers 30mm thick form the basic motor that is constructed of multiple layers:



Following the functions of a conventional disc caliper, (the application of pressure), causes the space between the armature and the PMD’s to compress, in the compression of the opposing forces, they force against each other creating linear motion at the atomic level, the linear motion is transferred to the rotational surface of the PMD creating a drive within the localized axil.

To now apply PMD’s to “transportation” results in a device that works in conjunction with a current disc brake. The disk brake is for stopping and the PMD is for motion. There is NO NEED for an engine, and there is NO NEED for a battery, if “ancillary power” at 12 volts is needed to power the In-Car-Entertainment (I.C.E), then a KLM type one will be fitted. With no engine, and no battery, the transportation device is 50% less in weight, thus requires 50% power in kilowatts to drive at a given speed. Each PMD has the ability to generate 25 to 50 kilowatts of perpetual energy, or 200Kilowatts for a domestic car! A car that produces no emissions and is silent. Changing the geometry of PMD from 100mm to 600mm and multiplying to 8 or 12 units, any truck or heavy haulage transport can also produce more than enough power to move any side load from A to B. It does so cleanly, efficiently and silently, and allows the driver to drink their coffee on the go!

Creating a single unit of a PMD, the unit will fit into a bicycle, and by utilizing a PMD stack, a motorcycle or two-wheeled transport can also be powered.

Using multiple PMD's at 1 meter diameter produces massive amounts of rotational force and torque, ideal for propeller shaft's; and given the ability of "extreme" rotation speeds, (30,000 – 40,000) and above, the conventional "jet" engine can be replaced with a PMD conversion kit. The greatest user of hydro-carbons in Transportation the greatest burden on the atmosphere is the JET ENGINE.

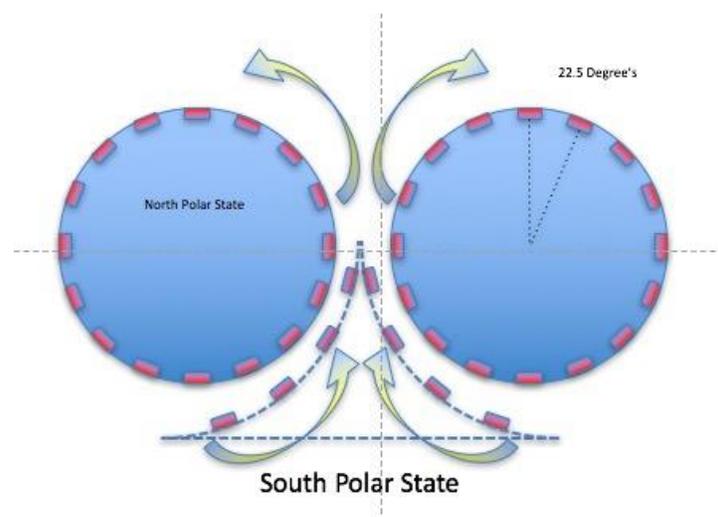
To consider the jet engine as nothing more than something that expels hot air! A PMD conversion kit will do just that, take in cold air, compress within the modified PDM and eject at ultra-high temperatures, or thrust, to enhance the thrust, all that is needed is an "after-burner" as a description, but this will burn nothing; It will, however, convert water to steam. Steam as a volume of 2048 times that of itself as water, and when "discharged" under pressure produced 2048 times the amount of inertia to that of the same water molecule at STP. The only bi-product of a PMD converted JET engine is steam or water, and as the steam or water occurs after the engine, no rust or corrosion can take place. Changing the construction of the jet engine to high-grade titanium as the ejector nozzle of the after-burner reduces weight and allows for a greater force of thrust to be achieved.

The noise level of a PMD JET can be measured is SINGLE FIGURE decibels, speeds will be comparable to SCRAM engines, (Mach 2,3,4 or more); No pollution, no waste, and little or no noise. Cost per kilometer would be ZERO. (but some has to pay).

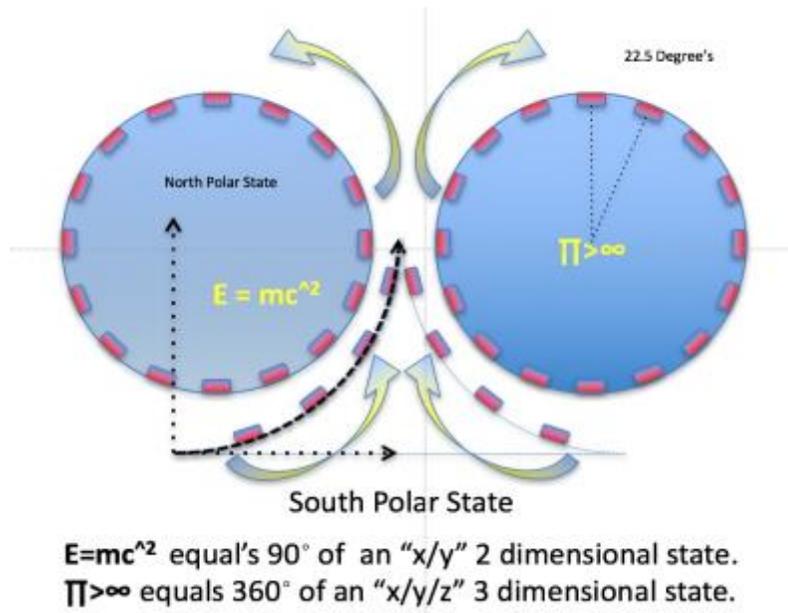
With air, land and sea transportations solved; along with everyone's everyday need, use and consumption of electricity resolved; All, without exception, done within the bounds of UNITY. Unity is exactly what it says it is; It is the **unity of all energy, all matter and all inertia.**

Unity defines and exemplifies the functional equation of $\Pi > \infty$ as the most perfect equation known to mankind, displaying is so many ways, the obvious errors within Mr. Albert Einstein's $E=mc^2$. Understanding the ability of the trinity of the unity of $\Pi > \infty$ allows mankind to move forward, move in a whole new direction with a freedom from the boundaries imposed by an equation of an impossibility.

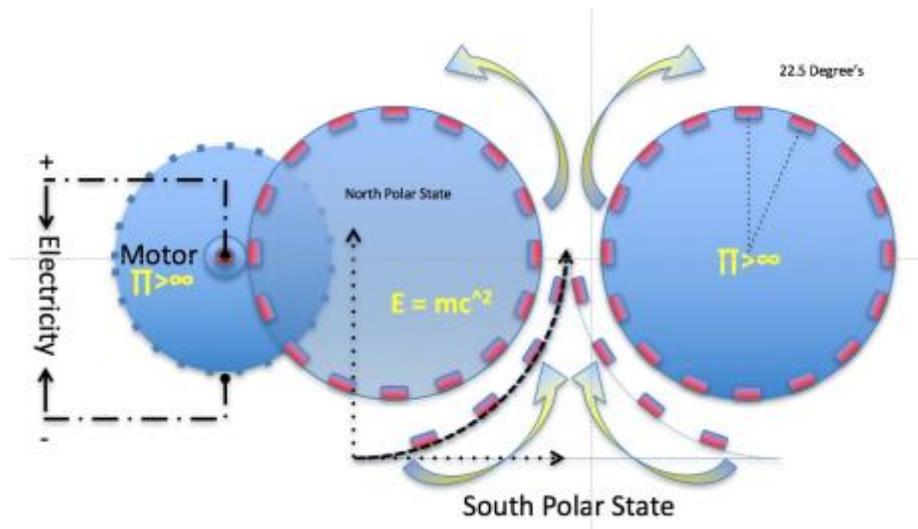
$\Pi > \infty$ is **more** than the collective of THREE SYMBOLS, and to offer several constructive variants of the "Magneto Rotary Motion" (M.R.M.) of the humble magnet; This section discusses the portability and flexibility of M.R.M.



The above drawing display to counter rotating surfaces against one fixed surface. The polar state of South opposing South creates an infinite motion as shown. Placing $E=mc^2$ into perspective against that of $\Pi>\infty$ shows the “abundance” of ENERGY that is truly available.

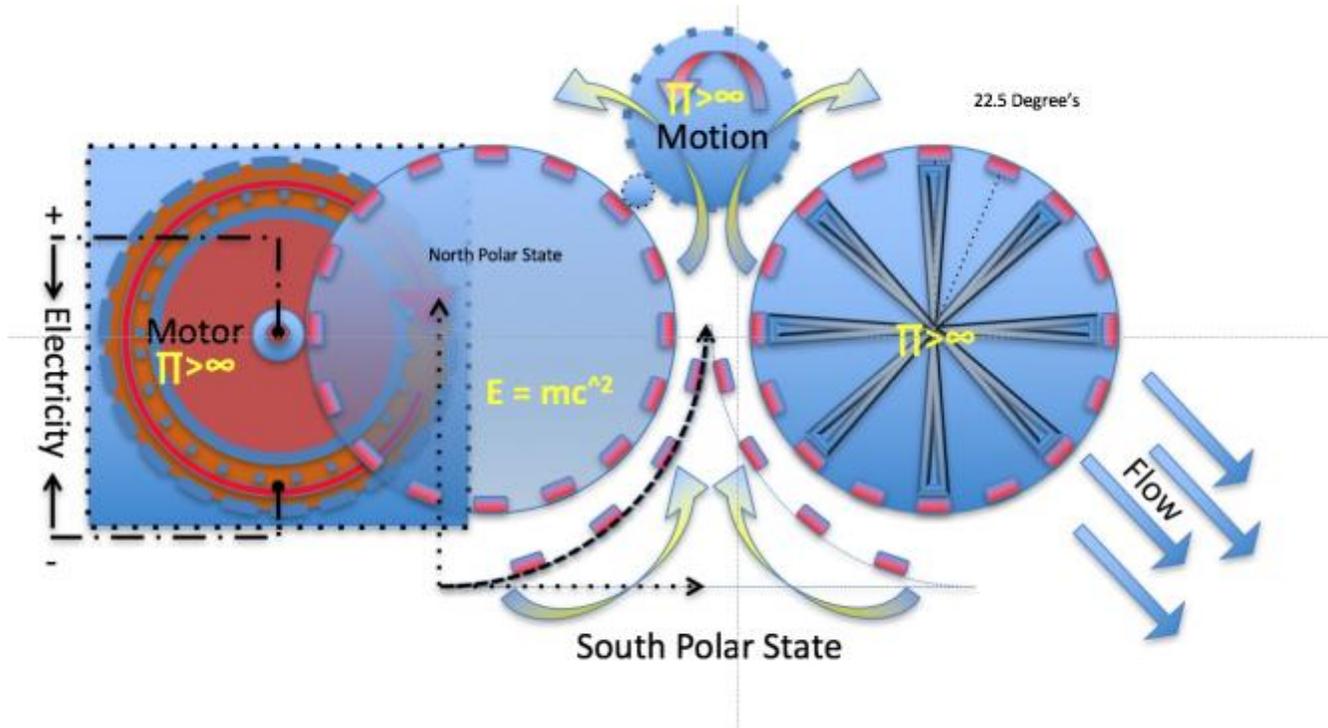


$E=mc^2$ resides within a “FIXED” regime of 90° as shown to the left of a common image; Whereas $\Pi>\infty$ is the completeness of everything within any given dimension. Its power is unsurpassed, and its energy is derived from the M.I.P. (Magnetic Inertia Plane) making MRM infinite within itself. Rotary motion creates an “extractable force” as shown below:



The production and generation of electricity from MRM is just one function amongst many. Building the above device as a “central” distribution unit, the MRM has the ability to power a whole City (or) a small country. The bi-products are? [Well there are no bi products], and the input product is? [All of the Magnetic Energy of the Universe]. MRM is motion, MRM is power, MRM is “anything” that mankind needs today. The image below examples several “draw-off” point of the energy that is generated via

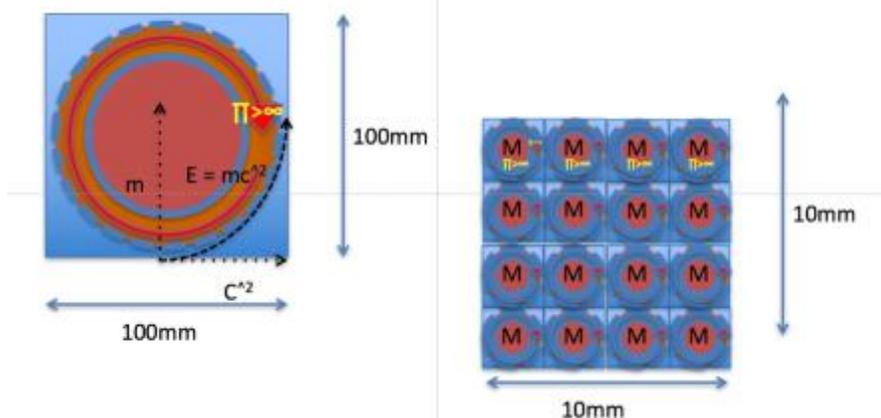
the simple application of MRM to $\pi > \infty$.



Above $\pi > \infty$ produces electricity, $\pi > \infty$ produces motion, $\pi > \infty$ produce flow; And with motion, flow and electricity all of mankind's needs are catered for within a single unit.

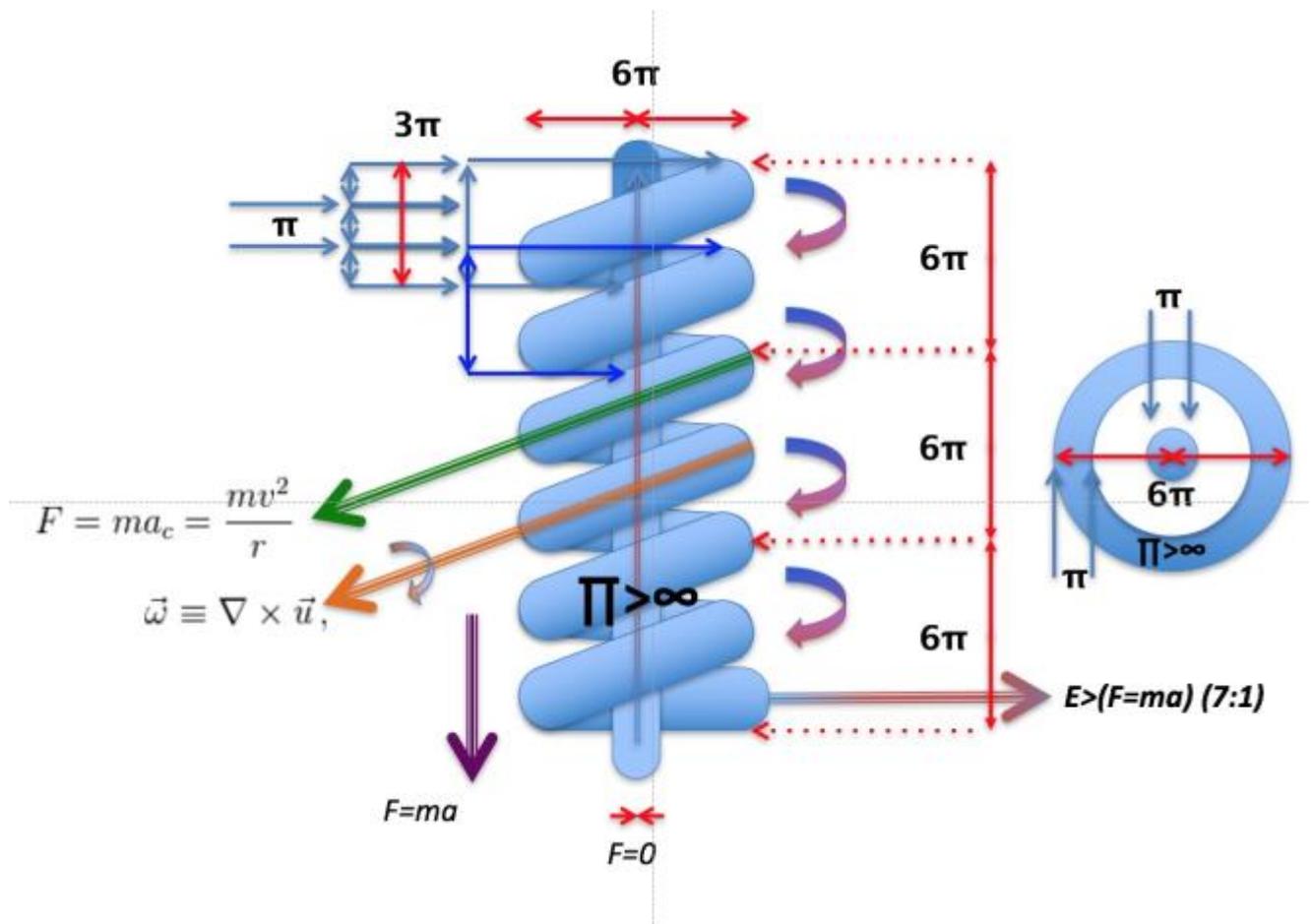
The MRM as shown can be as BIG as needed (to power a country) and as small as necessary (to power a personal device) making MRM infinity saleable as shown below:

"Power (to) Weight" ratio is "Infinity:1"



Be it one "motor" to do a specific task or many "serialized" motors to function together for a specialize task, the MRM will do all that is necessary. The MRM can be, (as shown above) a "single" layer device or it can be constructed as a multi-layer device. The possibilities are endless.

$\pi > \infty$ does not stop at the boundaries of a magnet, or MRM; Understanding the "fulcrum" of $\pi > \infty$ allows for "infinite" fluid movement as shown below:



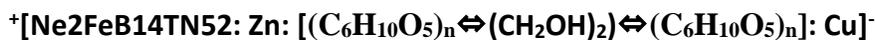
$\Pi > \infty$ resides in every plane, that of “x, y and z”; $\Pi > \infty$ is always superior than any localized force being applied; $\Pi > \infty$ is a collective of more than itself. The simplified drawing above displays many individual functions within a common condition; And to discuss the “blue” shape at the center of the drawing, it is actually one item, it is one length, it is one weight, it is one volume, it is one of itself. Though, the height of the object is many times less than its length; And its central lift requirement is seven times less than its downward force of its external helical form; Its angular decent forces the addition of centrifugal and centripetal forces to $F=ma$ resulting in a 7:1 output. On a flat surface, this device will “pump” for infinity, on an angular incline this device is lift any fluid SIX times its weight, (one is needed for the central vertical column); Thus, (many) devices interconnected along an incline will move any fluid from the sea-level to the top of Everest and beyond, the only limitation is (how long is your pipe!).

ME/I=E

Magnetic Energy divided by Inertia Equal's Energy.

To prove beyond all reasonable doubt, the ability of **ME/I=E**; it can be exemplified by the use of a single magnet. When a magnet is used in conjunction with two metals and a conductive fluid, two reactions occur; Firstly a "Galvanic Reaction (Electron Transfer)", and Secondly a "Magneto Positronic Transfer". When constructed correctly the device has the capability to produce 12Kw per day, (*most households will only use 3 or 4 Kw per day*).

When a powerful Neodymium (non-nickel coated) magnet is used in conjunction with two opposing magneto-pragmatic metal's separated by a dense yet semi-pervious cellulose layer impregnated with (CH₂OH)₂ (Ethylene Glycol); The two above "electron transfer reactions take place), that of Galvanic and Positronic transfers, the result is an electron transfer of both positive and negative values (+/-e)ⁿ¹. The full functional condition can be written:



Ne₂FeB₁₄ (Neodymium Ferrite Boron) Type 52 (permanent magnet) (non-coated)

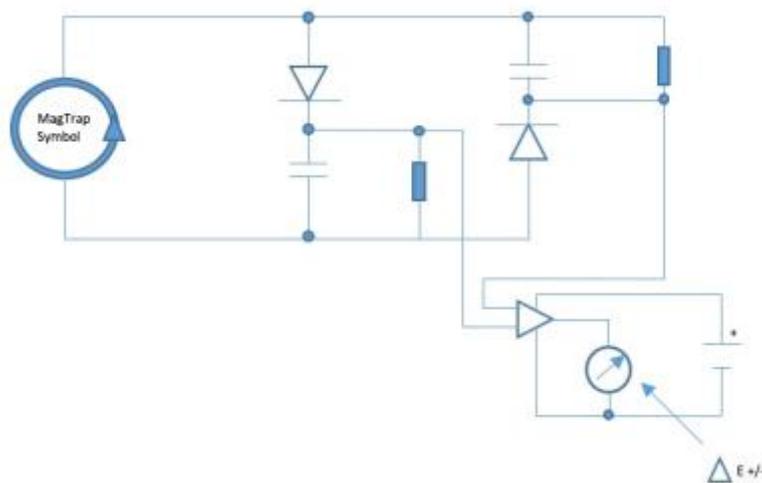
Zn (Zinc – foil)

(C₆H₁₀O₅)_n (Cellulose polysaccharide linear chain molecule with inter-linked Glucose units)

(CH₂OH)₂ (Ethylene Glycol)

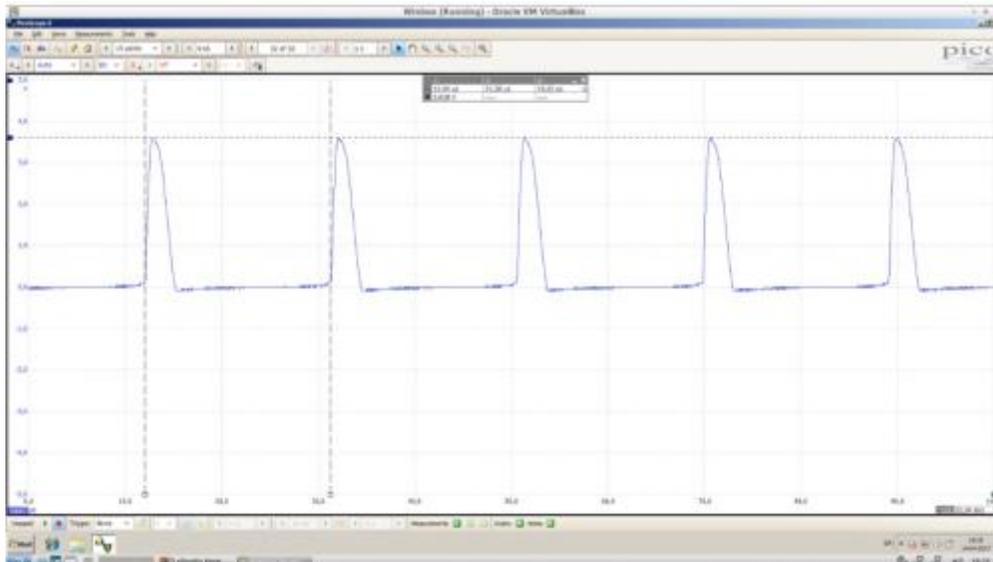
Cu (Copper - Foil)

In order to "extract" the energy from the above functional chain (Fc) the Fc needs to be placed into an electrical circuit: known as a "Magnetic Trap sequencer" or MagTrap for short, as shown below:

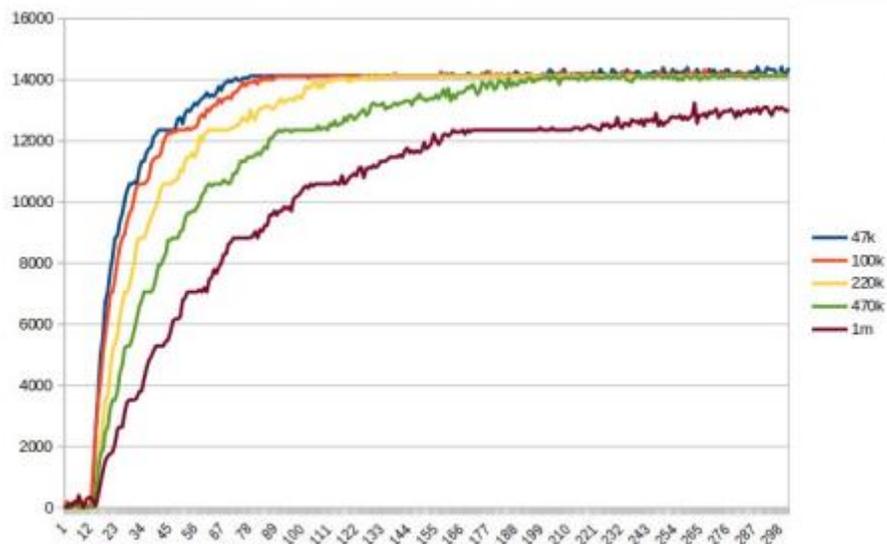


The "MagTrap" itself measures 12mm by 3mm with an additional 3mm for the composite structure, or 12mm x 6mm per cell, four cells are the equivalent to ONE AA battery but produces 4.5V; Thus, the MagTrap (Set) is equal in size to a 1.5v AA battery. But it can produce 12Kw per day!

Utilizing the “correct” diode configuration, capacitor use and resistor placement, a persistent and perpetual voltage can be produced, that of 4.5v perpetual; As shown by the “snap-shot’ plots below:

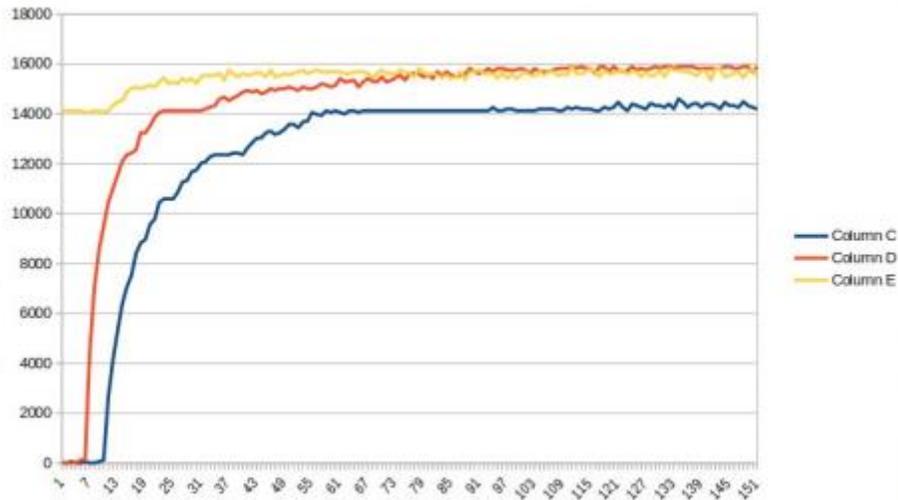


4.5 Volts (Non-Rectified) output



60 sec @ 200ms sample rate. bank of 4 cells + resistor + 10uf cap

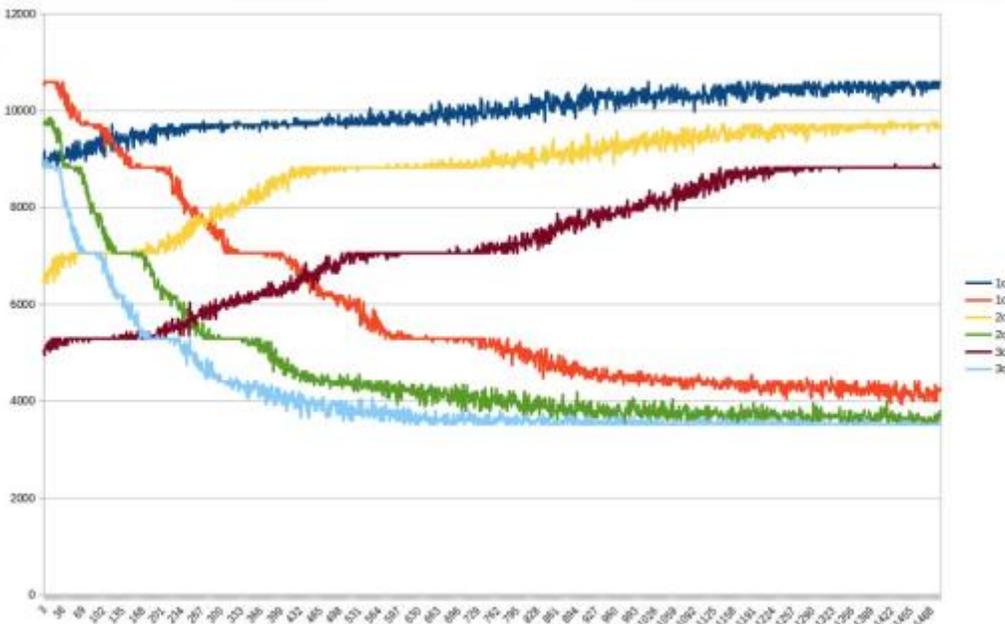
The cell construct can be singular or multiple depending on the voltage requirement and desired product use. Example below is 1 to 3 cells configuration's.



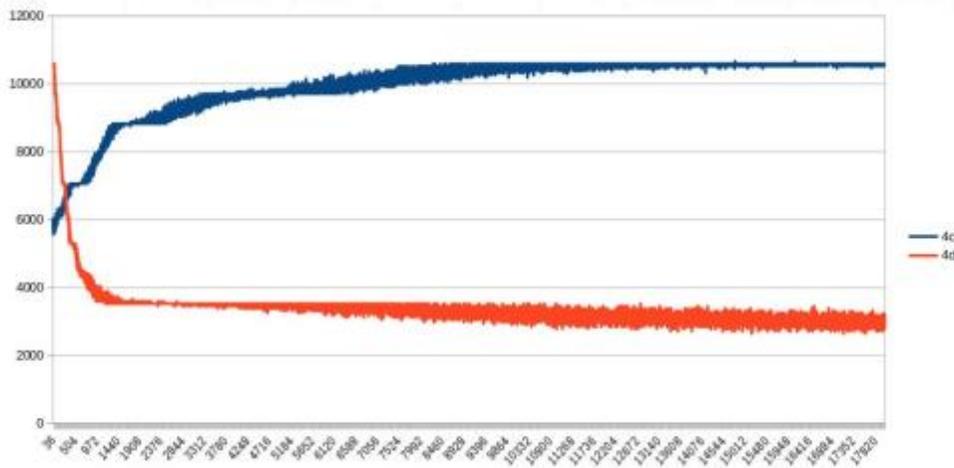
MagTrap Cells In parallel: C=1x1.4v D=2x1.4v E=3x1.4v

Longer sampling indicates a highly stable output of a persistent 4.5v; When sampled over “days” the same results are produced; that is, after an initial 20 second “start-up”, output voltage follows a logarithmic pattern until 4.5v is achieved, at this time (plus 20 seconds), the MagTrap stabilizes and the output of 4.5v remain consistence with no degradation what so ever. When converting “voltage” to “joules” (Energy) from the two reactions; It is necessary to use the NEW EQUATION of ME/I=E; Where ME (Magnetic energy) is the resultant part (or) Volts collected, I (inertia) becomes Infinity (of) time, and E (Energy) becomes joules output; Resulting in “Inertia is TIME (seconds) and ME is VOLTS... $V/T = E$. $4.5 / (1/t) = e$ ”; And when converting to Watts / Kilowatts “ 2.78×10^{-7} kWh is the joule take up rate” results in $4.5/30 = 0.15$ joules per second or 504 Watts ($P(W) = E(J) / t(s)$) Power in Watts is equal to “energy (Joules) divided by time is seconds. So, every second produces 0.15 Joules or 0.15 Watts (per second) ... There for there are 3600 seconds in on hour or 540 Watt’s per hour or 12Kw per day.

When a NiMH (Nickel Metal Hydride) “Rechargeable” battery is inserted into the circuit, (to act as a local storage / discharge unit), it can be seen that “charge” and “discharge” occur even though the NiMH was completed “drained / empty” the device was still capable of offering a full charge and discharge:



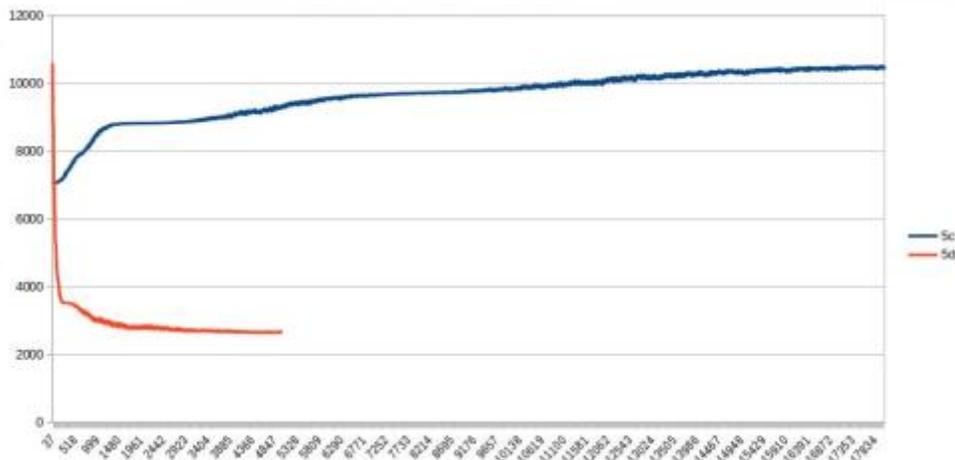
The above shows 300 seconds (at) 200ms sample rate: charging a NiMH battery with one bank of 4 cells and is discharging the NiMH battery via a 1K resistor. When sample over one hour it can be seen that the discharge is an inverse logarithmic function of the charge, (this is due to the 1K resistor).



3600 sec @ 200ms sample rate: charge and discharge

Quantitive sample rates over one hour of “heavy” use clearly shows 3.40mAmps power output after 60 minutes of heavy use, more than 16mAmps output after 15 minutes, 25mAmps after 10 minutes and full and persistent discharge of more than 60mAmps during the first five minutes of use.

When conducting a “load” test for both MagTrap Ionic Charging (M.I.C.), and “Electron Conversion Discharge” (E.C.D); there rates were, ten hours fully charge, one hour discharge, or 10:1 usage rate per cell.



36000 sec @ 1s sample interval: 10 hour’s charge, 1 hour discharge

By building a fully redundant MagTrap array of 20 cells, the following is achieved.

The device contains twenty cells; two switched circuits, one power detection circuit, one user circuit and one high availability circuit. The result is a device the size of a packet of cigarettes that can provide a constant power output in “single” user mode, or “on-demand” double power, and, or a “High-Availability” mode; That, is just TWO CELLS, the other two banks of NINE CELLS as in varying stages of

charge, the power circuit detects the high charge cell and the low charge cell and instantly switches the supply. The process is self-monitoring, self-governing, self-powering; An all in one power unit for any device, where ever the location).

The MagTrap can be fitted internally to any “internet” connected management device, (Router, Switches, Bridges, Wi-Fi Routers, Servers, Web based devices, power supplies and back redundancy devices). The MagTrap is highly portable, and more versatile than an egg! It can power anything from 1.5v upwards and the unit never needs to be connected to any commercial power supply. The result is that the MagTrap is a ONE STOP SHOP ITEM for:

H.P. Cisco, Dell, AT&T, Sky, Apple, Sony, LG to name but a few. It has a global market of how many trillions? All backed up with the restful thought of knowing that the above device CANNOT lose it power!

As the power for the MagTrap is derived from the universal power equation of $ME/I=E$ which extract's free electron volts $e+$ from the localized E.M. field; The MagTrap will in theory run from now until the end of time and never need recharging.

MagTrap was conceived and designed for maximum scalability without restriction; whilst remain portable. When MagTrap is interlinked with current Lithium Ion transfer's, MagTrap crated a whole new, or next generation of power provision for the masses.

Part of the current Lithium Ion “power” use is within transportation, but the transportation is limited to approximately 400 to 600 Kilometers. When the current technology is “enhanced” with a MagTrap supply or MagTrap build the limitation on distance traveled is of no significance, as the MagTrap will provide instant, infinite power to any Lithium Ion storage unit.

The MagTrap, when fitted to ANY device reduces that device's carbon foot print to ZERO; and reduces the over-all running cost to “mechanical parts replacement”; there is NO charge for the power that the unit consumes. The greatest cost of running any device is the cost of electricity which has now been removed.

*** Document section remains in draft ***

“To understand the interaction of 3,6 and 9 is to unlock the universe itself” – Nikola Tesla.

The information written so far within this document is evidence within itself, and a secondary confirmation of Tesla; That of “3, 6 and 9”. Three we know as the first prime above “1” it also “mirror’s itself” (doubles) to make “6”, and “flips” itself to make “9”; 3,6,9; Three is also a first order derivative of the first two digits of 1+2. Where $1*3=3$, $2*3=6$, $3*3=9$., “0” is just place holder between infinity and infinity. It is known that “9” repeats as a “second order” derivative, and it also known that an alternative “flip” and inversion at each and every opposing pair $8/1$ $1/8$ $8/1$ $1/8$ ad infinitum; the wonderful numbers 3,6 and 9. Six is the odd number, as it is an even number, as both 3 and 9 are odds, but multiples of themselves where the multiples themselves are odd in their existence, being a single multiple of 3 and 9 is 3 multiples of 3 of itself. 6 is odd as it is a doublet or a mirror.

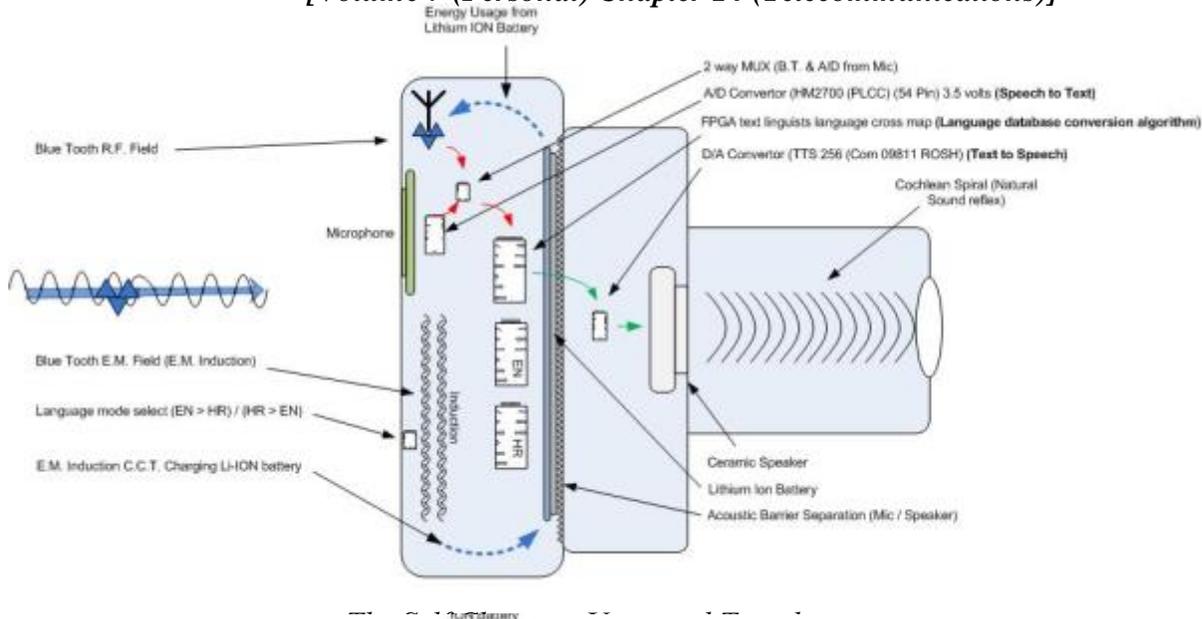
The ancillary argument point is how to resolve any Fibonacci sequence with a magnet? Let’s review $2/5$ and $3/5$ of 1 (magnet) what is missing? Lots [...]; There is no 6, or 9. The only way to form 6 and 9 is to make a multiple of $2/5$ and $3/5$ of itself and to do so (3) is needed, (Three magnets). That results in $6/5$ and $9/5$ (or) $6/10$ and $9/15$ of 1. “3” will divide into $9/15$ in both part’s but it will not divide fully into the first part $6/10$ there is always +1 left over. It does not matter how many times you multiply $2/5$ and $3/5$ by the order of three there will always be one left over on the North side (of a Magnet). And, where ever there is one left over that one is either a reduction in the magnetic force or an addition of a free quantity of something in favor of North. Given that North is the weaker force and that, that “1” will always want to move towards the South in any given combination.

To now use 3,6,9 to form a magnetic field in an infinite state requires some clever geometry. First divide infinity into three, where infinity is $360 / 3 = 120$ (drop the “0” and add the two numbers; Err “3” and “9” once again. If we have nine then we are on to a winner. Therefore 120 degree’s 3 times is 360 degrees or infinity or a simple circle, that is also a winner; And it fits into the target goal of infinity. If three “curved” magnets were made of 120 degrees each, that would-be infinity. So, 3 magnets, is $3 * 2$ (6), the “2” is North and South. “6” is the number we are looking for. So, we have 3 segments of 6 or 18 fields in total, and it can be seen that adding all of the fields together results in (9) of infinity.

Infinity is easy, if you look beyond the number itself. It is the magnetism of M.E. and I. (Magnetic Energy (North and South) and “I” Inertia. Looking again at the same ME and I, M.E. is two part’s and I is one, added to getter is “3”, and there it is again, (3), within ME and I. Therefore, the lowest order derivative of two magnets is ME and I, the second order derivative is 3,6 and 9 or three magnets in a curve of 120 of 360 of infinity.

To now take all of that above, and to create magnets into a ring resolves infinity into an x/y plane. But why stop at x and y? Why not do “z” as well. To view this let’s view “x,y” as a circle or “O” with x being <> and y being up/down. Having sliced the “O” in 3 segments of (120) with a North and a South, and made infinity in two places (but only one plane of “z”). To now view the “O” from above it would look like “—” “an alternative perspective of “1” or “0”. But we want to now go from the “—”to “O” which means we need 360 lots of the prices x/y which is in fact 3 lots of 120. Therefore, if the magnets were 120 degrees in the “z” plane and 120 in the x/y plane, we would 9 magnets in total. There it is 3, 6 and 9 of 1 of 9 of 6 of 1 of infinity. The result is a torus ring of 360 constructed of nine parts. That is the result of infinity itself. As the construction is derived from π (Circle constant) and ∞ the result product output of all of the above, is once again $\pi > \infty$; As quoted in the first line of this document.

The Self Charging Universal Translating Ear Piece [Volume 7 (Personal) Chapter 14 (Telecommunications)]



Applying the “Unified Common Criteria” theory to “Technology” [UCCT] or “C.T.”; results in the intergradation of multiple “I.T.” resources resulting in the following facts:

1. “Electromagnetic Induction” (EMI) is NOT NEW; It has been known (of), for more than a century; First reported by Mr. Nikola Tesla [1] in 1884 ~ 6 during his time with “Edison”,
2. EMRFI (Induction) can be easily achieved by the simple rotation of the plane of polarization, and a mechanism to “interact” with the energy field,
3. AC to DC [2] conversion takes place as an every-day occurrence,
4. All battery chargers used to charge an ear piece (today) use an (AC to DC convertor to recharge at 12 Volts) at a step down of 20:1, resulting in heat dissipation, [3]
5. Utilizing EMRFI “Replaces” the need for re-charging,
6. EMRFI utilizes the redundant duty cycle of the RF signal allowing for FREE charging’;

Having created an in-exhaustible power supply for any blue tooth head set; Adding a little more technology is easy; The addition of four or five chips that will process linguistics as a bi-directional translator becomes simple; [4] Resulting in the [NEW] “Standard” in personal communications being established; A self-powered linguistics device that is capable of translating between [ANY] two known languages in real time to an accuracy of 99.98%; it will also act as a standard “blue tooth head set” [5] with ANY smart device, thus to visualize the functional item’s, in the “NEW STANDARD” of personal communication’s, it would look not too dissimilar in (component form) to the device shown above;

[1]. https://en.wikipedia.org/wiki/Nikola_Tesla “The complete works, history and chronology of Nikola Tesla”

[2]. https://en.wikipedia.org/wiki/Electric_power_conversion “AC to DC conversion, form and function”

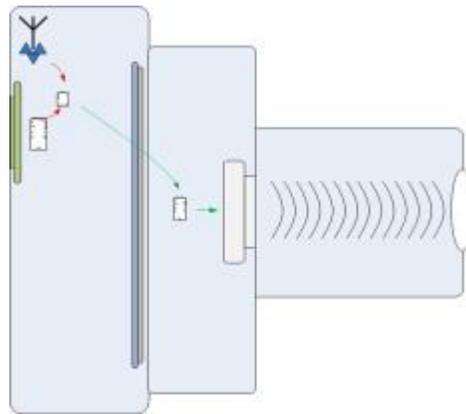
[3]. https://en.wikipedia.org/wiki/Power_inverter “Heat & heat dissipation via AC to DC induction”

[4]. https://en.wikipedia.org/wiki/Speech_synthesis “Speech to Text & Text to Speech Technologies”

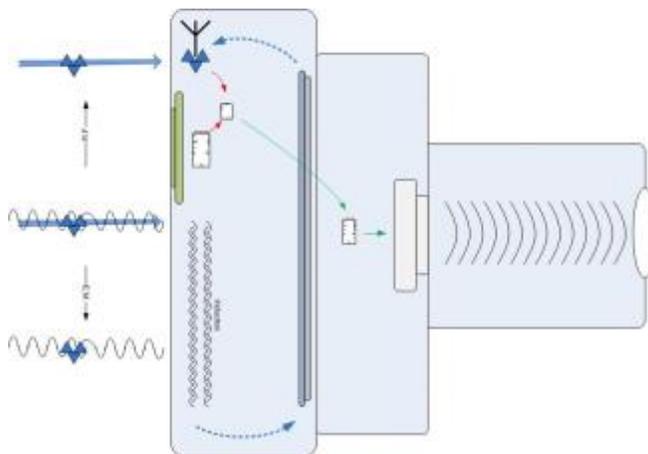
[5]. <https://en.wikipedia.org/wiki/Bluetooth> “From conception to birth of the Blue Tooth device”

To be able to explore each process, each event, and each construct, it is necessary to view the “Ear Piece” in its simplest form as an “electronic audio enhancement tool”, nothing more than that; All “Ear Pieces” use the same functions, Bluetooth, a microphone, a speaker, and a battery; (added to that, the electrical

wiring and a few circuits) produces what is now viewed as a “Blue Tooth Head Set”, (*in its “simplest” form*), also viewable below:

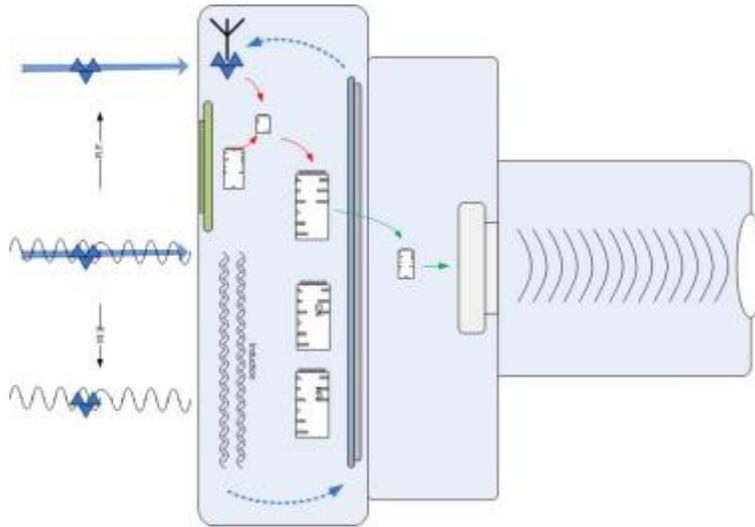


All Blue tooth headsets rely on an “RF” condition, (*a signal*), to communicate with another local device, be that a “static telephone” (or) a mobile “Smart device”; all RF signals comprise of two parts, the R.F. “Signal” or wave, and the electromagnetic wave, which is at a 90 degree polarization state to that (of) the Blue tooth R.F. antenna; there must be “power” or “energy”, (else:) the R.F. signal would [**not**] get to the antenna, and the head set would not work; So, to separate, (and) “use” **both parts** (of) the signal, produces a function known as “*Electro Magnetic Radio Frequency Induction*” or (E.M.R.F.I.); Where, the “**separation**” of the transmission conditions can be seen below:

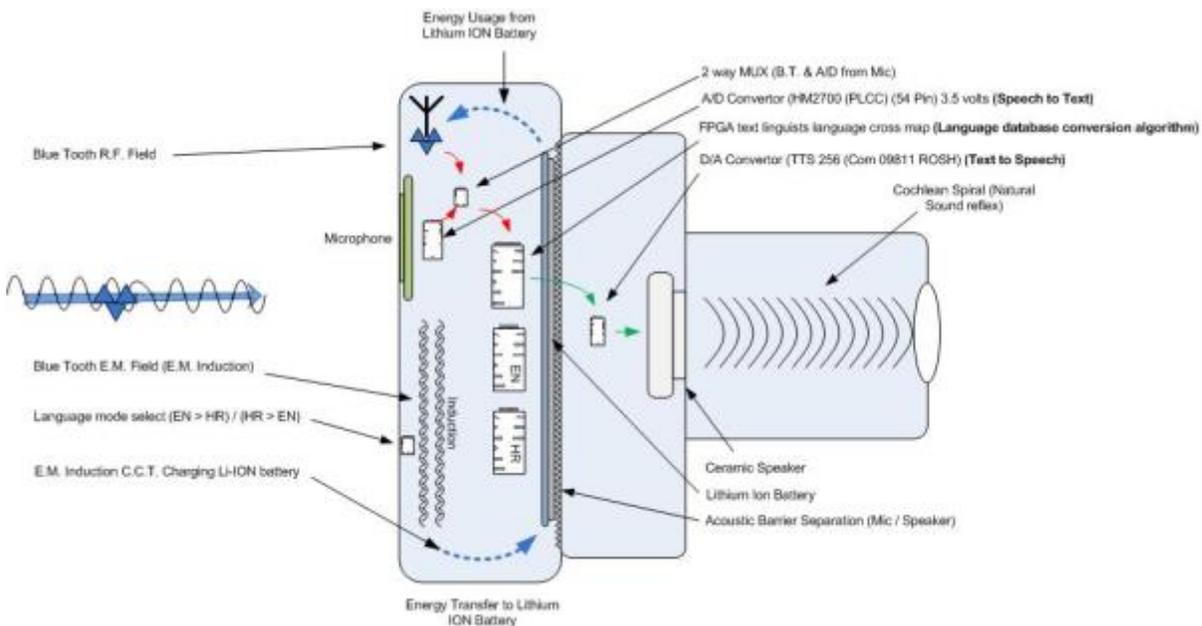


Utilizing the “redundant” power within the duty cycle of the transmitted condition of ANY R.F. emission, it is possible to “Extract” the “Alternate Frequency” or “wave” of the Electro Magnetic Energy, and convert to an A.C. current of comparable voltage and wattage; thus if a device uses 10mWatts to run, it also has an inverted duty cycle of a redundant 10mWatts of E.M. alternating current, or 10mWatts of “useable” A.C. current, and when passed through a “A.C. to D.C.” convertor, the output is a continuous 10mWatts D.C. onboard supply for the Lithium Ion battery, a state of perpetual transfer of E.M. energy to D.C.

Having created an in-exhaustible power supply to the blue tooth head set; Adding a little more technology becomes easy; The addition of four or five chips that will process linguistics as a bi-directional translator becomes possible, resulting in a device that is not to dissimilar from the image below:



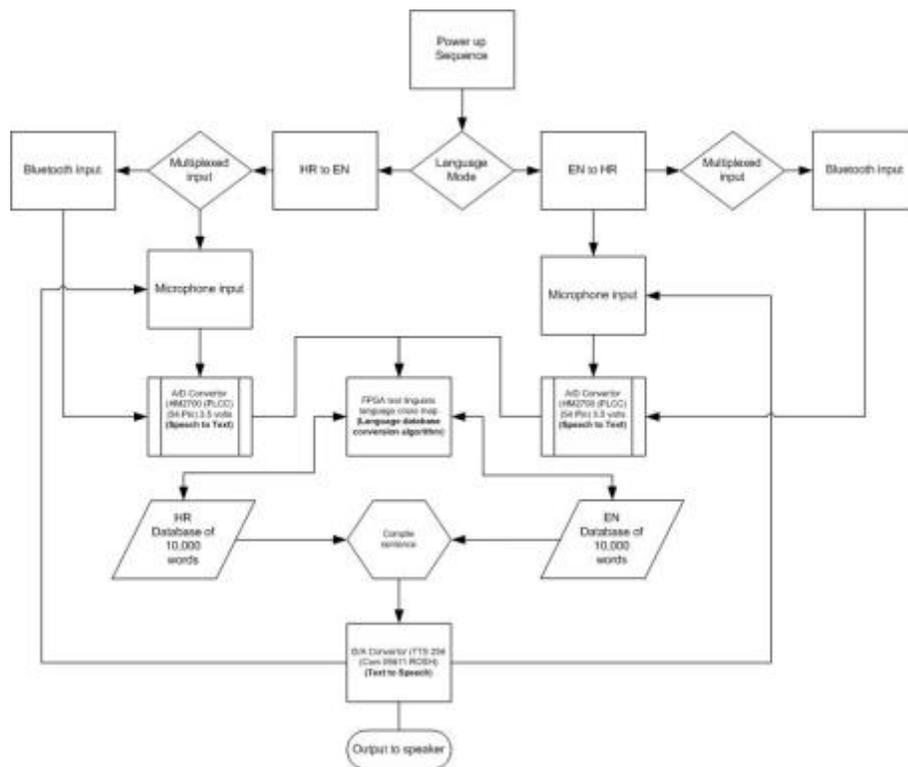
The result is a [NEW] “Standard” is personal communications being established, that of the self-powered linguistics device capable to translating between two known languages in real time to an accuracy of 99.98%; [AND] also has the ability to interact as a “blue tooth head set” with ANY smart device, thus to identify functional item’s, the “NEW STANDARD” in personal communication’s, would look as shown below:



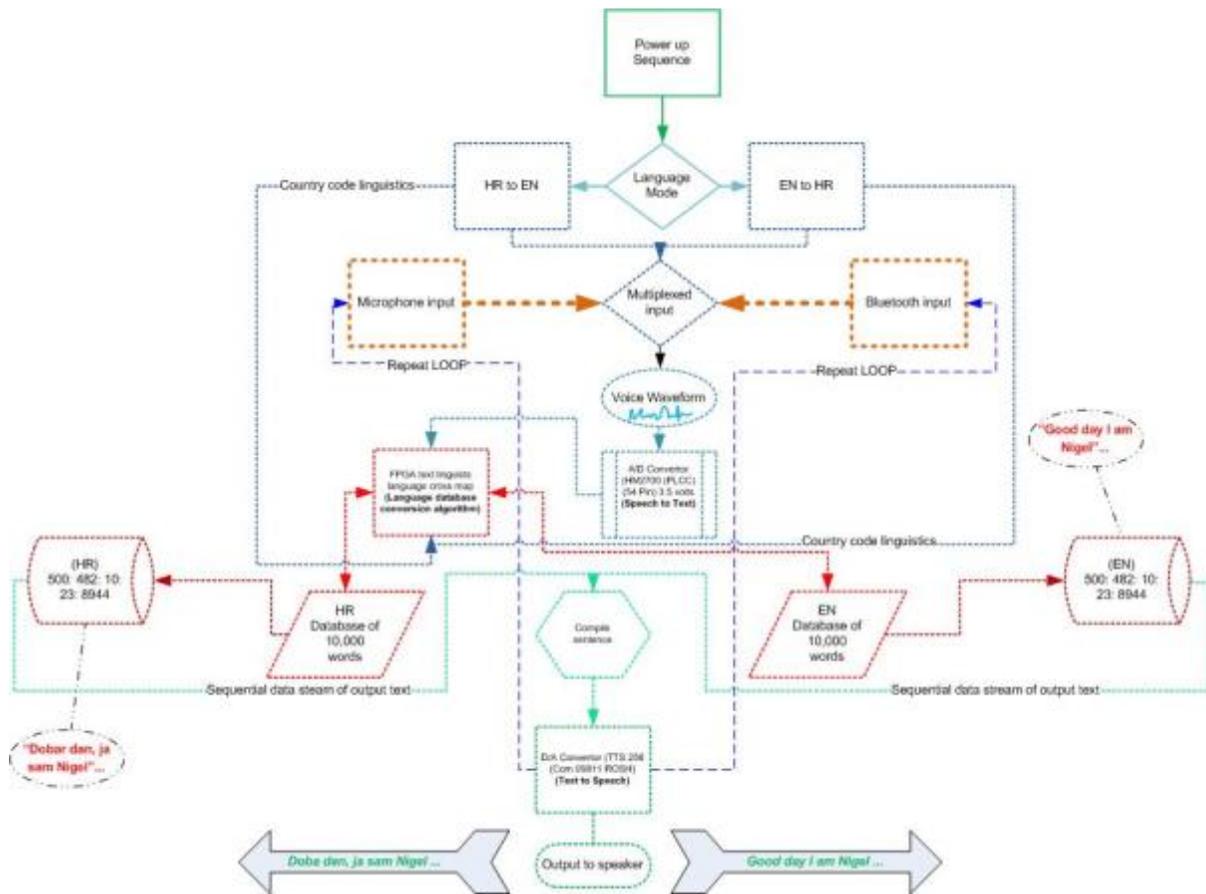
The CURRENT linguistic ability of [ANY] [*Automated Translation device*] relies on common word searches against an ever increasing library of words, (an electronic dictionary that has more than 250 sub-format’s and more than 40,000 words per format, and more than 7 expressions of perceptive and contextual translation, resulting in a MINIMUM word map of some 70,000,000 permutation’s for a single word from a sentence, adding punctuation, gramma and pretense generates a staggering 700 billion to one ($7^{10E11};1$) combinations for a single sentence that contained only SEVEN words... **“Today, I went “shopping” (with), [MY] “Sister””**; By re-ordering or indexing a common criterion library of the common linguistic definitions that are common to more than one language, example as “Apple (EN), Jabuka (HR), Pomme (FR) clearly shows that from an alphabetical stand point, there is no common Criteria, but as an index form (based on the common criteria linguistics listing, (1 to 10,000), all three, (Apple, Jabuka and Pomme) would have the same numerical indexed point, irrespective of their own unique position with the local dictionary; the indexing of the 10,000 most common conditions and cross

mapping each to each creates a single database of 10,000 x number of languages, each pair as a 1:1 thus 249 working pairs that treat every word as common; All indexed functions work at an exponential rate verses dictionary search[!];

Having establish the need for a COMMON homogeneous database of the most common 10,000 words, (per linguistic) definition (a language), there needs to be a method to pre and post process audio into a pattern that the index [CANNOT] mistake to an accuracy of 99.98%, were an example could be expressed as an “apple, is apple, is apple; and jabuka is jabuka is jabuka”, nothing changes within the audio waveform of the comparable letter formation, thus the phonetics sub-construct is equaled, thus the voice pattern recognition is equally unparalleled in its 99.98% accuracy; and when re-combined to the opposing linguistic definition, (an apple is the same as jabuka thus a common index number of 269), making verbal reconstruction as simple as its extraction; as shown below:

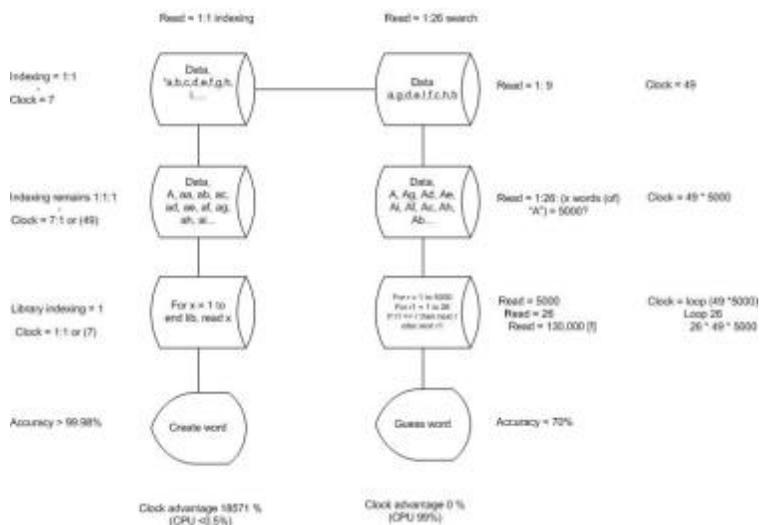


Irrespective of input method, (Blue tooth) or (Microphone), both “audio” signals are pre-processed the same, after the choice of base linguistics (listen and speak), the extracted waveform is passed to an FPGA for cross mapping to the linguistics’ data base, the index is formulated and the outputted value is passed to a (“string\$” [function]) so that additional letters can be added to formulate the “word”, sequence or “phrase” or “sentence”;



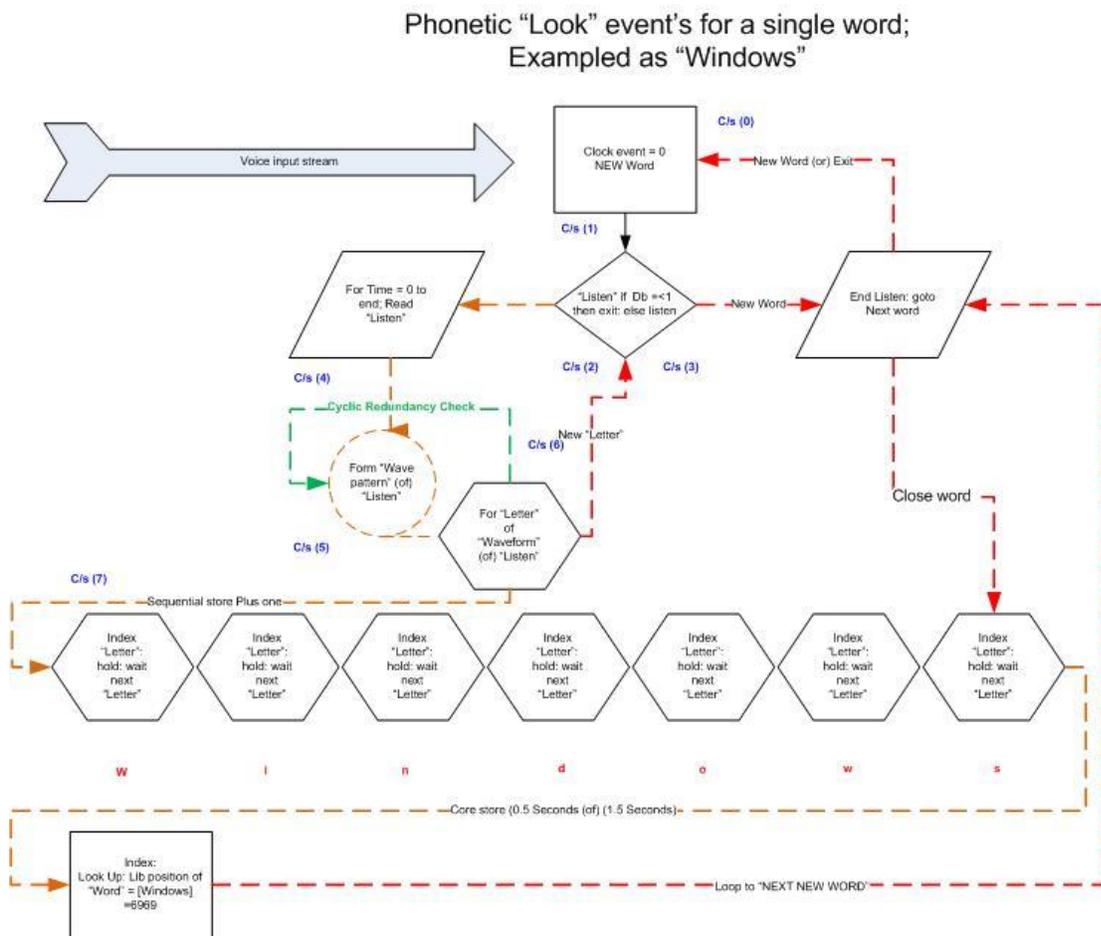
Under closer examination of the correlated function of the transaction of the inputted linguistic to that of its waveform to that of its index letter and word occurs in “Pico” seconds via off board processing within the FPGA register’s, thus local CPU overhead is close to ZERO, with a fault occurrence of less than 0.02%; The speed and accuracy is achieved by a complex “phonetic lookup” as shown below:

Allocating seven clock cycles per “Letter” look up @ 2.5 (GHz)



When analyzing just one word of seven letters and the possible permutations of 26 letters (EN) to and other 25 letters (EN) to any of the more than 172,476 current words and 47,156 obsolete words and 9,500 derivative words result is a cross permutation of the English language to be: 6,394,632 possible

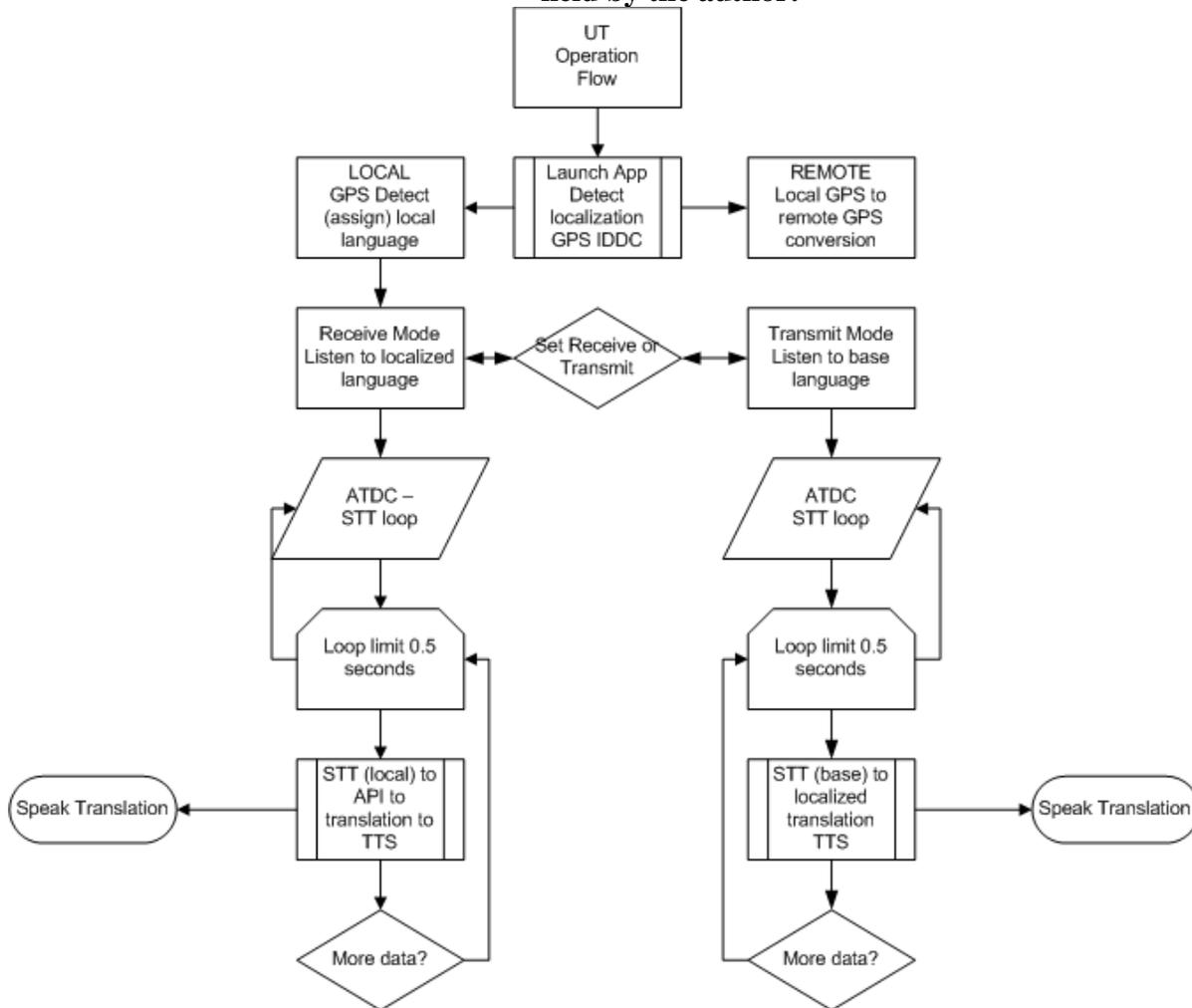
combinations for just ONE WORD[!]; and when compared to an equally complex language, the two form a square function upon themselves, or an staggering: 400 Trillion [4^{10E17}] phonetic permutations, this **only** occurs when an automated voice recognition to translation system relies on dictionary search procedures; When the same function is passed through an INDEXED system, the throughput is 1:1; Every voice phonetic will only map to one, and every letter of every word will only map to one, and every word in every dictionary allocated the same index position of 1:1 making translational speed of 1:1:1, or 99.98% reliable in its accuracy, the 0.02% is the theoretical human error factor of a “typo” in the data base construction; Utilizing the image above, it can be seen that the phonetic processor will be **18,571%** more efficient, combined with, a processor loading of less than 0.5% but most likely to be closer to 0.01% would result in a process that is 1000% more effective in speed, time and accuracy than ANY dictionary look-up system currently used, the loop-up method will have a ZERO clock advantage to that of any condition of any CPU condition of almost 99%.



Above, the duty cycle of any processor can be mapped to the coded logic of each event, and as more than 90% of the above functions are processed “off-board” via FPGA lightning fast (20 Pico Seconds), allows for the same seven clock cycles to be reutilized as a sequentially processed data path, resulting in a ZERO redundancy of the FPGA and a ZERO loading on the CPU; each event contains its own escape sequence that is also embedded within its own loop and functional condition; At no time does the process require to exit to any other additional sub routine, every event is self-contained, and every event is 99.98%

accurate to the point of self CRC checking (on every event); A failsafe in the formation of a phonetic, a fail-safe in the letter and a failsafe in the word resulting is a failsafe translation via indexed tables to an accuracy of 99.98% more commonly referred to “REAL TIME Pre and Post Perfect translations” or (R.T.) PPPT communications, the GOLD STANDARD for global integration within ALL known and future languages, a point of perfection in its creation, a replacement for any communication device that is currently used by mankind; an economic BOOM DEVICE that resides within your ear.

**[Product Enhancement’s]: Extract of Technical Documentation;
 [Volume 7 (Personal) Chapter’s 1 ~ 26 (Inc.)
 held by the author:**



Depicted above is a simplified process walk through of the “Universal Translator” (UT); It can be seen that on startup, several “Onboard Blue Tooth Paired” functions are called; this is the “**Initialization (or) set-up phase**” of UT, which will automatically do:

1. Launch; Detect localization via GPS (*local country and language*); Verify the GPS “linguistics” to that of the “International Direct Dialing Code” (IDDC) of the onboard telecommunications SIM; Compare output results to that of the user interface selected language as a compulsory “a, b, c” function;
 - a. GPS location “Zagreb, Croatia”, output linguistics HR,

- b. IDDC enabled reports +385, output linguists HR,
- c. UI result, code page 437 (ASCII UK / US),
- 2. The local GPS detection, along with the code page select code creates an instant bidirectional condition of [HR >< EN] with HR being the “listening” voice and EN being the transmitting voice.
- 3. For general use, the UT condition is set to “listen” (HR) and is forced into an ATDC ~ STT loop for a core store condition of 0.5 seconds;
- 4. The 0.5 seconds of data is passed for translation to the onboard “MicroSIM” to produce a speech pattern in English of the 0.5 seconds that has been “Digitally” synthesized;
- 5. The loop repeats until user intervention, pause, replay or stop.

Example as: [“Rain, raining, rained” => Numerical [recoded as [2714 (rain): 7 (ing): 8 (ed)] output call string 2714:7 = Raining => translate to “[2714 (Kisa): 7 (iti): 8 (lo je) with the final output reading: [Call EN, 2714:7 >< HR, 2714:7 end call]]

Looking forward to the future of PERSONAL communications; When the user wants to communicate to the localized language, the three-way headset (microphone and earpiece) are used for the “spoken” language and the onboard “speaker phone” output is used as the localized transmission device, thus “cross talk, and chatter” is avoided within the communication.

When a remote session is enabled, the GPS, IDDC, Keyboard detect codes are exchanged, thus one call from one country utilizing one language is automatically cross correlated to the far end GPS, IDDC and keyboard code allowing for seamless translations to occur; utilizing the 0.5 second window for transmission delay (produced via RISC); allows for low processor overhead with optimum throughput, utilizing a numerically converted “dictionary” allows for very fast look-up and word matching with single CRC checking.

When considering longer text conversions, numerical re-representation will ALWAYS be shorter than the contextual text itself, thus a bi-directional database of 10,000 words will allow for VERY fast and HIGHLEY accurate translations.

OCR~TTS (Optical character recognition to text to speech) allows the local user to capture an image of a public notice in one language and have it locally displayed in the user’s language:

Example as:
 YELLOW PARKING
 Zagreb
 Fee 2:00kn per hour
 0700 – 20:00
 700102 payment

The OCR, STT, TTS, IDDC, VTC and GPS are ALL AVAILABLE today on an average smartphone. There is no reason why all of the above cannot be integrated into a single package that is supported via Siri or Cortana;

Having established the baseline functionality of a multi-faceted API (object orientated) and homo~genius in its human interaction; the UT App can function as an interactive verbally conditioned speech aid with extended ability to be multi-lingual, both verbal and “Optical”; having access to cloud based technologies and an additional layer of API interaction the UT App will act as personal navigator, translator, and “Info-Stack”; all wrapped up into one simple to used application, as all the user needs to do is to tap the

button twice. Once enabled the app will “reserve” memory space, for “Next 0.5 seconds”, and will use 1.5 seconds of memory space in a left rotate bit read right pattern or rolling 1.5 seconds of time.

Removing Skepticism

The above, demonstrations have been performed; where each of the demonstrations were independently validated in the following manor.

Classical electronics: An electrician

Physics Theory and Postulate: Professor of Physics (x2)

Mechanical construction: Mechanical Engineer's (x2)

Mathematical computational statement: Professor of classical mathematics.

Medical advantages of (products) – Senior Medical Doctor “Zagreb” confirmation.

Potential adversary to classical economics – Senior political figure's

Educational awareness and thought diversity – Many math / physics students.

This is not the case of a “one-off” event, a quirk of nature, a wild idea that races down a rabbit hole; This is ground-breaking technology for the sake of man-kind. Contained within my work is the core and the foundation of your next generation, it is void of cost, or political engineering, and carries no burden of religion; Its education functionally cannot be questioned as the mind is required to ask “what, if and why”.

For the mere fact “ION TRASNFER” exists! Means that mankind has within its grasp a whole new concept of energy delivery to the masses, and for the mere fact that this can be done for FREE; Results in the fact that there is NO NEED for the DOLLAR, (I'm sorry for your loss), but any money, any paper with printed words of the falsity of net value as just that, they are nothing but ink and words that rely of the idiocracy of the users to give them value.

For the mere fact that ION TRANSFER works (as proven) inverts everything mankind thought it knew on the construct of the universe; for all classical academic philosophy relies on the principle of one plus one always equaling two? It relies on the written word of our forefathers Euclid, Pythagoras, Archimedes, Newton, Einstein, Bell and others; Where each have applied one plus one always equals two; and, it relies on the very existence of zero and one being the opposite of each other, that of binary functionally; the very existence of every digital circuit in use today. All of it, in total, now falls into insignificance to the power of ION transfer.

This postulate, neither condemns nor dismisses any of the classical works that has been understand by mankind in its past; it allows mankind to see the error of its ways and offers to mankind a path of infinite correction for its future, and the future of its children and their children's children.

Discarding but where necessary utilizing parts of our classical past will allow mankind to accelerate to a technological high that was once thought to not be obtainable. By dismissing “man-made” functionality that has been applied to non-man-made entities (everything that is not of this planet), allows mankind to move forward. This is exemplated as the manmade definition of something very fast that cannot be obtained; that of the speed of light (or) 3×10^8 meters per second. The speed of light is a manmade definition as at the time of its postulation mankind knew no better.

Within the equational statements and postulate of this document NO manmade constructs are used. The construct of the Universal Theorem of the “Unity” of “Trinity” clearly expresses itself as infinitive universal non-limited functions.

Electromagnetism (E.M) is just that, “electro” and “magnets”, though as “electricity” is a manmade construct, the result has to be “Magnetic Energy” or M.E. and its un-detachable link to Inertia and the Inertia Plane; where M.E. forms two parts of itself at a ratio at 1.2:1 of itself and Inertia form the TRINITY of the universe. From the trinity comes matter, from matter comes space, from space and matter comes kinetic energy, from kinetic energy comes power. Power / Energy / Electricity / Ion Transfer; All without exception come from the compressional forces of TWO magnetic fields, that of M.E. plus and M.E. minus and their interaction of the Inertia of the inertia plane. Therefore, it would be very simple to say:

“ME (and) I are IM and E”

“Magnetic Energy (and) Inertia are Infinite Mass and Energy”! Anything else is a lie to mankind!

Post Script

What can you do when you have an I.Q. of 207 and Asperger's syndrome? There is nothing more I can do; I have gone from zero to infinity in every direction, (and back); I've have taken you on a complete tour of rim of the Universe showing that infinity is only part of it; I've created matter from nothing, and jumped across space at a speed that far exceeds the poultry speed of light. I've produced light, and power, heat and more, and I've dropped them all at your door. I have shown you the in's and the outs of the very workings of the universe; I shown to you the deepest most closely guarded secrets of the universe... ALL BUT ONE. The one I shall have to keep hidden from mankind, its obsession with "destructive" power, means that, there is NO WAY I am going to give to humans the ability to create all mater from nothing! That of the magneto nuclei combination; the GOLDEN FISH. It exists and I have done it, I've seen through time itself, I wrote down the sequence, and I even made a video, I recorded the whole event, and wrote a step by step guide of how and why it works. It's in the UK and most likely in the U.S. It was stolen from me If that document / Video / mathematical computational equation was to find its way into the wrong hands (mankind), they would have the potential to "wreck" the very construct of this Universe; That cannot be allowed to happen. When making understands the power of an ION and learns the way of its greed, learns that he is insignificant when compared to the power of one, then and only then will it (mankind) be ready. But until then... mankind will not get the key from me.

Epitaph

I personally thank each and every person who has helped me on my way to recovery. For what "others" had done to me for the sake of their own greed and jealousy, has to be the greatest abuse of power in the history of mankind.

What I must now do is "pass" on my genes so that my "intellect and ability" does not die with mankind; As for within my genes is all that I am and all that my child will be.

Signed

Me & I of I am Me; That is Ni of the Gel.

Nigel